

## APPLICATIONS OF FIBRE CONTRACTION PRINCIPLE TO SOME CLASSES OF FUNCTIONAL INTEGRAL EQUATIONS

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**Abstract.** Let  $a < c < b$  real numbers,  $(\mathbb{B}, |\cdot|)$  a (real or complex) Banach space,  $H \in C([a, b] \times [a, c] \times \mathbb{B}, \mathbb{B})$ ,  $K \in C([a, b]^2 \times \mathbb{B}, \mathbb{B})$ ,  $g \in C([a, b], \mathbb{B})$ ,  $A : C([a, c], \mathbb{B}) \rightarrow C([a, c], \mathbb{B})$  and  $B : C([a, b], \mathbb{B}) \rightarrow C([a, b], \mathbb{B})$ . In this paper we study the following functional integral equation,

$$x(t) = \int_a^c H(t, s, A(x)(s))ds + \int_a^t K(t, s, B(x)(s))ds + g(t), \quad t \in [a, b].$$

By a new variant of fibre contraction principle (A. Petrușel, I.A. Rus, M.A. Șerban, Some variants of fibre contraction principle and applications: from existence to the convergence of successive approximations, *Fixed Point Theory*, 22 (2021), no. 2, 795-808) we give existence, uniqueness and convergence of successive approximations results for this equation. In the case of ordered Banach space  $\mathbb{B}$ , Gronwall-type and comparison-type results are also given.

**Key Words and Phrases:** Functional integral equation, Volterra operator, Picard operator, fibre contraction principle, Gronwall lemma, comparison lemma.

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## 1. INTRODUCTION

In this paper we study the following functional integral equation,

$$x(t) = \int_a^c H(t, s, A(x)(s))ds + \int_a^t K(t, s, B(x)(s))ds + g(t), \quad t \in [a, b], \quad (1.1)$$

where  $a < c < b$  are real numbers,  $(\mathbb{B}, |\cdot|)$  is a Banach space,  $H \in C([a, b] \times [a, c] \times \mathbb{B}, \mathbb{B})$ ,  $K \in C([a, b]^2 \times \mathbb{B}, \mathbb{B})$ ,  $g \in C([a, b], \mathbb{B})$  and  $A : C([a, c], \mathbb{B}) \rightarrow C([a, c], \mathbb{B})$  and  $B : C([a, b], \mathbb{B}) \rightarrow C([a, b], \mathbb{B})$  are given operators.

For some examples of such integral equations see [5], [6], [16], [28], [2], [4], [7].

Let  $V : C([a, b], \mathbb{B}) \rightarrow C([a, b], \mathbb{B})$  be defined by

$$V(x)(t) := \int_a^c H(t, s, A(x)(s))ds + \int_a^t K(t, s, B(x)(s))ds + g(t), \quad t \in [a, b].$$

In this paper we consider on the spaces of continuous functions max-norms.

Let us suppose that

- (C<sub>1</sub>)  $\exists L_H > 0 : |H(t, s, \eta_1) - H(t, s, \eta_2)| \leq L_H |\eta_1 - \eta_2|$ , for all  $t \in [a, b]$ ,  $s \in [a, c]$ ,  $\eta_1, \eta_2 \in \mathbb{B}$ ;
- (C<sub>2</sub>)  $\exists L_K > 0 : |K(t, s, \eta_1) - K(t, s, \eta_2)| \leq L_K |\eta_1 - \eta_2|$ , for all  $t, s \in [a, b]$ ,  $\eta_1, \eta_2 \in \mathbb{B}$ ;
- (C<sub>3</sub>)  $\exists L_A > 0 : \max_{[a, c]} |A(y)(t) - A(z)(t)| \leq L_A \max_{[a, c]} |y(t) - z(t)|$ , for all  $y, z \in C([a, c], \mathbb{B})$ ;
- (C<sub>4</sub>)  $\exists L_B > 0 : |B(y)(t) - B(z)(t)| \leq L_B \max_{[a, t]} |y(s) - z(s)|$ , for all  $t \in [a, b]$ .

If we apply the contraction principle, in a standard way, for equation (1.1), we have the following result:

**Theorem 1.1.** *In addition to the above conditions we suppose that:*

$$(C'_5) \quad L_H L_A (c - a) + L_K L_B (b - a) < 1.$$

*Then the equation (1.1) has in  $C([a, b], \mathbb{B})$  a unique solutions,  $x^*$  and  $x^* = \lim_{n \rightarrow \infty} x_n$ , where  $x_n$  is defined by  $x_0 \in C([a, b], \mathbb{B})$ ,  $x_{n+1} = V(x_n)$ ,  $n \in \mathbb{N}$ , i.e.,  $V$  is a Picard operator.*

The aim of this paper is to improve condition  $(C'_5)$ , obtaining the same conclusions. In order to do this we shall apply instead of contraction principle, a new variant of fibre contraction principle, variant given in [13].

