

# Chapter 2. Descriptive Statistics

**Statistics** is a branch of Mathematics that deals with the collection, analysis, display and interpretation of numerical data. It consists of two main areas:

**Descriptive Statistics** includes the collection, presentation and description of numerical data. It is what most people think of when they hear the word “Statistics”.

**Inferential Statistics** consists of the techniques of interpretation, of modeling the results from descriptive Statistics and then using them to make inferences.

As a discipline, Statistics has mostly developed in the past century. Probability theory - the mathematical foundation for statistics - was developed in the 17th to 19th centuries based on work by Thomas Bayes, Pierre-Simon Laplace and Carl Gauss. In contrast to the somewhat theoretical nature of probability, Statistics is an applied science concerned with analysis and modeling of data. Modern Statistics as a rigorous scientific discipline traces its roots back to the late 1800's and Francis Galton and Karl Pearson. R. A. Fisher, in the early 20th century, was a leading pioneer of modern Statistics, introducing key new ideas and concepts.

A new trend in modern Statistics is **Exploratory Data Analysis (EDA)**. This new area of Statistics was promoted by John Tukey beginning in the 1970's. He proposed a reformation of Statistics, where statistical inference is just one component of data analysis. He encouraged statisticians to explore the data, often using statistical graphics and other data visualization methods, and possibly formulate hypotheses that could lead to new data collection and experiments.

As a consequence, new disciplines in Statistics were established, such as *Robust statistics* and *Nonparametric tests*, which do not rely so heavily on theoretical assumptions and are not so easily affected by outliers (extreme observations).

## 1 Analysis and Display of Data

### 1.1 Basic Concepts

A **population** is a set of individuals, objects, items or measurements whose properties are to be analyzed.

In order to form a population, a set must have a common feature. The population of interest must be carefully defined and is considered so when its membership list is specified.

A subset of the population (a set of observed units collected from the population) is called a **sample**, or a **selection**. A sample must be **random** (each element of the population must have the

same chance of being chosen) and representative for the population it was drawn from (the structure of the sample must be similar to the structure of the population).

A **characteristic** or **variable** is a certain feature of interest of the elements of a population or a sample, that is about to be analyzed statistically. Characteristics can be *quantitative* (numerical) or *qualitative* (a certain trait). From the probabilistic point of view, a numerical characteristic is a random variable. Further, numerical variables can be *discrete* (if they can be counted) or *continuous* (if they can be measured). A numerical characteristic is called a **parameter**, if it refers to an entire population and a **statistic**, if it refers just to a sample.

The outcomes of an experiment yield a set of **data**, i.e. the values that a variable takes for all the elements of a population or a sample.

## 1.2 Data Collection, Sampling

An important first step in any statistical analysis is the **sampling technique**, i.e. the collection of methods and procedures used to gather data. There are several ways of collecting data: If every element of a population is selected, then a **census** is compiled. However, this technique is hardly ever used these days, because it can be expensive, time consuming or just plain impossible. Instead, only a **sample** is selected, which is analyzed and based on the findings, inferences (estimates) are made about the entire population, as well as measurements of the degree of accuracy of the estimates.

A sample is chosen based on a **sampling design**, the process used to collect sample data. If elements are chosen on the basis of being “typical”, then we have a **judgment sample**, whereas if they are selected based on probability rules, we have a **probability sample**. Statistical inference requires probability samples. The most familiar probability sample is a **random sample**, in which each possible sample of a certain size has the same chance of being selected and every element in the population has an equal probability of being chosen.

Other types of samples may be considered:

- *systematic* sample
- *stratified* sample
- *quota* sample
- *cluster* sample

Throughout the remaining chapters, we will only consider **random samples**.

Sometimes discrepancies occur between a sample and its underlying population.

**Sampling errors** are caused simply by the fact that only a portion of the entire population is observed. For most statistical procedures, sampling errors decrease (and converge to zero) if the sample size is appropriately increased.

**Non-sampling errors** are produced by inappropriate sampling designs or wrong statistical techniques. No statistical procedures can save a poorly collected sample!

### 1.3 Graphical Display of Data, Frequency Distribution Tables, Histograms

“A picture is worth a thousand words!”

Once the sample data is collected, it must be represented in a relevant, “easy to read” way, one that hopefully reveals important features, patterns of behavior, connections, etc.

**Circle graphs** (“**pie**” **charts**) and **bar graphs** are popular ways of displaying data, that use the proportions of each type of data and represent them as percentages.

