

## ABOUT SOME INTEGRAL EQUATION IN TERMS OF A METRIC AND ORDER RELATION

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**Abstract.** In this paper we shall study, in terms of a metric and an order relation, the existence, uniqueness and data dependence for the solutions of integral equation

$$x(t) = (g_1(t) + \int_a^t K_1(t, s, x(s))ds) \cdot (g_2(t) + \int_a^t K_2(t, s, x(s))ds), \quad t \in [a, b].$$

Our results extend the results from I.M.Olaru *An Integral Equation via Weakly Picard Operators*, *Fixed Point Theory*, 11(2010), No. 1, pp 97-106.

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### 1. INTRODUCTION

Let  $X$  be a nonempty set and  $T : X \rightarrow X$  an operator. We denote by  $T^0 := 1_X$ ,  $T^1 := T$ ,  $T^{n+1} := T^n \circ T$ ,  $n \in \mathbb{N}$  the iterate operators of the operator  $T$ . We also have

$$F_T := \{x \in X \mid T(x) = x\}$$

the set of fixed point for operator  $T$ .

**Definition 1.1.** (see [3]) *Let  $X$  be a nonempty set and let us consider  $s(X) := \{\{x_n\}_{n \in \mathbb{N}} \mid x_n \in X\}$ ,  $c(X) \subset s(X)$  and  $Lim : c(X) \rightarrow X$  an operator. We say that  $(X, c(X), Lim)$  is an  $L$ -space (denoted also by  $(X, \xrightarrow{F})$ ) if the following conditions are satisfied:*

- (i) *if  $x_n = x$  for all  $n \in \mathbb{N}$  then  $\{x_n\}_{n \in \mathbb{N}} \in c(X)$  and  $Lim\{x_n\}_{n \in \mathbb{N}} = x$*
- (ii) *if  $\{x_n\}_{n \in \mathbb{N}} \in c(X)$  and  $Lim\{x_n\}_{n \in \mathbb{N}} = x$  then for all subsequences  $\{x_{n_i}\}_{i \in \mathbb{N}}$  of  $\{x_n\}_{n \in \mathbb{N}}$  we have  $\{x_{n_i}\}_{i \in \mathbb{N}} \in c(X)$  and  $Lim\{x_{n_i}\}_{i \in \mathbb{N}} = x$*

**Definition 1.2.** *Let  $(X, \xrightarrow{F})$  be an  $L$ -space An operator  $T : X \rightarrow X$  is orbitally continuous if  $x \in X$  and  $T^{n(i)}(x) \rightarrow a \in X$  as  $i \rightarrow \infty$  imply  $T^{n(i)+1}(x) \rightarrow T(a) \in X$  as  $i \rightarrow \infty$ .*

**Definition 1.3.** (see [12]) Let  $(X, \xrightarrow{F})$  be an  $L$ -space. An operator  $T : X \rightarrow X$  is weakly Picard operator (WPO) if the sequence  $(T^n(x))_{n \in \mathbb{N}}$  converges, for all  $x \in X$  and the limit (which depend on  $x$ ) is a fixed point of  $T$ .

**Definition 1.4.** (see [12]) If the operator  $T$  is WPO and  $F_T = \{x^*\}$  then by definition  $T$  is Picard operator.

Notice that if  $T$  is WPO, then we define the operator  $T^\infty : X \rightarrow F_T$  by

$$T^\infty(x) = \lim_{n \rightarrow \infty} T^n(x).$$

**Definition 1.5.** A triple  $(X, \xrightarrow{F}, \preceq)$  is called an ordered  $L$ -space if  $(X, \xrightarrow{F})$  is an  $L$ -space and  $\preceq$  is a partial order on  $X$  which is closed with respect to  $\xrightarrow{F}$  i.e. if  $\{x_n\}_{n \in \mathbb{N}}$  and  $\{y_n\}_{n \in \mathbb{N}}$  are sequences in  $X$  such that  $x_n \preceq y_n$  for every  $n \in \mathbb{N}$  and  $x_n \rightarrow x$ ,  $y_n \rightarrow y$  as  $n \rightarrow \infty$  then  $x \preceq y$ .