In a similar way we study the equation

$$x(t) = \int_b^c H(t, s, A(x)(s))ds + \int_b^t K(t, s, B(x)(s))ds + g(t), \quad t \in [a, b],$$

with suitable conditions on  $H$ ,  $K$ ,  $A$  and  $B$ .

Throughout this paper we shall use the notations from [28], [22] and [13].

## 2. PRELIMINARIES

**2.1. Weakly Picard operators.** Let  $(X, \rightarrow)$  be an  $L$ -space, where  $X$  is a nonempty set and  $\rightarrow$  is a convergence structure defined on  $X$ . If  $T : X \rightarrow X$  is an operator, then we denote by  $F_T := \{x \in X : x = T(x)\}$  the fixed point set of  $T$ .

In the above context,  $T : X \rightarrow X$  is called a weakly Picard operator (briefly *WPO*) if, for each  $x \in X$ , the sequence of Picard iterations  $(T^n(x))_{n \in \mathbb{N}}$  converges with respect to  $\rightarrow$  to a fixed point of  $T$ . In particular, if  $F_T = \{x^*\}$ , then  $T$  is called a Picard operator (briefly *PO*).

If  $T : X \rightarrow X$  is a *WPO*, then we define a set retraction  $T^\infty : X \rightarrow F_T$  by the formula

$$T^\infty(x) := \lim_{n \rightarrow \infty} T^n(x).$$

If  $T$  is *PO* with its unique fixed point  $x^*$ , then  $T^\infty(X) = \{x^*\}$ .

For the weakly Picard operator theory see [21], [29], [25], [27], [30].

**Theorem 2.1.** (*Abstract Gronwall lemma*) ([21], [29]) *Let  $(X, \rightarrow, \leq)$  be an ordered  $L$ -space and  $T : X \rightarrow X$  be an operator. We suppose that:*

- (i)  $T$  is a *WPO*;
- (ii)  $T$  is increasing.

*Then:*

- (a)  $x \leq T(x) \implies x \leq T^\infty(x)$ ;
- (b)  $x \geq T(x) \implies x \geq T^\infty(x)$ .

**Theorem 2.2.** (*Abstract Comparison lemma*) ([21], [29]) *Let  $(X, \rightarrow, \leq)$  be an ordered  $L$ -space and  $T, U, V : X \rightarrow X$  be three operators. We suppose that:*

- (i)  $T \leq U \leq V$ ;
- (ii)  $T, U$  and  $V$  are *WPOs*;
- (iii) the operator  $U$  is increasing.

*Then:*

$$x \leq y \leq z \implies T^\infty(x) \leq U^\infty(y) \leq V^\infty(z).$$

**2.2. Fibre contraction principle.** The standard fibre contraction principle has the following statement:

**Theorem 2.3.** *Let  $(X_0, \rightarrow)$  be an  $L$ -space. For  $m \in \mathbb{N}^*$ , let  $(X_i, d_i)$ ,  $i \in \{1, \dots, m\}$  be complete metric spaces. Let  $T_0 : X_0 \rightarrow X_0$  be an operator and, for  $i \in \{1, \dots, m\}$ , let us consider  $T_i : X_0 \times X_1 \times \dots \times X_i \rightarrow X_i$ . We suppose that:*

- (1)  $T_0$  is a *WPO*;
- (2) for each  $i \in \{1, 2, \dots, m\}$ , the operators  $T_i(x_0, \dots, x_{i-1}, \cdot) : X_i \rightarrow X_i$  are  $l_i$ -contractions;
- (3) for each  $i \in \{1, 2, \dots, m\}$ , the operators  $T_i$  are continuous.

*Then, the operator  $T = (T_0, T_1, \dots, T_m) : \prod_{i=0}^m X_i \rightarrow \prod_{i=0}^m X_i$ , defined by*

$$T(x_0, \dots, x_m) := (T_0(x_0), T_1(x_0, x_1), \dots, T_m(x_0, \dots, x_m))$$

is a WPO. Moreover, when  $T_0$  is a PO, then  $T$  is a PO too.

For other results regarding fibre contractions, see [11], [23], [30], [25], [34], [31], ..., fibre generalized contractions, see [20], [32], [33], [34], ..., fibre generalized contractions on generalized metric spaces, see [1], [3], [18], [24], [20], ... .