**Example 1.1.** Suppose that a software company is having 25 items on sale, 5 of which are learning programs (L), 8 are antivirus programs (AV), 3 are games (G) and the rest (9) are miscellaneous (M).

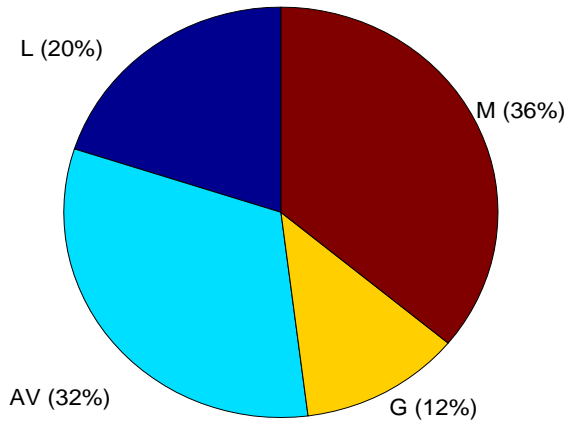
The pie chart and the bar graph are shown in Figure 1.

#### Frequency Distribution Tables

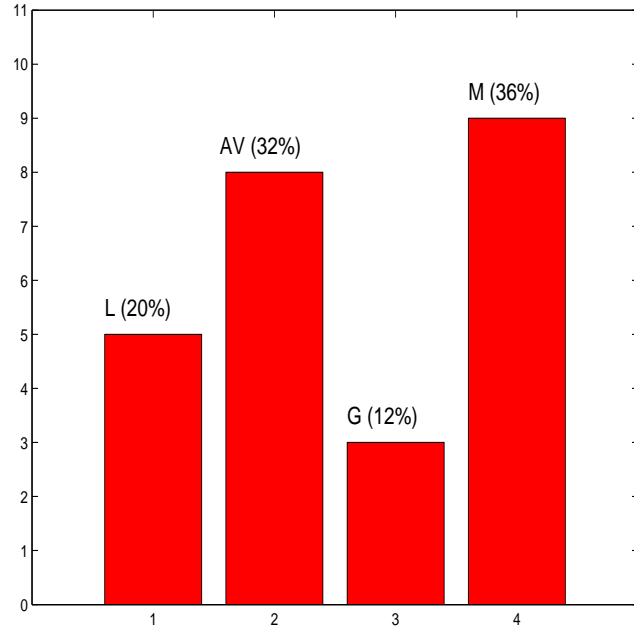
Once collected, the raw data must be “organized” in a relevant and meaningful manner. One way to do that is to write it in a **frequency distribution table**, which contains the values  $x_i, i = \overline{1, k}$ , sorted in increasing order, together with their (**absolute**) **frequencies**,  $f_i, i = \overline{1, k}$ , i.e. the number of times each value occurs in the sample data, as seen in Table 1.

Value	Frequency
$x_1$	$f_1$
$x_2$	$f_2$
$\vdots$	$\vdots$
$x_k$	$f_k$

Table 1: Frequency Distribution Table



(a) Pie Chart



(b) Bar Graph

Fig. 1: Example 1.1

If needed, the table can also contain the **relative frequencies**

$$rf_i = \frac{f_i}{N}, \forall i = \overline{1, k},$$

usually expressed as percentages, the **cumulative frequencies**

$$F_i = \sum_{j=1}^i f_j, \forall i = \overline{1, k},$$

or **relative cumulative frequencies**

$$rF_i = \frac{1}{N} \sum_{j=1}^i f_j, \forall i = \overline{1, k},$$

where  $N = \sum_{i=1}^k f_i$  is the sample size.

However, when the data volume is large and the values are non-repetitive, the frequency distribution is not of much help. Every value is listed with a frequency of 1. In this case, it is better to *group* the data into *classes* and construct a **grouped frequency distribution table**. So, first we

decide on a reasonable number of classes  $n$ , small enough to make our work with the data easier, but still large enough to not lose the relevance of the data. Then for each class  $i = \overline{1, n}$ , we have

- the **class limits**  $c_{i-1}, c_i$ ,
- the **class mark**  $x_i = \frac{c_{i-1} + c_i}{2}$ , the midpoint of the interval, as an identifier for the class,
- the **class width (length)**  $l_i = c_i - c_{i-1}$ ,
- the **class frequency**  $f_i$ , the sum of the frequencies of all observations  $x$  in that class.

