

## GENERAL COMPOSITE ITERATIVE METHODS FOR GENERAL SYSTEMS OF VARIATIONAL INEQUALITIES

A. LATIF\*, A.S.M. ALOFI\*\*, A.E. AL-MAZROOEI\*\*\* AND J.C. YAO\*\*\*\*

\*Department of Mathematics, King Abdulaziz University  
P.O. Box 80203, Jeddah 21589, Saudi Arabia  
E-mail: [alatif@kau.edu.sa](mailto:alatif@kau.edu.sa)

\*\*Department of Mathematics, King Abdulaziz University  
P.O. Box 80203, Jeddah 21589, Saudi Arabia  
E-mail: [aalofi1@kau.edu.sa](mailto:aalofi1@kau.edu.sa)

\*\*\*Department of Mathematics, University of Jeddah  
P.O.Box 80327, Jeddah 21589, Saudi Arabia  
E-mail: [aealmazrooei@kau.edu.sa](mailto:aealmazrooei@kau.edu.sa)

\*\*\*\*,<sup>1</sup>Center for General Education, China Medical University  
Taichung 40402, Taiwan;  
and  
Department of Mathematics, King Abdulaziz University  
P.O. Box 80203, Jeddah 21589, Saudi Arabia  
E-mail: [yaojc@mail.cmu.edu.tw](mailto:yaojc@mail.cmu.edu.tw)

**Abstract.** In this paper, we introduce a general composite implicit scheme and a general composite explicit scheme for finding a solution of general system of variational inequalities in a real Hilbert space. We establish the strong convergence of these two general composite schemes to a solution of the general system of variational inequalities which is the unique solution of some variational inequality. Applications to variational inequalities are given.

**Key Words and Phrases:** General composite iterative method, general system of variational inequalities, inverse-strongly monotone mapping, strictly pseudocontractive mapping, nonexpansive mapping, fixed point.

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### 1. INTRODUCTION

Let  $H$  be a real Hilbert space with inner product  $\langle \cdot, \cdot \rangle$  and induced norm  $\| \cdot \|$ ,  $C$  be a nonempty closed convex subset of  $H$ .

Let  $A : C \rightarrow H$  be a nonlinear mapping on  $C$ . The classical variational inequality problem (VIP) [15] is to find  $x^* \in C$  such that

$$\langle Ax^*, x - x^* \rangle \geq 0, \quad \forall x \in C. \quad (1.1)$$

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<sup>1</sup>Corresponding author.

The solution set of VIP (1.1) is denoted by  $\text{VI}(C, F)$ . The VIP (1.1) has been extensively studied both in theory and algorithms. See, e.g., [21], [16], [19], [3], [4], [13] and the references therein.

Let  $F_1, F_2 : C \rightarrow H$  be two mappings. We consider the following general system of variational inequalities (GSVI) of finding  $(x^*, y^*) \in C \times C$  such that

$$\begin{cases} \langle \nu_1 F_1 y^* + x^* - y^*, x - x^* \rangle \geq 0, & \forall x \in C, \\ \langle \nu_2 F_2 x^* + y^* - x^*, x - y^* \rangle \geq 0, & \forall x \in C, \end{cases} \quad (1.2)$$

where  $\nu_1 > 0$  and  $\nu_2 > 0$  are two constants. The solution set of GSVI (1.2) is denoted by  $\text{GSVI}(C, F_1, F_2)$ . Recently, many authors have been devoting the study of the GSVI (1.2); see e.g., [11], [24], [9], [7], [8], [2], [5], [10], [20], [14], [1], [6] and the references therein.

In this paper, we introduce a general composite implicit scheme and a general composite explicit scheme for finding a solution of GSVI (1.2) in a real Hilbert space  $H$ . Further, we establish the strong convergence of these two general composite schemes to a solution of GSVI (1.2), which is also the unique solution of some variational inequality.

## 2. PRELIMINARIES

We need the following notions and facts.

A mapping  $F : C \rightarrow H$  is said to be

(i)  $L$ -Lipschitz if there exists a constant  $L \geq 0$  such that

$$\|Fx - Fy\| \leq L\|x - y\|, \quad \forall x, y \in C.$$

(ii) monotone if

$$\langle Fx - Fy, x - y \rangle \geq 0, \quad \forall x, y \in C;$$

(iii)  $\eta$ -strongly monotone if there exists a constant  $\eta > 0$  such that

$$\langle Fx - Fy, x - y \rangle \geq \eta\|x - y\|^2, \quad \forall x, y \in C;$$

(iv)  $\alpha$ -inverse-strongly monotone if there exists a constant  $\alpha > 0$  such that

$$\langle Fx - Fy, x - y \rangle \geq \alpha\|Fx - Fy\|^2, \quad \forall x, y \in C.$$

It can be easily seen that if  $T$  is nonexpansive, then  $I - T$  is monotone. It is also easy to see that the projection  $P_C$  is 1-ism.

On the other hand, it is obvious that if  $F : C \rightarrow H$  is  $\alpha$ -inverse-strongly monotone, then  $F$  is monotone and  $\frac{1}{\alpha}$ -Lipschitz continuous. Moreover, we also have that, for all  $u, v \in C$  and  $\lambda > 0$ ,

$$\|(I - \lambda F)u - (I - \lambda F)v\|^2 \leq \|u - v\|^2 + \lambda(\lambda - 2\alpha)\|Fu - Fv\|^2. \quad (2.1)$$

So, if  $\lambda \leq 2\alpha$ , then  $I - \lambda F$  is a nonexpansive mapping from  $C$  to  $H$ .