In [19] it is obtained a new type of fibre contraction principle in the following settings:

Let  $(X_i, d_i)$  ( $i \in \{1, \dots, m\}$  where  $m \geq 2$ ) be metric spaces and  $U_1 \subset X_1 \times X_2$ ,  $U_2 \subset U_1 \times X_3, \dots, U_{m-1} \subset U_{m-2} \times X_m$ , be nonempty subsets.

For  $x \in X_1$ , we define

$$U_{1x} := \{x_2 \in X_2 \mid (x, x_2) \in U_1\},$$

for  $x \in U_1$ , we define

$$U_{2x} := \{x_3 \in X_3 \mid (x, x_3) \in U_2\}, \dots,$$

and for  $x \in U_{m-2}$ , we define

$$U_{m-1x} := \{x_m \in X_m \mid (x, x_m) \in U_{m-1}\}.$$

We suppose that  $U_{1x}, U_{2x}, \dots, U_{m-1x}$  are nonempty.

If  $T_1 : X_1 \rightarrow X_1$ ,  $T_2 : U_1 \rightarrow X_2, \dots, T_m : U_{m-1} \rightarrow X_m$ , then we consider the operator

$$T : U_{m-1} \rightarrow X_1 \times X_2 \times \dots \times X_m,$$

defined by

$$T(x_1, \dots, x_m) := (T_1(x_1), T_2(x_1, x_2), \dots, T_m(x_1, x_2, \dots, x_m)).$$

The result is the following.

**Theorem 2.4.** ([19]) *We suppose that:*

(1)  $(X_i, d_i)$ ,  $i \in \{2, \dots, m\}$  are complete metric spaces and  $U_i$ ,  $i \in \{1, \dots, m-1\}$  are closed subsets;

(2)  $(T_1, T_2, \dots, T_{i+1})(U_i) \subset U_i$ ,  $i \in \{1, \dots, m-1\}$ ;

(3)  $T_1$  is a WPO;

(4) there exist  $L_i > 0$  and  $0 < l_i < 1$ ,  $i \in \{1, \dots, m-1\}$  such that

$$d_{i+1}(T_{i+1}(x, y), T_{i+1}(\tilde{x}, \tilde{y})) \leq L_i \tilde{d}_i(x, \tilde{x}) + l_i d_{i+1}(y, \tilde{y}),$$

for all  $(x, y), (\tilde{x}, \tilde{y}) \in U_i$ ,  $i \in \{1, \dots, m-1\}$ , where  $\tilde{d}_i$  is a metric induced by  $d_1, \dots, d_i$  on  $X_1 \times \dots \times X_i$ , defined by  $\tilde{d}_i := \max\{d_1, \dots, d_i\}$ .

Then  $T$  is WPO. If  $T_1$  is PO, then  $T$  is a PO too.

### 3. ABSTRACT VOLTERRA OPERATORS ON SPACES OF CONTINUOUS FUNCTIONS OF ONE VARIABLE

By definition, an operator  $V : C([a, b], \mathbb{B}) \rightarrow C([a, b], \mathbb{B})$  is forward Volterra operator if the following implication holds:

$$x, y \in C([a, b], \mathbb{B}), \quad x|_{[a, t]} = y|_{[a, t]} \Rightarrow V(x)|_{[a, t]} = V(y)|_{[a, t]},$$

for all  $t \in [a, b]$ .

An operator  $V : C([a, b], \mathbb{B}) \rightarrow C([a, b], \mathbb{B})$  is backward Volterra operator iff:

$$x, y \in C([a, b], \mathbb{B}), \quad x|_{[t, b]} = y|_{[t, b]} \Rightarrow V(x)|_{[t, b]} = V(y)|_{[t, b]},$$

for all  $t \in [a, b]$ .

If  $a < c < b$  then  $V$  is forward Volterra operator w.r.t. the interval  $[c, b]$  iff

$$x, y \in C([a, b], \mathbb{B}), \quad x|_{[a, t]} = y|_{[a, t]} \Rightarrow V(x)|_{[a, t]} = V(y)|_{[a, t]}, \quad \text{for all } t \in [c, b].$$

The operator  $V$  is backward Volterra operator w.r.t. the interval  $[a, c]$  iff:

$$x, y \in C([a, b], \mathbb{B}), \quad x|_{[t, b]} = y|_{[t, b]} \Rightarrow V(x)|_{[t, b]} = V(y)|_{[t, b]}, \quad \text{for all } t \in [a, c].$$