Notice that we used the same notation  $x_i$  for primary data and for class marks. This is by choice, since in the case of grouped data, the class mark plays the role of a “representative” for that class and the class frequency is taken as being the frequency of that one value. The double notation should not cause confusion throughout the text, since  $N$  is the sample size, so  $x_1, \dots, x_N$  denotes the primary data, while  $n$  is the number of classes and thus,

$$\begin{pmatrix} x_i \\ f_i \end{pmatrix}_{i=\overline{1, n}}$$

denotes the grouped frequency distribution of the data.

The grouped frequency distribution table will look similar to the one in Table 1, only it will contain classes instead of individual values, each with their corresponding features.

**Remark 1.2.**

1. Relative or cumulative frequencies can also be computed for grouped data, as well, using the same formulas as for ungrouped data.
2. In general, the classes are taken to be of the same length  $l$ .
3. When all classes have the same length, the number of classes,  $n$ , and the class length  $l$  determine each other (if one is known, so is the other). In this case, there are two customary procedures (empirical formulas) of determining the number of classes:

One is a formula for  $n$ , known as *Sturges’ rule*

$$n = 1 + \frac{10}{3} \log_{10} N, \tag{1.1}$$

where  $N$  is the sample size. Then it follows that  $l = \frac{x_{\max} - x_{\min}}{n}$ .

The other is a formula for the class width

$$l = \frac{8}{100} (x_{\max} - x_{\min}). \tag{1.2}$$

Then  $n = \frac{x_{\max} - x_{\min}}{l}$ .

Once we determined  $n$  and  $l$ , we have  $c_i = x_{\min} + i \cdot l$ ,  $i = \overline{0, n}$ .

## Histograms and Frequency Polygons

When data is grouped into classes, the best way to visualize the frequency distribution is by constructing a **histogram** (hist). A histogram is a type of bar graph, where classes are represented by rectangles whose bases are the class lengths and whose heights are chosen so that the areas of the rectangles are proportional to the class frequencies. If the classes have all the same length, then the heights will be proportional to the class frequencies. If relative frequencies are considered (so the proportionality factor is  $N$ , the total number of observations), then the total areas of all rectangles will be equal to 1. For a large volume of data grouped into a reasonably large number of classes, the histogram gives a rough approximation of the density function (pdf) of the population from which the sample data was drawn.

An alternative in that sense (the sense of roughly approximating the shape of the density function) to histograms are **frequency polygons**, obtained by joining the points with coordinates  $(x_i, f_i)$ ,  $i = \overline{1, n}$  ( $x$ -coordinates are the class marks and  $y$ -coordinates are the class frequencies).

**Example 1.3.** The following represents the grades distribution in a Statistics exam, for a group of 3<sup>rd</sup> year students:

7 8 10 5 4 5 5 6 5 8 9 9 1 4 5 5 7 10  
5 9 2 2 10 10 8 3 8 7 5 6 7 8 9 9 9 4.

Let us analyze these data. First, we sort them in increasing order:

1 2 2 3 4 4 4 5 5 5 5 5 5 5 5 6 6 7  
7 7 7 8 8 8 8 8 9 9 9 9 9 9 10 10 10 10

There are  $N = 36$  observations, with  $x_{\min} = 1$  and  $x_{\max} = 10$ .

Since the sample size is not too large and there are repetitions, we can construct the ungrouped frequency distribution table:

Value	Frequency
1	1
2	2
3	1
4	3
5	8
6	2
7	4
8	5
9	6
10	4

Table 2: Frequency Distribution Table

Let us group the data into classes of the same length. With Sturges' rule, we get

$$n = 6.1877 \approx 6, \quad l = 1.5,$$

while if using formula (1.2), we have

$$l = 0.72, \quad n \approx 12.$$

The grouped frequency tables are shown in Tables 3 and 4. We have also included the relative and cumulative frequencies. Figure 2 shows the corresponding histogram and frequency polygon for grouped data.

No	Class	Mark	Freq.	C. Freq.	R. Freq.	R. C. Freq.
1	[ 1.00 , 2.50)	1.75	3	3	8%	8%
2	[ 2.50 , 4.00)	3.25	4	7	11%	19%
3	[ 4.00 , 5.50)	4.75	8	15	22%	41%
4	[ 5.50 , 7.00)	6.25	6	21	17%	58%
5	[ 7.00 , 8.50)	7.75	5	26	14%	72%
6	[ 8.50 , 10.00]	9.25	10	36	28%	100%

Table 3: Grouped Frequency Distribution Table With  $n = 6$  Classes

**Remark 1.4.** Due to rounding errors, the length of the last class may be slightly different than the rest of them, even when we group data into classes of the same width.