The following abstract Gronwall type lemma takes place for POs

**Lemma 1.1.** Let  $(X, \xrightarrow{F}, \preceq)$  be an ordered  $L$ -space and  $T : X \rightarrow X$  be an operator. We suppose that:

- (a)  $T$  is a PO with respect to  $\rightarrow$  (we denote by  $x_T^*$  its unique fixed point);
- (b)  $T$  is increasing with respect to  $\preceq$ ;

Then we have:

- (i)  $x \in X$ ,  $x \preceq T(x)$  implies  $x \preceq x_T^*$ ;
- (ii)  $x \in X$ ,  $T(x) \preceq x$  implies  $x_T^* \preceq x$ .

**Definition 1.6.** (see [9]) A nonempty ordered set  $(X, \preceq)$  is said to be generalized directed set if for each pair of elements  $x, y \in X$  there exists  $z \in X$  such that  $(x, z)$  and  $(y, z)$  are in  $X_{\preceq}$  where  $X_{\preceq} := \{(x, y) \in X \times X \mid x \preceq y \text{ or } y \preceq x\}$ .

**Definition 1.7.** (see [9]) Let us consider  $(X, \preceq)$  an ordered set and  $T : X \rightarrow X$  an operator. Then  $T$  is called a generalized monotone operator if  $(T \times T)(X_{\preceq}) \subset X_{\preceq}$ , where  $(T \times T)(x, y) := (T(x), T(y))$  for  $(x, y) \in X \times X$ .

**Definition 1.8.** (see [11]) A function  $\varphi : \mathbb{R}_+ \rightarrow \mathbb{R}_+$  is a comparison function if the following conditions are satisfied:

- (i)  $\varphi$  is increasing;
- (ii) the sequence  $\varphi^n(t) \rightarrow 0$  as  $n \rightarrow \infty$ , for every  $t > 0$ .

**Definition 1.9.** (see [11]) A comparison function is a strong comparison function if

$$\sum_{k \geq 0} \varphi^k(t) < \infty, \text{ for any } t > 0.$$

Next result will be used by us in order to study the existence and uniqueness of solution for the above mentioned integral equation.

**Lemma 1.2.** (see [9]) Let  $X$  be a nonempty set,  $d$  be a metric on  $X$  and  $\preceq$  an order relation on  $X$ . We consider an operator  $T : X \rightarrow X$  having the generalized monotone property. We suppose that:

- (i)  $(X, \preceq)$  is a generalized directed set;
- (ii) if  $(x, y) \in X_{\preceq}$ , then  $x$  and  $y$  are asymptotically equivalent;
- (iii) the set  $X_T = \{x \in X \mid T(x) \preceq x \text{ or } x \preceq T(x)\}$  is not empty and  $T : X_T \rightarrow X_T$  is WPO.

Then  $T : X \rightarrow X$  is a PO.

More results about generalized contraction in partially ordered complete metric spaces can be found in [2], [1], [5], [4], [6], [8], [10], [9]

## 2. EXISTENCE AND UNIQUENESS RESULTS

Let us consider denote

$$X = C([a, b], \mathbb{R}_+) := \{x : [a, b] \rightarrow \mathbb{R}_+ \mid x \text{ is continuous}\}.$$

We consider on  $X$  the following norms:

$$\|x\|_{\infty} = \max_{t \in [a, b]} |x(t)|, \quad \|x\|_{\tau} = \max_{t \in [a, b]} |x(t)| \cdot e^{-\tau(t-a)}, \tau > 0$$

and the standard order relation

$$x \preceq y \iff x(t) \leq y(t), (\forall)t \in [a, b].$$

We get the following Banach lattices  $(X, +, \mathbb{R}, \|\cdot\|_{\tau}, \preceq)$  and  $(X, +, \mathbb{R}, \|\cdot\|_{\infty}, \preceq)$ . From the above definition we notice that  $(X, \preceq)$  is a generalized directed set. Next we shall study, in the above defined Banach lattices, the existence and uniqueness, data dependence for the solution of the following integral equation:

$$x(t) = (g_1(t) + \int_a^t K_1(t, s, x(s))ds) \cdot (g_2(t) + \int_a^t K_2(t, s, x(s))ds), \quad t \in [a, b] \quad (2.1)$$

The equation (2.1) is equivalent with the following fixed point problem

$$x = T(x) \quad (2.2)$$

where:

$$T : C([a, b], \mathbb{R}_+) \rightarrow C([a, b], \mathbb{R}_+) \\ T(x)(t) = (g_1(t) + \int_a^t K_1(t, s, x(s))ds) \cdot (g_2(t) + \int_a^t K_2(t, s, x(s))ds) \quad (2.3)$$