**Example 3.1.** For  $f \in C([a, b] \times \mathbb{R}^p, \mathbb{R}^p)$  let us consider the Cauchy problem

$$\begin{aligned} x'(t) &= f(t, x(t)), \quad t \in [a, b], \\ x(a) &= \alpha. \end{aligned}$$

This problem is equivalent with the following integral equation

$$x(t) = \alpha + \int_a^t f(s, x(s)) ds, \quad t \in [a, b].$$

Let  $V : C([a, b], \mathbb{R}^p) \rightarrow C([a, b], \mathbb{R}^p)$  be defined by

$$V(x)(t) := \alpha + \int_a^t f(s, x(s)) ds, \quad t \in [a, b].$$

The operator  $V$  is a forward Volterra operator.

If we consider the Cauchy problem

$$\begin{aligned} x'(t) &= f(t, x(t)), \quad t \in [a, b], \\ x(b) &= \beta, \end{aligned}$$

then this problem is equivalent with the integral equation,

$$x(t) = \beta + \int_b^t f(s, x(s)) ds, \quad t \in [a, b].$$

In this case the corresponding operator,  $V : C([a, b], \mathbb{R}^p) \rightarrow C([a, b], \mathbb{R}^p)$  defined by the second part of this integral equation is backward Volterra operator.

If for  $t_0 \in ]a, b[$ , we consider the Cauchy problem

$$\begin{aligned} x'(t) &= f(t, x(t)), \quad t \in [a, b], \\ x(t_0) &= \gamma, \end{aligned}$$

then this problem is equivalent with the integral equation

$$x(t) = \gamma + \int_{t_0}^t f(s, x(s)) ds, \quad t \in [a, b],$$

and the corresponding operator  $V$  is a forward Volterra operator with respect to  $[t_0, b]$  and is backward Volterra operator w.r.t. the interval  $[a, t_0]$ .

**Example 3.2.** Let the operator  $V : C[a, b] \rightarrow C[a, b]$  defined by  $V(x)(t) := x(g(t))$ , where  $g \in C([a, b], [a, b])$ . If  $g(t) \leq t, \forall t \in [a, b]$ , then  $V$  is forward Volterra operator and if  $g(t) \geq t, \forall t \in [a, b]$  then  $V$  is a backward Volterra operator.

**Example 3.3.**  $V : C[a, b] \rightarrow C[a, b], V(x)(t) := \max_{[a, t]} u(\tau), t \in [a, b]$  is a forward Volterra operator.

**Example 3.4.** Let  $A : C([a, b], \mathbb{B}) \rightarrow C([a, b], \mathbb{B})$  be a forward Volterra operator. Then the operator  $V : C([a, b], \mathbb{B}) \rightarrow C([a, b], \mathbb{B})$  defined by

$$V(x)(t) := \int_a^t A(u)(s) ds$$

is a forward Volterra operator.

**Example 3.5.** ([2], [16]) Let  $V : C([0, b], \mathbb{B}) \rightarrow C([0, b], \mathbb{B})$  be such that

$$|V(x)(t) - V(y)(t)| \leq \alpha |x(t) - y(t)| + \frac{\gamma}{t^\beta} \int_0^t |x(s) - y(s)| ds,$$

$\forall x, y \in C([0, b], \mathbb{B}), \forall t \in [0, b]$ , where  $\alpha, \beta \in [0, 1[$  and  $\gamma > 0$  are given real numbers.

The operator  $V$  is a forward Volterra operator.

For more considerations on abstract Volterra operator, see [9], [36]. For other examples see [2], [4], [5], [6], [7], [12], [14], [16], [17], [22], [35], ...

#### 4. BASIC RESULTS

Let us consider the equation (1.1) in the conditions  $(C_1) - (C_4)$ . For  $m \in \mathbb{N}, m \geq 2$  we shall use the following notations:

$$t_0 := c, \quad t_k := c + \frac{k(b-c)}{m}, \quad k = \overline{1, m}, \quad X_0 = C([a, c], \mathbb{B}),$$

$$X_i = C([t_{i-1}, t_i], \mathbb{B}), \quad X = \prod_{i=0}^m X_i.$$

We consider the spaces of continuous functions with the max-norms. In order to use the variant of fibre contraction principle given by Theorem 2.4, we need the following subsets:

$$U_i = \{(x_0, x_1, \dots, x_i) \in \prod_{k=0}^i X_k \mid x_k(t_k) = x_{k+1}(t_k), \quad k = \overline{1, m-1}\}, \quad i = \overline{1, m}.$$

For  $x \in X_0$ ,

$$U_{1x} := \{x_1 \in X_1 \mid (x, x_1) \in U_1\},$$

for  $x \in X_{i-1}$ ,

$$U_{ix} := \{x_i \in X_i \mid (x, x_i) \in U_i\}, \quad i = \overline{2, m}.$$

We remark that,  $U_i, U_{ix}$ ,  $i = \overline{1, m}$  are nonempty closed subsets.