No	Class	Mark	Freq.	C. Freq.	R. Freq.	R. C. Freq.
1	[ 1.00 , 1.72)	1.36	1	1	3%	3%
2	[ 1.72 , 2.44)	2.08	2	3	6%	9%
3	[ 2.44 , 3.16)	2.80	1	4	3%	12%
4	[ 3.16 , 3.88)	3.52	0	4	0%	12%
5	[ 3.88 , 4.60)	4.24	3	7	8%	20%
6	[ 4.60 , 5.32)	4.96	8	15	22%	42%
7	[ 5.32 , 6.04)	5.68	2	17	6%	48%
8	[ 6.04 , 6.76)	6.40	0	17	0%	48%
9	[ 6.76 , 7.48)	7.12	4	21	11%	59%
10	[ 7.48 , 8.20)	7.84	5	26	14%	73%
11	[ 8.20 , 8.92)	8.56	0	26	0%	73%
12	[ 8.92 , 10]	9.46	10	36	27%	100%

Table 4: Grouped Frequency Distribution Table With  $n = 12$  Classes

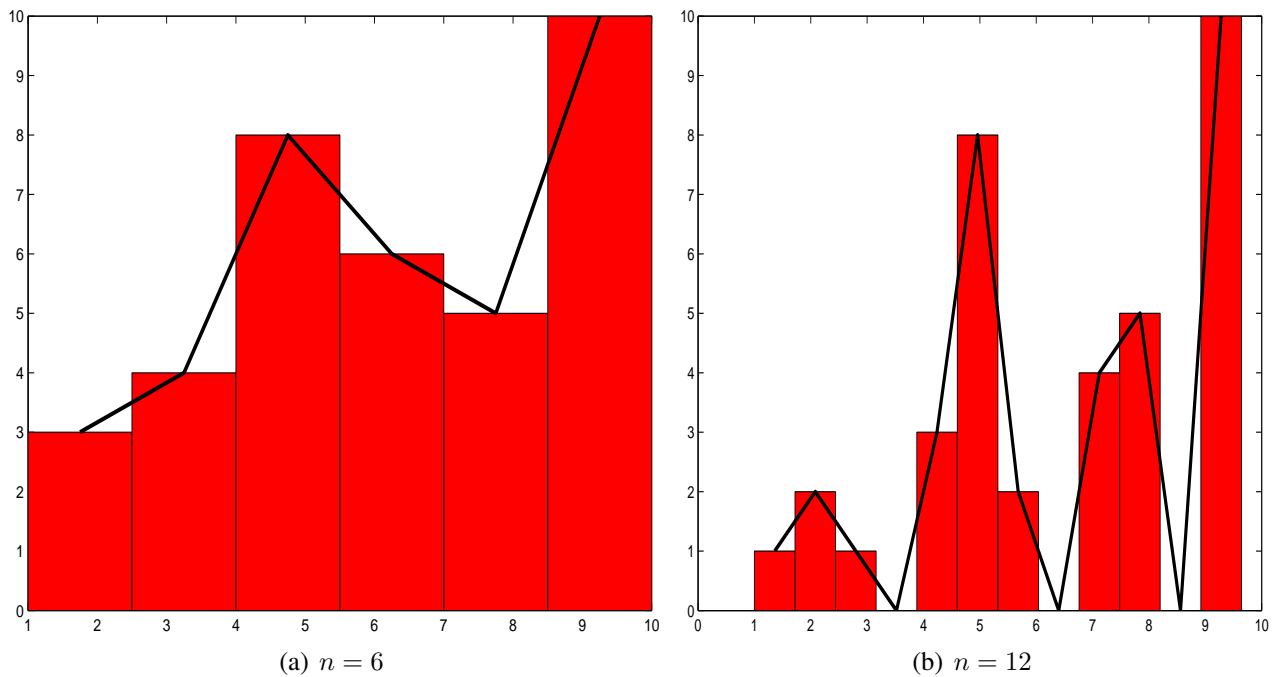


Fig. 2: Histogram and Frequency Polygon



## 2 Calculative Descriptive Statistics

In the last section, we have considered some graphical methods for getting an idea of the shape of the density function of the population from which the sample data was drawn. Some characteristics, such as symmetry, regularity can be observed from these graphical displays of the data. Next, we consider some statistics that allow us to summarize the data set analytically. It is hoped that these will give us some idea of the values of the parameters that characterize the entire population. We are looking mainly at two types of statistics: *measures of central tendency*, i.e. values that locate the observations with highest frequencies (so, where most of the data values lie) and *measures of variability* that indicate how much the values are spread out.