Our first result is the following one, where we get the existence and uniqueness, in the Banach lattices  $(X, +, \mathbb{R}, \|\cdot\|_{\tau}, \preceq)$ , for the solution of equation (2.1)

**Theorem 2.1.** *We suppose that*

- (i)  $g_i \in C([a, b], \mathbb{R}_+)$ ,  $K_i \in C([a, b] \times [a, b] \times \mathbb{R}_+, \mathbb{R}_+)$ ,  $i = \overline{1, 2}$ ;
- (ii)  $K_i(t, s, \cdot) : \mathbb{R}_+ \rightarrow \mathbb{R}_+$  is increasing for every  $t, s \in [a, b]$ ,  $i = \overline{1, 2}$ ;
- (iii) there exists  $L_{K_i} > 0$  such that

$$|K_i(t, s, u) - K_i(t, s, v)| \leq L_{K_i}|u - v|,$$

for all  $t, s \in [a, b]$ ,  $u, v \in \mathbb{R}_+, u \leq v$ ,  $i = \overline{1, 2}$ ;

(iv) there exists  $M_{K_i} > 0$  such that

$$|K_i(t, s, u)| \leq M_{K_i},$$

for all  $t, s \in [a, b]$ ,  $u, v \in \mathbb{R}_+$ ,  $i = \overline{1, 2}$ ;

(v) the set  $X_T$  is not empty;

Then

- (a) the equation (2.1) has a unique solution  $x^* \in C([a, b], \mathbb{R}_+)$ ;
- (b) if  $x \in X$  is such that  $x \preceq T(x)$  then  $x \preceq x^*$ ;
- (c) if  $x \in X$  is such that  $T(x) \preceq x$  then  $x^* \preceq x$ ;

*Proof.* (a) First of all we remark that the condition (ii) leads us to the fact that the operator  $T$  defined by equation (2.3) is increasing and consequently it is a generalized monotone operator. On the other hand for all  $x, y \in X_{\preceq}$  we have that

$$\begin{aligned} & |T(x)(t) - T(y)(t)| \leq \\ & \leq |(g_1(t) + \int_a^t K_1(t, s, x(s))ds) \cdot (g_2(t) + \int_a^t K_2(t, s, x(s))ds) - \\ & - (g_1(t) + \int_a^t K_1(t, s, y(s))ds) \cdot (g_2(t) + \int_a^t K_2(t, s, y(s))ds)| = \\ & = |(g_1(t) + \int_a^t K_1(t, s, x(s))ds) \cdot (g_2(t) + \int_a^t K_2(t, s, x(s))ds) - \\ & - (g_1(t) + \int_a^t K_1(t, s, x(s))ds) \cdot (g_2(t) + \int_a^t K_2(t, s, y(s))ds) + \\ & + (g_1(t) + \int_a^t K_1(t, s, x(s))ds) \cdot (g_2(t) + \int_a^t K_2(t, s, y(s))ds) - \\ & - (g_1(t) + \int_a^t K_1(t, s, y(s))ds) \cdot (g_2(t) + \int_a^t K_2(t, s, y(s))ds)| \leq \\ & \left( \frac{L_{K_2} M(g_1, K_1)}{r} + \frac{L_{K_1} M(g_2, K_2)}{\tau} \right) \|x - y\|_{\tau} e^{\tau(t-a)}, \end{aligned}$$

where

$$M(g_1, K_1) := \max_{t \in [a, b]} |g_1(t)| + M_{K_1}(b - a)$$

$$M(g_2, K_2) := \max_{t \in [a, b]} |g_2(t)| + M_{K_2}(b - a).$$

Then, for any  $x, y \in X_{\preceq}$  we have that

$$\|T(x) - T(y)\|_{\tau} \leq \left( \frac{L_{K_2} M(g_1, K_1)}{\tau} + \frac{L_{K_1} M(g_2, K_2)}{\tau} \right) \|x - y\|_{\tau}.$$

Thus, for any  $x \in X_T$  we get that

$$\|T(x) - T^2(x)\|_\tau \leq \left( \frac{L_{K_2}M(g_1, K_1)}{\tau} + \frac{L_{K_1}M(g_2, K_2)}{\tau} \right) \|x - T(x)\|_\tau$$

and consequently  $T : X_T \rightarrow X_T$  is a graphic  $L$ -contraction. and taking into account that

$$O_T(z) := \{T^n(z) \mid n \in \mathbb{N}\} \subset X_T$$

we get that  $T^n(z) \rightarrow T^\infty(z) \in F_T$ , for any  $z \in X_T$ . Hence  $T$  is a WPO on  $X_T$ . Since the operator  $T$  is a  $L$ -contraction on  $X_T$  we obtain that

$$d(T^n(x), T^n(y)) \leq L^n \cdot d(x, y) \rightarrow 0,$$

as  $n \rightarrow \infty$  for any  $x, y \in X_{\preceq}$  and consequently  $x, y$  are asymptotic equivalent. Lemma 1.2 leads us to the conclusion that operator  $T$  is PO and therefore the equation (2.1) has a unique solution in  $C([a, b], \mathbb{R}_+)$ .