We also need the following operators:

$$R_i : C([a, t_i], \mathbb{B}) \rightarrow \prod_{k=0}^i X_k, \quad R_i(x) = \left( x|_{[a, t_0]}, x|_{[t_0, t_1]}, \dots, x|_{[t_{i-1}, t_i]} \right), \quad i = \overline{1, m}.$$

It is clear that,  $R_i(C([a, t_i], \mathbb{B})) = U_i$  and  $R_i : C([a, t_i], \mathbb{B}) \rightarrow U_i$  is an increasing homeomorphism.

Since the operator,  $V : C([a, b], \mathbb{B}) \rightarrow C([a, b], \mathbb{B})$  defined by  $V(x)(t) :=$  second part of equation (1.1), is a forward Volterra operator on  $[c, b]$ , it induces the following operators:

$$\begin{aligned} T_0 & : X_0 \rightarrow X_0, \\ T_0(x_0)(t) & = V(x_0)(t), \quad t \in [a, c], \\ T_1 & : U_1 \rightarrow X_1, \\ T_1(x_0, x_1)(t) & := \int_a^c H(t, s, A(x_0)(s))ds + \int_a^c K(t, s, B(x_0)(s))ds \\ & + \int_c^t K(t, s, B(R_1^{-1}(x_0, x_1)(s)))ds + g(t), \quad t \in [c, t_1], \\ T_2 & : U_2 \rightarrow X_2, \\ T_2(x_0, x_1, x_2)(t) & := \int_a^c H(t, s, A(x_0)(s))ds + \int_a^c K(t, s, B(x_0)(s))ds \\ & + \int_c^{t_1} K(t, s, B(R_1^{-1}(x_0, x_1)(s)))ds \\ & + \int_{t_1}^t K(t, s, B(R_2^{-1}(x_0, x_1, x_2)(s)))ds + g(t), \quad t \in [t_1, t_2], \\ & \dots \\ T_m & : U_m \rightarrow X_m, \\ T_m(x_0, x_1, \dots, x_m)(t) & := \int_a^c H(t, s, A(x_0)(s))ds + \int_a^c K(t, s, B(x_0)(s))ds + \dots \\ & + \int_{t_{m-1}}^t K(t, s, B(R_m^{-1}(x_0, x_1, \dots, x_m)(s)))ds + g(t), \quad t \in [t_{m-1}, b]. \end{aligned}$$

Let

$$\begin{aligned} T & : = (T_0, T_1, \dots, T_m), \\ T(x_0, x_1, \dots, x_m) & : = (T_0(x_0), T_1(x_0, x_1), \dots, T_m(x_0, x_1, \dots, x_m)). \end{aligned}$$

If on the cartesian product we consider max-norms, the operators  $R_i$ ,  $i = \overline{1, m}$  are isometries. From the above definitions, we remark that

$$(T_0, T_1)(U_1) \subset U_1, \quad (T_0, T_1, \dots, T_m)(U_m) \subset U_m.$$

In the conditions  $(C_1) - (C_4)$  we have that:  $T_0$  is  $(L_H L_A + L_K L_B)(c-a)$ -Lipschitz.

If we suppose that

$$(C_5) \quad (L_H L_A + L_K L_B)(c - a) < 1$$

then we are in the conditions of Theorem 2.4 with

$$L_i = \max \left\{ (L_H L_A + L_K L_B)(c - a), \frac{L_K L_B(b - c)}{m} \right\}$$

and  $l_i = \frac{L_K L_B(b - c)}{m}$ , with suitable  $m \in \mathbb{N}$ .

From this theorem we have that  $T$  is PO.

Since  $V = R_m^{-1} T R_m$  and  $V^n = R_m^{-1} T^n R_m$ , it follows that  $V$  is PO.