### 2.1 Measures of Central Tendency

These are values that tend to locate in some sense the “middle” of a set of data. The term “average” is often associated with these values. Each of the following measures of central tendency can be called the “average” value of a set of data.

**Definition 2.1.** The (*arithmetic*) *mean* ( $\overline{\text{mean}}$ ) of the data  $x_1, \dots, x_N$  is the value

$$\bar{x}_a = \frac{1}{N} \sum_{i=1}^N x_i. \quad (2.1)$$

For grouped data,  $\left( \begin{array}{c} x_i \\ f_i \end{array} \right)_{i=1, n}$ ,

$$\bar{x}_a = \frac{1}{N} \sum_{i=1}^n f_i x_i.$$

**Remark 2.2.** Some immediate properties of the arithmetic mean are the following:

1. The sum of all deviations from the mean is equal to 0. Indeed,

$$\sum_{i=1}^N (x_i - \bar{x}_a) = \sum_{i=1}^N x_i - N\bar{x}_a = 0.$$

2. The mean minimizes the mean square deviation, i.e. for every  $a \in \mathbb{R}$ ,

$$\sum_{i=1}^N (x_i - a)^2 \geq \sum_{i=1}^N (x_i - \bar{x}_a)^2.$$

A straightforward computation leads to

$$\begin{aligned}
 \sum_{i=1}^N (x_i - a)^2 &= \sum_{i=1}^N [(x_i - \bar{x}_a) - (a - \bar{x}_a)]^2 \\
 &= \sum_{i=1}^N (x_i - \bar{x}_a)^2 - 2(a - \bar{x}_a) \sum_{i=1}^N (x_i - \bar{x}_a) \\
 &\quad + N \sum_{i=1}^N (a - \bar{x}_a)^2 \\
 &\geq \sum_{i=1}^N (x_i - \bar{x}_a)^2,
 \end{aligned}$$

since the second term is 0 and the third term is always nonnegative.

**Definition 2.3.** The **geometric mean** (geomean) of the data  $x_1, \dots, x_N$  is the value

$$\bar{x}_g = \sqrt[N]{x_1 \dots x_N}. \quad (2.2)$$

For grouped data,  $\left( \begin{array}{c} x_i \\ f_i \end{array} \right)_{i=1, n}$ ,

$$\bar{x}_g = \sqrt[N]{x_1^{f_1} \dots x_n^{f_n}}.$$

The geometric mean is used in Economics Statistics for price study. One of its distinctive features is that it emphasizes the relative deviations from central tendency, as opposed to the absolute deviations, emphasized by the arithmetic mean.

**Definition 2.4.** The **harmonic mean** (harmmean) of the data  $x_1, \dots, x_N$  is the value

$$\bar{x}_h = \frac{N}{\sum_{i=1}^N \frac{1}{x_i}}. \quad (2.3)$$

For grouped data,  $\left( \begin{array}{c} x_i \\ f_i \end{array} \right)_{i=1, n}$ ,

$$\bar{x}_h = \frac{N}{\sum_{i=1}^n \frac{f_i}{x_i}}.$$

The harmonic mean has applications in Economics Statistics in the study of time norms.

**Remark 2.5.**

1. For any set of data  $x_1, \dots, x_N$ , the well-known *means inequality* holds:

$$\bar{x}_h \leq \bar{x}_g \leq \bar{x}_a,$$

with equality holding if and only if  $x_1 = \dots = x_N$ .

2. The most widely used is the arithmetic mean. When nothing else is mentioned, we simply say *mean*, instead of *arithmetic mean*, and use the simplified notation  $\bar{x}$ .

**Definition 2.6.** The **median** (median) is the value  $x_{me}$  that divides a set of ordered data  $X$  into two equal parts from the probability (or frequency) point of view, i.e. the value with the property

$$P(X < x_{me}) \leq \frac{1}{2} \leq P(X \leq x_{me}), \tag{2.4}$$

or, equivalently,

$$\begin{aligned} P(X > x_{me}) &\leq 1/2 \\ P(X < x_{me}) &\leq 1/2. \end{aligned} \tag{2.5}$$

So, the median is exceeded with probability no greater than 0.5 and is preceded with probability no greater than 0.5.