(b)+(c) It follows from Lemma 1.1 applied to the operator  $T$ . □

**Theorem 2.2.** *We suppose that  $g_1, g_2, K_1, K_2$ , verify the conditions (i) – (v) from the Theorem 2.1 and  $(L_{K_1} \cdot M(g_2, K_2) + L_{K_2} \cdot M(g_1, K_1)) \cdot (b - a) < 1$  where*

$$M(g_1, K_1) := \max_{t \in [a, b]} |g_1(t)| + M_{K_1}(b - a)$$

$$M(g_2, K_2) := \max_{t \in [a, b]} |g_2(t)| + M_{K_2}(b - a).$$

Then

- (a) the equation (2.1) has a unique solution  $x^* \in C([a, b], \mathbb{R}_+)$ ;
- (b) if  $x \in X$  is such that  $x \preceq T(x)$  then  $x \preceq x^*$ ;
- (c) if  $x \in X$  is such that  $T(x) \preceq x$  then  $x^* \preceq x$ .

*Proof.* (a) By using the same arguments as in the proof of Theorem 2.1 we have that

$$\|T(x) - T(y)\|_\infty \leq M(g_1, g_2, K_1, K_2)(b - a)\|x - y\|_\infty,$$

for all  $x, y \in X_{\preceq}$ .

$$M(g_1, g_2, K_1, K_2) := L_{K_1}M(g_2, K_2) + L_{K_2}M(g_1, K_1).$$

Now, the conclusions follows from Lemma 1.2

(b)-(e) Analogous with the proof or Theorem2.1. □

**Theorem 2.3.** *We suppose that*

- (i)  $g_1, g_2, K_1, K_2$ , verify the conditions (i), (ii), (iv) and (v) from the Theorem 2.1;
- (ii) there exists  $\varphi : \mathbb{R}_+ \rightarrow \mathbb{R}_+$  a strong comparison function such that

$$|K_i(t, s, u) - K_i(t, s, v)| \leq \varphi(|u - v|),$$

for all  $t, s \in [a, b]$ ,  $u, v \in \mathbb{R}_+, u \leq v$   $i = \overline{1, 2}$ ;

- (iii)  $(M(g_1, K_1) + M(g_2, K_2))(b - a) \leq 1$
- (iv)  $X_T$  is not empty and  $T : X \rightarrow X$  is orbitally continuous;

Then

- (a) the equation (2.1) has a unique solution  $x^* \in C([a, b], \mathbb{R}_+)$ ;

- (b) if  $x \in X$  is such that  $x \preceq T(x)$  then  $x \preceq x^*$ ;  
(c) if  $x \in X$  is such that  $T(x) \preceq x$  then  $x^* \preceq x$ .

*Proof.* (a) First of all we remark that the condition (ii) leads us to the fact that the operator  $T$  has the generalized monotone property. On the other hand for all  $x, y \in X_{\preceq}$  we have that

$$\begin{aligned}
& |T(x)(t) - T(y)(t)| \leq \\
& \leq |(g_1(t) + \int_a^t K_1(t, s, x(s))ds) \cdot (g_2(t) + \int_a^t K_2(t, s, x(s))ds) - \\
& - (g_1(t) + \int_a^t K_1(t, s, y(s))ds) \cdot (g_2(t) + \int_a^t K_2(t, s, y(s))ds)| = \\
& = |(g_1(t) + \int_a^t K_1(t, s, x(s))ds) \cdot (g_2(t) + \int_a^t K_2(t, s, x(s))ds) - \\
& - (g_1(t) + \int_a^t K_1(t, s, x(s))ds) \cdot (g_2(t) + \int_a^t K_2(t, s, y(s))ds) + \\
& + (g_1(t) + \int_a^t K_1(t, s, x(s))ds) \cdot (g_2(t) + \int_a^t K_2(t, s, y(s))ds) - \\
& - (g_1(t) + \int_a^t K_1(t, s, y(s))ds) \cdot (g_2(t) + \int_a^t K_2(t, s, y(s))ds)| \leq \\
& (M(g_1, K_1) + M(g_2, K_2)) \cdot (b - a)\varphi(\|x - y\|_{\infty}),
\end{aligned}$$