So, we have:

**Theorem 4.1.** *We consider the equation (1.1) in the condition  $(C_1) - (C_5)$ . Under these conditions we have that:*

- (i) *The equation (1.1) has in  $C([a, b], \mathbb{B})$  a unique solution,  $x^*$ .*
- (ii) *The sequence,  $(x_n)_{n \in \mathbb{N}}$ , defined by*

$$\begin{aligned} x^0 &\in C([a, b], \mathbb{B}), \\ x^{n+1}(t) &= \int_a^c H(t, s, A(x^n)(s)) ds + \int_a^t K(t, s, B(x^n)(s)) ds + g(t), \quad t \in [a, b], \end{aligned}$$

*converges to  $x^*$ , i.e., the operator  $V$  is PO.*

**Remark 4.2.** If we take,  $\mathbb{B} = \mathbb{R}^p$  or  $\mathbb{C}^p$  or another finite dimensional Banach space, then Theorem 4.1 is a result for a system of functional integral equations.

**Remark 4.3.** If we take,  $\mathbb{B} := l^p(\mathbb{C})$  or  $\mathbb{B} := l^p(\mathbb{R})$ ,  $1 \leq p \leq \infty$ , or another Banach space of sequences, Theorem 4.1 is a result for an infinite system of functional integral equations.

**Remark 4.4.** For some particular cases of  $A$  and  $B$  our result is in connection with some result given in [2], [4], [5], [6], [7], [10], [14], [26], [28], [35], [8], [12], [13], [15].

## 5. EQUATIONS WITH BACKWARD VOLTERRA OPERATORS

In this section we consider the following integral equation

$$x(t) = \int_b^c H(t, s, A(x)(s)) ds + \int_b^t K(t, s, B(x)(s)) ds + g(t), \quad t \in [a, b], \quad (5.1)$$

where  $a < c < b$  are real numbers,  $(\mathbb{B}, |\cdot|)$  is a Banach space,  $H \in C([a, b] \times [c, b] \times \mathbb{B}, \mathbb{B})$ ,  $K \in C([a, b]^2 \times \mathbb{B}, \mathbb{B})$ ,  $g \in C([a, b], \mathbb{B})$  and  $A : C([c, b], \mathbb{B}) \rightarrow C([c, b], \mathbb{B})$  and  $B : C([a, b], \mathbb{B}) \rightarrow C([a, b], \mathbb{B})$  are operators. We suppose that:

- $(\tilde{C}_1) \quad \exists L_H > 0 : |H(t, s, \eta_1) - H(t, s, \eta_2)| \leq L_H |\eta_1 - \eta_2|$ , for all  $t \in [a, b]$ ,  $s \in [c, b]$ ,  $\eta_1, \eta_2 \in \mathbb{B}$ ;
- $(\tilde{C}_2) \quad \exists L_K > 0 : |K(t, s, \eta_1) - K(t, s, \eta_2)| \leq L_K |\eta_1 - \eta_2|$ , for all  $t, s \in [a, b]$ ,  $\eta_1, \eta_2 \in \mathbb{B}$ ;
- $(\tilde{C}_3) \quad \exists L_A > 0 : \max_{[c, b]} |A(y)(t) - A(z)(t)| \leq L_A \max_{[c, b]} |y(t) - z(t)|$ , for all  $y, z \in C([c, b], \mathbb{B})$ ;
- $(\tilde{C}_4) \quad \exists L_B > 0 : |B(y)(t) - B(z)(t)| \leq L_B \max_{[t, b]} |y(s) - z(s)|$ , for all  $t \in [a, b]$ ;



$$(\tilde{C}_5) (L_H L_A + L_K L_B)(b - c) < 1.$$

For  $m \in \mathbb{N}, m \geq 2$  we shall use the following notations:

$$t_0 := c, \quad t_k := c - \frac{k(c-a)}{m}, \quad k = \overline{1, m}, \quad X_0 = C([c, b], \mathbb{B}),$$

$$X_i = C([t_{i+1}, t_i], \mathbb{B}), \quad X = \prod_{i=0}^m X_i.$$

We will apply again Theorem 2.4 in the following settings. The continuous functions spaces are endowed with the max-norms. We consider the following subsets:

$$U_i = \{(x_0, x_1, \dots, x_i) \in \prod_{k=0}^i X_k \mid x_k(t_k) = x_{k+1}(t_k), \quad k = \overline{0, m-1}\}, \quad i = \overline{1, m},$$

$$U_{1x} := \{x_1 \in X_1 \mid (x, x_1) \in U_1\}, \quad \text{for } x \in X_0.$$

For  $x \in X_0$ , for  $x \in X_{i-1}$ ,  $U_{ix} := \{x_i \in X_i \mid (x, x_i) \in U_i\}$ ,  $i = \overline{2, m}$ .

We remark that,  $U_i, U_{ix}$ ,  $i = \overline{1, m}$  are nonempty closed subsets.