**Remark 2.7.**

1. For a sample, the median is exceeded by at most one half of the observations and is preceded by at most one half of observations.
2. The median may or may not be one of the values in the data. If the sorted primary data is

$$x_1 \leq \dots \leq x_N,$$

then

$$x_{me} = \begin{cases} x_{k+1}, & \text{if } N = 2k + 1 \\ \frac{x_k + x_{k+1}}{2}, & \text{if } N = 2k \end{cases} .$$

**Definition 2.8.** A *mode*,  $x_{mo}$ , of a set of data is a most frequent value.

**Remark 2.9.**

1. Notice from the wording of the definition that the mode may not be unique. A set of data can have one mode, two modes – *bimodal data*, three modes – *trimodal data*, or more – *multimodal data*. If every value occurs only once, we say that there is *no mode*.
2. For symmetric distributions, we have

$$\bar{x} = x_{me} = x_{mo}.$$

This is true, for instance, for the Normal distribution. In general,

$$x_{mo} \approx \bar{x} - 3(\bar{x} - x_{me}).$$

## 2.2 Measures of Variability

Once we have located the “middle” of a set of data, it is important to measure the variability of the data, how unstable the data can be and how much the data values can differ from its expectation or from other middle values. These values will help us assess reliability of our estimates and accuracy of our forecasts. These measures of variation will have small values for closely grouped data (little variation) and larger values for more widely spread out data (large variation).

Consider the primary data  $X = \{x_1, \dots, x_N\}$ . The first two measures of variation give a very general idea of the spread in the data values.

**Definition 2.10.** The *range* ( $\boxed{\text{range}}$ ) of  $X$  is the difference

$$x_{max} - x_{min}.$$

If the values of  $X$  are sorted in increasing order, then the range is  $x_N - x_1$ .

**Definition 2.11.** The *mean absolute deviation* ( $\boxed{\text{mad}}$ ) of  $X$  is the value

$$MAD = \frac{1}{N} \sum_{i=1}^N |x_i - \bar{x}|.$$

Next, following the idea behind the definition of the median, we define values that divide the data into certain percentages.

**Definition 2.12.** Let  $X$  be a set of data sorted increasingly.

- (1) The **percentiles** (prctile) of  $X$  are the values  $P_1, P_2, \dots, P_{99}$  that divide the data into 100 equal parts, i.e. for  $k = \overline{1, 99}$ ,  $P_k$  has the property

$$P(X < P_k) \leq \frac{k}{100}, \quad P(X > P_k) \leq \frac{100 - k}{100}. \quad (2.6)$$

- (2) The **quartiles** of  $X$  are the values

$$Q_1 = P_{25}, \quad Q_2 = P_{50} = x_{me} \quad \text{and} \quad Q_3 = P_{75}, \quad (2.7)$$

that divide the data into 4 equal parts.

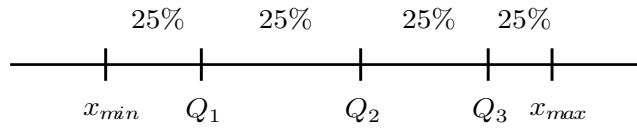


Fig. 3: Quartiles

**Definition 2.13.** Let  $X$  be a set of sorted data with quartiles  $Q_1, Q_2$  and  $Q_3$ .

- (1) The **interquartile range** (iqr) is the difference between the third and the first quartile

$$IQR = Q_3 - Q_1. \quad (2.8)$$

- (2) The **interquartile deviation** or the **semi interquartile range** is the value

$$IQD = \frac{IQR}{2} = \frac{Q_3 - Q_1}{2}. \quad (2.9)$$

- (3) The **interquartile deviation coefficient** or the **relative interquartile deviation** is the value

$$IQDC = \frac{IQD}{x_{me}} = \frac{Q_3 - Q_1}{2Q_2}. \quad (2.10)$$

**Remark 2.14.**

1. The interquartile deviation is an absolute measure of variation and it has an important property: the range  $x_{me} \pm IQD$  contains approximately 50% of the data.
2. The interquartile deviation coefficient  $IQDC$  varies between  $-1$  and  $1$ , taking values close to  $0$  for symmetrical distributions, with little variation and values close to  $\pm 1$  for skewed data with large variation.