where

$$M(g_1, K_1) := \max_{t \in [a, b]} |g_1(t)| + M_{K_1}(b - a)$$

$$M(g_2, K_2) := \max_{t \in [a, b]} |g_2(t)| + M_{K_2}(b - a).$$

Then, for any  $x, y \in X_{\preceq}$  we have that

$$\|T(x) - T(y)\|_{\infty} \leq (M(g_1, K_1) + M(g_2, K_2)) \cdot (b - a) \cdot \varphi(\|x - y\|_{\infty}) \leq \varphi(\|x - y\|_{\infty}).$$

From the above inequality we get that  $T : X_T \rightarrow X_T$  is a  $\varphi$ -contraction and consequently

$$d(Tx, T^2(x)) \leq \varphi(d(x, T(x))),$$

for every  $x \in X_T$ . Then we obtain

$$d(T^n(x), T^{n+1}(x)) \leq \varphi^n(d(x, T(x))) \rightarrow 0,$$

as  $n \rightarrow \infty$ , for every  $x \in X_T$ . Therefore, for any  $n \in \mathbb{N}$  and  $p \geq 1$  we have that

$$d(T^n(x), T^{n+p}(x)) \leq \sum_{k=0}^{p-1} \varphi^{n+k}(d(x, T(x)))$$

and taking into consideration the strong comparison assumption on  $\varphi$  we get that, for each  $x \in X_T$ , the sequence  $\{T^n(x)\}_{n \in \mathbb{N}}$  is Cauchy. Since  $T \mid X_T$  is orbitally continuous it follows that  $T^n(x) \rightarrow T^\infty(x) \in F_T$  as  $n \rightarrow \infty$ , for each  $x \in X_T$  and consequently  $T : X_T \rightarrow X_T$  is WPO.

On the other hand the operator  $T$  being a  $\varphi$ -contraction on  $X_T$  we obtain that

$$d(T^n(x), T^n(y)) \leq \varphi^n(d(x, y)) \rightarrow 0,$$

as  $n \rightarrow \infty$  for any  $x, y \in X_{\leq}$  and consequently  $x, y$  are asymptotic equivalent. By using Lemma 1.2 we conclude that the equation (2.1) has a unique solution in  $C([a, b], \mathbb{R}_+)$ .

(b)+(c) It follows from Lemma 1.1 applied to the operator  $T$ . □

### 3. DATA DEPENDENCE: CONTINUITY

Consider the equation (2.1) and let us denote by  $x(\cdot; g_1, g_2, K_1, K_2)$  the solution of this equation. We have

**Theorem 3.1.** *Let  $g_1^j, g_2^j, K_1^j, K_2^j$ ,  $j = 1, 2$  be as in the Theorem 2.2. We suppose that*

(a) *there exists  $\eta_i > 0$  such that*

$$|g_i^1(t) - g_i^2(t)| \leq \eta_i,$$

*for all  $t \in [a, b]$ ,  $i = 1, 2$ ;*

(b) *there exists  $\mu_i > 0$  such that*

$$|K_i^1(t, s, u) - K_i^2(t, s, u)| \leq \mu_i,$$

*for all  $t, s \in [a, b]$ ,  $u \in \mathbb{R}_+$ ,  $i = 1, 2$ .*

Then

$$\begin{aligned} & \|x(\cdot; g_1^1, g_2^1, K_1^1, K_2^1) - x(\cdot; g_1^2, g_2^2, K_1^2, K_2^2)\|_\infty \leq \\ & \leq \frac{M(g_1^1, K_1^1)(\eta_2 + \mu_2(b - a)) + M(g_2^2, K_2^2)(\eta_1 + \mu_1(b - a))}{1 - \frac{\alpha}{\tau}}, \end{aligned}$$

where

$$\alpha = \max_{j=1,2} \{L_{K_2^j} M(g_1^j, K_1^j) + L_{K_1^j} M(g_2^j, K_2^j)\}.$$