We also need the following operators:

$$R_i : C([t_i, b], \mathbb{B}) \rightarrow \prod_{k=0}^i X_k, \quad R_i(x) = \left( x|_{[t_0, b]}, x|_{[t_1, t_0]}, \dots, x|_{[t_i, t_{i-1}]} \right), \quad i = \overline{1, m}.$$

It is clear that,  $R_i(C([t_i, b], \mathbb{B})) = U_i$  and  $R_i : C([t_i, b], \mathbb{B}) \rightarrow U_i$  is an increasing homeomorphism.

Since the operator,  $V : C([a, b], \mathbb{B}) \rightarrow C([a, b], \mathbb{B})$  defined by  $V(x)(t) :=$  second part of equation (5.1), is a backward Volterra operator on  $[a, c]$ , it induces the following operators:

$$\begin{aligned} T_0 & : X_0 \rightarrow X_0, \\ T_0(x_0)(t) & : = V(x_0)(t), \quad t \in [c, b], \\ T_1 & : U_1 \rightarrow X_1, \\ T_1(x_0, x_1)(t) & := \int_b^c H(t, s, A(x_0)(s))ds + \int_b^c K(t, s, B(x_0)(s))ds \\ & + \int_c^t K(t, s, B(R_1^{-1}(x_0, x_1)(s))ds + g(t), \quad t \in [t_1, c], \\ T_2 & : U_2 \rightarrow X_2, \\ T_2(x_0, x_1, x_2)(t) & := \int_b^c H(t, s, A(x_0)(s))ds + \int_b^c K(t, s, B(x_0)(s))ds \\ & + \int_c^{t_1} K(t, s, B(R_1^{-1}(x_0, x_1)(s))ds \\ & + \int_{t_1}^t K(t, s, B(R_2^{-1}(x_0, x_1, x_2)(s))ds + g(t), \quad t \in [t_2, t_1], \\ & \dots \end{aligned}$$

$$T_m : U_m \rightarrow X_m,$$

$$T_m(x_0, x_1, \dots, x_m)(t) := \int_b^c H(t, s, A(x_0)(s))ds + \int_b^c K(t, s, B(x_0)(s))ds + \dots$$

$$+ \int_{t_{m-1}}^t K(t, s, B(R_m^{-1}(x_0, x_1, \dots, x_m)(s))ds + g(t), \quad t \in [a, t_{m-1}].$$

Let

$$T \quad : \quad = (T_0, T_1, \dots, T_m),$$

$$T(x_0, x_1, \dots, x_m) \quad : \quad = (T_0(x_0), T_1(x_0, x_1), \dots, T_m(x_0, x_1, \dots, x_m)).$$

If on the cartesian product we consider max-norms, the operators  $R_i$ ,  $i = \overline{1, m}$  are isometries. From the above definitions, we remark that

$$(T_0, T_1)(U_1) \subset U_1, \quad (T_0, T_1, \dots, T_m)(U_m) \subset U_m.$$

In the conditions  $(C_1) - (C_4)$  we have that:  $T_0$  is  $(L_H L_A + L_K L_B)(b - c)$ -contraction and  $T_i$ ,  $i = 1, \dots, m$ , satisfy the condition (5) from the Theorem 2.4 with  $L_i = \max \left\{ (L_H L_A + L_K L_B)(b - c), \frac{L_K L_B(c - a)}{m} \right\}$  and  $l_i = \frac{L_K L_B(c - a)}{m}$ , with suitable  $m \in \mathbb{N}$ .

From this theorem we have that  $T$  is PO.

Since  $V = R_m^{-1} T R_m$  and  $V^n = R_m^{-1} T^n R_m$ , it follows that  $V$  is PO.

So, we have:

**Theorem 5.1.** *We consider the equation (5.1) in the condition  $(\tilde{C}_1) - (\tilde{C}_5)$ . Under these conditions we have that:*

- (i) *The equation (5.1) has in  $C([a, b], \mathbb{B})$  a unique solution,  $x^*$ .*
- (ii) *The sequence,  $(x_n)_{n \in \mathbb{N}}$ , defined by*

$$x^0 \in C([a, b], \mathbb{B}),$$

$$x^{n+1}(t) = \int_a^c H(t, s, A(x^n)(s))ds + \int_a^t K(t, s, B(x^n)(s))ds + g(t), \quad t \in [a, b],$$