**Outliers**

The interquartile range is also involved in another important aspect of statistical analysis, namely the detection of outliers. An *outlier*, as the name suggests, is basically an atypical value, “far away” from the rest of the data, that does not seem to belong to the distribution of the rest of the values in the data set.

For example, in a set of data where all values but one are between  $0$  and  $1$ , a value of  $1000$  would surely seem out of place!

```
>> x=[rand(10,1); 1000]
x =
```

```
1.0e+03 *
0.0007
0.0000
0.0003
0.0000
0.0001
0.0008
0.0007
0.0003
0.0010
0.0000
1.0000
```

Outliers can arise for two reasons: either they are legitimate observations whose values are simply unusually large or unusually small, compared to the rest of the values in the data set, or they are the result of an error in measurement, of poor experimental techniques, or of mistakes in recording or

entering the data. Whichever the reason, they can adversely affect some values of the measures of central tendency and of variation, thus leading to erroneous inferential results.

```
>> mean(x)
```

```
ans =
```

```
91.2707
```

```
>> median(x)
```

```
ans =
```

```
0.3171
```

Once the presence of such outliers is detected, it is suggested that sample statistics be computed both with and without the outliers.

```
>> x = x(1:end-1)
```

```
x =
```

```
0.7000
```

```
0
```

```
0.3000
```

```
0
```

```
0.1000
```

```
0.8000
```

```
0.7000
```

```
0.3000
```

```
1.0000
```

```
0
```

```
>> mean(x)
```

```
ans =
    0.3900

>> median(x)

ans =
    0.3000
```

Thus the problem of detecting and locating an outlier is an important part of any statistical data analysis process.

For instance, one simple procedure would be to consider an outlier any value that is more than 2.5 standard deviations away from the mean, and an extreme outlier a value more than 3 standard deviations away from the mean. This procedure is justified by the “ $3\sigma$  rule” (the “ $3\sigma$  rule” is an application of Chebyshev’s inequality and states that most of the values that any random variable takes, at least 89%, lie within 3 standard deviations away from the mean) and would work well for unimodal and symmetrical distributions.

A more general approach, that works for skewed data, is to consider an outlier any observation that is outside the range

$$\left[ Q_1 - \frac{3}{2}IQR, Q_3 + \frac{3}{2}IQR \right] = [Q_1 - 3IQD, Q_3 + 3IQD].$$

**Example 2.15.** Consider the following set of data

0.5973	0.3624	0.8304	1.7347	1.2499
0.1104	0.8082	0.6039	0.3046	0.6183
0.0065	0.8748	1.3528	1.6458	1.5117
0.3253	-2.0000	-1.3000	1.7500	3.8500

We sort them in increasing order:

-2.0000	-1.3000	0.0065	0.1104	0.3046
0.3253	0.3624	0.5973	0.6039	0.6183
0.8082	0.8304	0.8748	1.2499	1.3528
1.5117	1.6458	1.7347	1.7500	3.8500



We have:

$$\begin{aligned} Q_1 &= 0.3150, \\ Q_2 &= 0.7133, \\ Q_3 &= 1.4323, \end{aligned}$$

$$Q_1 - \frac{3}{2}IQR = -1.3610,$$

$$Q_3 + \frac{3}{2}IQR = 3.1082.$$

The data (boxplot) (horizontally) is displayed graphically in Figure 4.