*Proof.* For  $j = \overline{1, 2}$  we consider the operators  $T_j : C([a, b], \mathbb{R}_+) \rightarrow C([a, b], \mathbb{R}_+)$  defined by

$$T_j(x)(t) = (g_1^j(t) + \int_a^t K_1^j(t, s, x(s))ds) \cdot (g_2^j(t) + \int_a^t K_2^j(t, s, x(s))ds).$$

According with Theorem 2.2 the above operators are POs and additionally

$$\|T_1(x) - T_2(x)\|_\infty \leq M(g_1^1, K_1^1)(\eta_2 + \mu_2(b - a)) + M(g_2^2, K_2^2)(\eta_1 + \mu_1(b - a)),$$

for all  $x \in C([a, b], \mathbb{R}_+)$ . Now the proof follows from the well known data dependence result (see [12], Theorem 10.2.1 pp.122 ) □

## 4. SMOOTH DEPENDENCE ON PARAMETER

Next we consider the following integral equation

$$x(t, \lambda) = (g_1(t, \lambda) + \int_a^t K_1(t, s, x(s, \lambda), \lambda) ds) \cdot (g_2(t, \lambda) + \int_a^t K_2(t, s, x(s, \lambda), \lambda) ds), \quad (4.1)$$

for all  $t \in [a, b]$ ,  $\lambda \in J \subset \mathbb{R}$ . We assume that

- (H<sub>1</sub>)  $J \subset \mathbb{R}$  an compact interval;
- (H<sub>2</sub>)  $g_i \in C^1([a, b] \times J, \mathbb{R}_+)$ ,  $K_i \in C^1([a, b] \times [a, b] \times \mathbb{R}_+ \times J, \mathbb{R}_+)$ ,  $i = 1, 2$ ;
- (H<sub>3</sub>) there exists  $L_{K_i} > 0$  such that:

$$|K_i(t, s, u) - K_i(t, s, v)| \leq L_{K_i} \cdot |u - v|,$$

for all  $t, s \in [a, b]$ ,  $u, v \in \mathbb{R}_+$ ,  $u \leq v$ ,  $\lambda \in J$ ,  $i = 1, 2$ ;

- (H<sub>4</sub>) there exists  $M_{K_i} > 0$  such that

$$|K_i(t, s, u, \lambda)| \leq M_{K_i}$$

$$\left| \frac{\partial K_i}{\partial u}(t, s, u, \lambda) \right| \leq M_{K_i}$$

for all  $t, s \in [a, b]$ ,  $u \in \mathbb{R}_+$ ,  $\lambda \in J$ ,  $i = 1, 2$ ;

- (H<sub>5</sub>)  $K_i(t, s, \cdot, \lambda) : \mathbb{R}_+ \rightarrow \mathbb{R}_+$  is increasing for every  $t, s \in [a, b]$ ,  $\lambda \in J$ ,  $i = 1, 2$ .

We define the operator

$$B : C([a, b] \times J, \mathbb{R}_+) \rightarrow C([a, b] \times J, \mathbb{R}_+),$$

$$B(x)(t, \lambda) =$$

$$= [g_1(t, \lambda) + \int_a^t K_1(t, s, x(s, \lambda), \lambda) ds] \cdot [g_2(t, \lambda) + \int_a^t K_2(t, s, x(s, \lambda), \lambda) ds]$$

According with Theorem 2.1, under hypothesis (H<sub>1</sub>) – (H<sub>5</sub>), the operator  $B$  is PO. Let  $x^*(\cdot, \lambda)$  the unique fixed point of operator  $B$ . Then

$$x^*(t, \lambda) =$$

$$[g_1(t, \lambda) + \int_a^t K_1(t, s, x^*(s, \lambda), \lambda) ds] \cdot [g_2(t, \lambda) + \int_a^t K_2(t, s, x^*(s, \lambda), \lambda) ds], \quad (4.2)$$

for all  $t \in [a, b]$ ,  $\lambda \in J \subset \mathbb{R}$ . We suppose that there exists  $\frac{\partial x^*}{\partial \lambda}$ . Then from relation (4.2) we obtain that

$$\begin{aligned} & \frac{\partial x^*}{\partial \lambda} = \\ & = \left[ \frac{\partial g_1}{\partial \lambda}(t, \lambda) + \int_a^t \frac{\partial K_1}{\partial u}(t, s, x^*(s, \lambda), \lambda) \cdot \frac{\partial x^*}{\partial \lambda}(s, \lambda) ds + \int_a^t \frac{\partial K_1}{\partial \lambda}(t, s, x^*(s, \lambda), \lambda) ds \right] \cdot \\ & \quad [g_2(t, \lambda) + \int_a^t K_2(t, s, x^*(s, \lambda), \lambda) ds] + [g_1(t, \lambda) + \int_a^t K_1(t, s, x^*(s, \lambda), \lambda) ds] \cdot \end{aligned}$$