*converges to  $x^*$ , i.e., the operator  $V$  is PO.*

## 6. GRONWALL-TYPE RESULTS

In this section we consider  $(\mathbb{B}, |\cdot|, \leq)$  an ordered Banach space. Related to the equation (1.1)

$$x(t) = \int_a^c H(t, s, A(x)(s))ds + \int_a^t K(t, s, B(x)(s))ds + g(t), \quad t \in [a, b],$$

we consider the inequalities:

$$x(t) \leq \int_a^c H(t, s, A(x)(s))ds + \int_a^t K(t, s, B(x)(s))ds + g(t), \quad t \in [a, b] \quad (6.1)$$

and

$$x(t) \geq \int_a^c H(t, s, A(x)(s))ds + \int_a^t K(t, s, B(x)(s))ds + g(t), \quad t \in [a, b]. \quad (6.2)$$

As an application of the Theorem 2.1 we have

**Theorem 6.1.** *We consider the equation (1.1) under the hypotheses  $(C_1) - (C_5)$  of the Theorem 4.1. In addition, we suppose that*

*$(C_6)$   $H(t, s, \cdot)$ ,  $K(t, s, \cdot)$ ,  $A$  and  $B$  are increasing.*

*Then*

- (a)  $x \leq x^*$  for any  $x$  solution of (6.1);
- (b)  $x \geq x^*$  for any  $x$  solution of (6.2);

*where  $x^*$  is the unique solution of (1.1).*

*Proof.* It follows from Theorem 4.1 that the operator  $V : C([a, b], \mathbb{B}) \rightarrow C([a, b], \mathbb{B})$  defined by  $V(x)(t) :=$  second part of equation (1.1) is a PO and from  $(C_6)$  we have that  $V$  is an increasing operator, so the conclusion is obtained from Theorem 2.1.  $\square$

## 7. COMPARISON-TYPE RESULTS

We consider the functional integral equations:

$$x_i(t) = \int_a^c H_i(t, s, A(x)(s))ds + \int_a^t K_i(t, s, B(x)(s))ds + g_i(t), \quad (7.1)$$

$$t \in [a, b], \quad i = \overline{1, 3},$$

where  $a < c < b$  are real numbers,  $(\mathbb{B}, |\cdot|, \leq)$  an ordered Banach space,  $H_i \in C([a, b] \times [a, c] \times \mathbb{B}, \mathbb{B})$ ,  $K_i \in C([a, b]^2 \times \mathbb{B}, \mathbb{B})$ ,  $g_i \in C([a, b], \mathbb{B})$ ,  $i = \overline{1, 3}$ , and  $A : C([a, c], \mathbb{B}) \rightarrow C([a, c], \mathbb{B})$  and  $B : C([a, b], \mathbb{B}) \rightarrow C([a, b], \mathbb{B})$  are given operators. We have the following comparison result:

**Theorem 7.1.** *We suppose that:*

- (i)  $H_i$ ,  $K_i$ ,  $g_i$ ,  $i = \overline{1, 3}$ ,  $A$ ,  $B$  satisfy the conditions  $(C_1) - (C_5)$ ;
- (ii)  $H_1 \leq H_2 \leq H_3$  and  $K_1 \leq K_2 \leq K_3$ ;
- (iii)  $H_2(t, s, \cdot)$ ,  $K_2(t, s, \cdot)$ ,  $A$  and  $B$  are increasing.

*If  $x_1(a) \leq x_2(a) \leq x_3(a)$  then  $x_1^* \leq x_2^* \leq x_3^*$ , where  $x_i^*$  is the unique solution of (7.1),  $i = \overline{1, 3}$ .*

*Proof.* From Theorem 4.1 we have that operator  $V_i : C([a, b], \mathbb{B}) \rightarrow C([a, b], \mathbb{B})$  defined by

$$V_i(x)(t) := \int_a^c H_i(t, s, A(x)(s))ds + \int_a^t K_i(t, s, B(x)(s))ds + g_i(t), \quad t \in [a, b]$$

is PO,  $i = \overline{1, 3}$ . Let  $F_{V_i} = \{x_i^*\}$ ,  $i = \overline{1, 3}$ .

If  $u \in \mathbb{B}$  then we denote by  $\tilde{u}$  the constant function

$$\tilde{u} : [a, b] \rightarrow \mathbb{B}, \quad \tilde{u}(t) = u.$$

It is clear that

$$V_i^\infty(\widetilde{x_i(a)}) = x_i^*, \quad i = \overline{1, 3},$$

and from (ii) we get that

$$V_1(x) \leq V_2(x) \leq V_3(x), \quad \forall x \in C([a, b], \mathbb{B}).$$

From condition (iii) we have that operator  $V_2$  is an increasing operator, so, the conclusion is obtained from Theorem 2.2.  $\square$

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