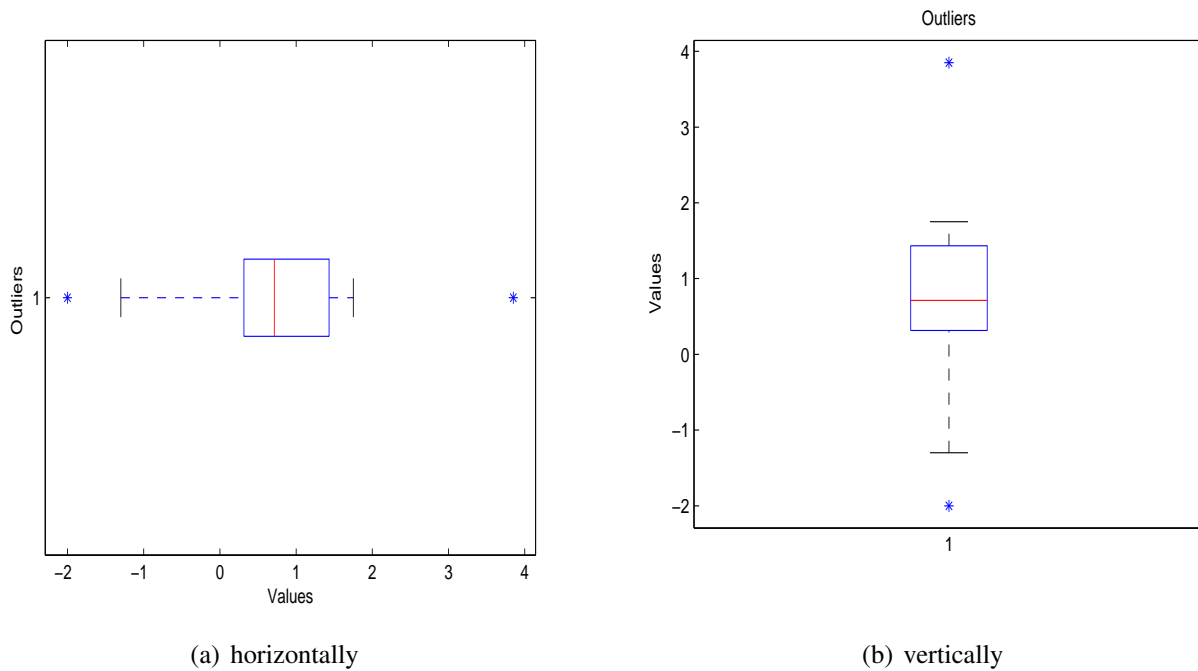


Fig. 4: Quartiles, Interquartile Range, Outliers

**Definition 2.16.**

(1) *The moment of order  $k$  is the value*

$$\bar{\nu}_k = \frac{1}{N} \sum_{i=1}^N x_i^k, \quad \bar{\nu}_k = \frac{1}{N} \sum_{i=1}^n f_i x_i^k, \tag{2.11}$$

*for primary and for grouped data, respectively.*

(2) The **central moment of order k** (`moment`) is the value

$$\bar{\mu}_k = \frac{1}{N} \sum_{i=1}^N (x_i - \bar{x})^k, \quad \bar{\mu}_k = \frac{1}{N} \sum_{i=1}^n f_i (x_i - \bar{x})^k \quad (2.12)$$

for primary and for grouped data, respectively.

(3) The **variance** (`var`) is the value

$$\bar{\sigma}^2 = \frac{1}{N} \sum_{i=1}^N (x_i - \bar{x})^2, \quad \bar{\sigma}^2 = \frac{1}{N} \sum_{i=1}^n f_i (x_i - \bar{x})^2 \quad (2.13)$$

for primary and for grouped data, respectively. The quantity  $\bar{\sigma} = \sqrt{\bar{\sigma}^2}$  is the **standard deviation** (`std`).

**Remark 2.17.**

1. We will see later that when the data represents a sample (not the entire population), a better formula for the variance is

$$s^2 = \frac{1}{N-1} \sum_{i=1}^N (x_i - \bar{x})^2, \quad s^2 = \frac{1}{N-1} \sum_{i=1}^n f_i (x_i - \bar{x})^2, \quad (2.14)$$

for the sample variance for primary or grouped data. The reason for that will have to do with the “bias” and will be explained later on in the next chapter. For now, we will just agree to use (2.13) to compute the variance of a set of data that represents a population and (2.14) for the variance of a sample.

2. In Matlab, when computing the variance of a population, we use `var(..., 1)`, as opposed to `var(...)`, for a sample. The command `std` has the same option.

3. A more efficient computational formula for the variance is

$$\bar{\sigma}^2 = \frac{1}{N} \left( \sum_{i=1}^N x_i^2 - \frac{1}{N} \left( \sum_{i=1}^N x_i \right)^2 \right), \quad (2.15)$$

which follows straight from the definition.

**Definition 2.18.** *The coefficient of variation is the value*

$$CV = \frac{\bar{\sigma}}{\bar{x}}.$$

**Remark 2.19.**

1. The coefficient of variation can be expressed as a ratio or as a percentage. It is useful in comparing the degrees of variation of two sets of data, even when their means are different.
2. The coefficient of variation is widely used in Biostatistics and Business Statistics. For example, in the investing world, the coefficient of variation helps brokers determine how much volatility (risk) they are assuming in comparison to the amount of return they can expect from a certain investment. The lower the value of the CV, the better the risk-return trade off.