$$\left[ \frac{\partial g_2}{\partial \lambda}(t, \lambda) + \int_a^t \frac{\partial K_2}{\partial u}(t, s, x^*(s, \lambda), \lambda) \cdot \frac{\partial x^*}{\partial \lambda}(s, \lambda) ds + \int_a^t \frac{\partial K_2}{\partial \lambda}(t, s, x^*(s, \lambda), \lambda) ds \right].$$

This relation suggest us to consider the following operator

$$\begin{aligned} C : C([a, b] \times J, \mathbb{R}_+) \times C([a, b] \times J, \mathbb{R}_+) &\rightarrow C([a, b] \times J, \mathbb{R}_+), \\ C(x, y)(t, \lambda) &:= \\ &\left[ \frac{\partial g_1}{\partial \lambda}(t, \lambda) + \int_a^t \frac{\partial K_1}{\partial u}(t, s, x(s, \lambda), \lambda) \cdot y(s, \lambda) ds + \int_a^t \frac{\partial K_1}{\partial \lambda}(t, s, x(s, \lambda), \lambda) ds \right] \cdot \\ &\quad \left[ g_2(t, \lambda) + \int_a^t K_2(t, s, x(s, \lambda), \lambda) ds \right] + \\ &\quad \left[ g_1(t, \lambda) + \int_a^t K_1(t, s, x(s, \lambda), \lambda) ds \right] \cdot \\ &\quad \left[ \frac{\partial g_2}{\partial \lambda}(t, \lambda) + \int_a^t \frac{\partial K_2}{\partial u}(t, s, x(s, \lambda), \lambda) \cdot y(s, \lambda) ds + \int_a^t \frac{\partial K_2}{\partial \lambda}(t, s, x(s, \lambda), \lambda) ds \right]. \end{aligned}$$

In this way we have the triangular operator

$$\begin{aligned} A : C([a, b] \times J, \mathbb{R}_+) \times C([a, b] \times J, \mathbb{R}_+) &\rightarrow C([a, b] \times J, \mathbb{R}_+) \times C([a, b] \times J, \mathbb{R}_+), \\ A(x, y)(t, \lambda) &= (B(x)(t, \lambda), C(x, y)(t, \lambda)). \end{aligned}$$

We remark that for each  $x \in C([a, b] \times J, \mathbb{R}_+)$  we have

$$\begin{aligned} |C(x, y)(t, \lambda) - C(x, z)(t, \lambda)| &= \\ &\left| \left[ \frac{\partial g_1}{\partial \lambda}(t, \lambda) + \int_a^t \frac{\partial K_1}{\partial u}(t, s, x(s, \lambda), \lambda) \cdot y(s, \lambda) ds + \int_a^t \frac{\partial K_1}{\partial \lambda}(t, s, x(s, \lambda), \lambda) ds \right] \cdot \right. \\ &\quad \left[ g_2(t, \lambda) + \int_a^t K_2(t, s, x(s, \lambda), \lambda) ds \right] \\ &\quad \left. + \left[ g_1(t, \lambda) + \int_a^t K_1(t, s, x(s, \lambda), \lambda) ds \right] \cdot \right. \\ &\quad \left[ \frac{\partial g_2}{\partial \lambda}(t, \lambda) + \int_a^t \frac{\partial K_2}{\partial u}(t, s, x, \lambda) \cdot y(s, \lambda) ds + \int_a^t \frac{\partial K_2}{\partial \lambda}(t, s, x, \lambda) ds \right] \\ &\quad \left. - \left[ \frac{\partial g_1}{\partial \lambda}(t, \lambda) + \int_a^t \frac{\partial K_1}{\partial u}(t, s, x(s, \lambda), \lambda) \cdot z(s, \lambda) ds + \int_a^t \frac{\partial K_1}{\partial \lambda}(t, s, x(s, \lambda), \lambda) ds \right] \cdot \right. \\ &\quad \left. \left[ g_2(t, \lambda) + \int_a^t K_2(t, s, x(s, \lambda), \lambda) ds \right] \right| \end{aligned}$$

$$\begin{aligned}
& [g_2(t, \lambda) + \int_a^t K_2(t, s, x(s, \lambda), \lambda) ds] \\
& - [g_1(t, \lambda) + \int_a^t K_1(t, s, x(s, \lambda), \lambda) ds] \cdot \\
& \left[ \frac{\partial g_2}{\partial \lambda}(t, \lambda) + \int_a^t \frac{\partial K_2}{\partial u}(t, s, x(s, \lambda), \lambda) \cdot z(s, \lambda) ds + \int_a^t \frac{\partial K_2}{\partial \lambda}(t, s, x(s, \lambda), \lambda) ds \right] \\
\leq & \left[ \int_a^t \left| \frac{\partial K_1}{\partial u}(t, s, x(s, \lambda), \lambda) \right| \cdot |y(s, \lambda) - z(s, \lambda)| ds \right] \cdot \left[ |g_2(t, \lambda)| + \int_a^t |K_2(t, s, x(s, \lambda), \lambda)| ds \right] + \\
& \left[ \int_a^t \left| \frac{\partial K_2}{\partial u}(t, s, x(s, \lambda), \lambda) \right| \cdot |y(s, \lambda) - z(s, \lambda)| ds \right] \cdot \left[ |g_1(t, \lambda)| + \int_a^t |K_1(t, s, x(s, \lambda), \lambda)| ds \right] \leq \\
& \frac{M_{K_1} \cdot M(g_2, K_2) + M_{K_2} \cdot M(g_1, K_1)}{\tau} \cdot e^{\tau \cdot (t-a)} \cdot \|y - z\|_\tau
\end{aligned}$$

where

$$\begin{aligned}
M(g_1, K_1) & := \max_{(t, \lambda) \in [a, b] \times J} |g_1(t, \lambda)| + M_{K_1}(b - a) \\
M(g_2, K_2) & := \max_{(t, \lambda) \in [a, b] \times J} |g_2(t, \lambda)| + M_{K_2}(b - a).
\end{aligned}$$

From the above inequality we get that

$$\|C(x, y) - C(x, z)\|_\tau \leq \frac{M_{K_1} \cdot M(g_2, K_2) + M_{K_2} \cdot M(g_1, K_1)}{\tau} \cdot \|y - z\|_\tau.$$

for each  $x, y, z \in C([a, b] \times J, \mathbb{R}_+)$ . Therefore the operator

$$C(x, \cdot) : C([a, b] \times J, \mathbb{R}_+) \rightarrow C([a, b] \times J, \mathbb{R}_+)$$

is a  $\alpha$ -contraction with  $\alpha := \frac{M(g_2, K_2)M_{K_1} + M(g_1, K_1)M_{K_2}}{\tau}$ . From the theorem of fiber contraction (see I.A. Rus [12] Theorem 10.5.1, pp.125) we have that the operator  $A$  is Picard operator. So, the sequences

$$x_{n+1} = B(x_n), n \in \mathbb{N}$$

$$y_{n+1} = C(x_n, y_n)$$

converges uniformly to  $(x^*, y^*) \in F_A$ , for all  $x_0, y_0 \in C([a, b] \times J, \mathbb{R}_+)$ .

If we take  $x_0, y_0 \in C([a, b] \times J, \mathbb{R}_+)$  such that  $y_0 = \frac{\partial x_0}{\partial \lambda}$  then  $y_1 = \frac{\partial x_1}{\partial \lambda}$  and by induction we prove that  $y_n = \frac{\partial x_n}{\partial \lambda}$ , for all  $n \in \mathbb{N}^*$ .

Thus

$$x_n \rightarrow x^*, \text{ uniform as } n \rightarrow \infty$$

$$\frac{\partial x_n}{\partial \lambda} \rightarrow y^*, \text{ uniform as } n \rightarrow \infty$$

These imply that there exists  $\frac{\partial x^*}{\partial \lambda}$  and  $\frac{\partial x^*}{\partial \lambda} = y^*$

From the above considerations, we have that

**Theorem 4.1.** *We consider the integral equation (4.1) in the hypothesis  $(H_1) - (H_5)$ . Then*

- (i) *the equation (4.1) has, in  $C([a, b] \times J, \mathbb{R}_+)$ , a unique solution  $x^*(t, \cdot)$ ;*
- (ii)  *$x^*(t, \cdot) \in C^1(J, \mathbb{R}_+)$ , for all  $t \in [a, b]$ .*

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