A mapping  $T : C \rightarrow C$  is called  $k$ -strictly pseudocontractive (or a  $k$ -strict pseudocontraction) if there exists a constant  $k \in [0, 1)$  such that

$$\|Tx - Ty\|^2 \leq \|x - y\|^2 + k\|(I - T)x - (I - T)y\|^2, \quad \forall x, y \in C.$$

The mapping  $T$  is pseudocontractive if and only if

$$\langle Tx - Ty, x - y \rangle \leq \|x - y\|^2, \quad \forall x, y \in C.$$

$T$  is strongly pseudocontractive if and only if there exists a constant  $\lambda \in (0, 1)$  such that

$$\langle Tx - Ty, x - y \rangle \leq \lambda \|x - y\|^2, \quad \forall x, y \in C.$$

The mapping  $T$  is also said to be pseudocontractive if  $k = 1$  and  $T$  is said to be strongly pseudocontractive if there exists a positive constant  $\lambda \in (0, 1)$  such that  $T + (1 - \lambda)I$  is pseudocontractive.

For any sequence  $\{x_n\}$ , we use  $x_n \rightharpoonup x$  for weak convergence and  $x_n \rightarrow x$  for strong converges. Moreover, we use  $\omega_w(x_n)$  to denote the weak  $\omega$ -limit set of the sequence  $\{x_n\}$ , i.e.,

$$\omega_w(x_n) := \{x \in H : x_{n_i} \rightharpoonup x \text{ for some subsequence } \{x_{n_i}\} \text{ of } \{x_n\}\}.$$

We denote by  $\text{Fix}(T)$  the set of fixed points of  $T$  and by  $\mathbf{R}$  the set of all real numbers. The metric (or nearest point) projection from  $H$  onto  $C$  is the mapping  $P_C : H \rightarrow C$  which assigns to each point  $x \in H$  the unique point  $P_C x \in C$  satisfying the property

$$\|x - P_C x\| = \inf_{y \in C} \|x - y\| =: d(x, C).$$

The following properties of projections are useful for our results.

**Proposition 2.1.** *Given any  $x \in H$  and  $z \in C$ . One has*

- (i)  $z = P_C x \Leftrightarrow \langle x - z, y - z \rangle \leq 0, \forall y \in C;$
- (ii)  $z = P_C x \Leftrightarrow \|x - z\|^2 \leq \|x - y\|^2 - \|y - z\|^2, \forall y \in C;$
- (iii)  $\langle P_C x - P_C y, x - y \rangle \geq \|P_C x - P_C y\|^2, \forall y \in H,$  which hence implies that  $P_C$  is nonexpansive and monotone.

A mapping  $T : H \rightarrow H$  is said to be firmly nonexpansive if  $2T - I$  is nonexpansive, or equivalently, if  $T$  is 1-inverse strongly monotone (1-ism),

$$\langle x - y, Tx - Ty \rangle \geq \|Tx - Ty\|^2, \quad \forall x, y \in H.$$

**Proposition 2.2.** (see [9]) *For given  $\bar{x}, \bar{y} \in C, (\bar{x}, \bar{y})$  is a solution of the GSVI (1.2) if and only if  $\bar{x}$  is a fixed point of the mapping  $G : C \rightarrow C$  defined by*

$$Gx = P_C(I - \nu_1 F_1)P_C(I - \nu_2 F_2)x, \quad \forall x \in C,$$

where  $\bar{y} = P_C(I - \nu_2 F_2)\bar{x}$ .

In particular, if the mapping  $F_j : C \rightarrow H$  is  $\zeta_j$ -inverse-strongly monotone for  $j = 1, 2$ , then the mapping  $G$  is nonexpansive provided  $\nu_j \in (0, 2\zeta_j]$  for  $j = 1, 2$ . We denote by  $\Xi$  the fixed point set of the mapping  $G$ .

We need some facts and tools in a real Hilbert space  $H$  which are listed as lemmas below.

**Lemma 2.1.** *Let  $X$  be a real inner product space. Then there holds the following inequality*

$$\|x + y\|^2 \leq \|x\|^2 + 2\langle y, x + y \rangle, \quad \forall x, y \in X.$$

**Lemma 2.2.** *Let  $H$  be a real Hilbert space. Then the following hold:*

- (a)  $\|x - y\|^2 = \|x\|^2 - \|y\|^2 - 2\langle x - y, y \rangle$  for all  $x, y \in H;$
- (b)  $\|\lambda x + \mu y\|^2 = \lambda\|x\|^2 + \mu\|y\|^2 - \lambda\mu\|x - y\|^2$  for all  $x, y \in H$  and  $\lambda, \mu \in [0, 1]$  with  $\lambda + \mu = 1;$

(c) If  $\{x_n\}$  is a sequence in  $H$  such that  $x_n \rightharpoonup x$ , it follows that

$$\limsup_{n \rightarrow \infty} \|x_n - y\|^2 = \limsup_{n \rightarrow \infty} \|x_n - x\|^2 + \|x - y\|^2, \quad \forall y \in H.$$

It is clear that, in a real Hilbert space  $H$ ,  $T : C \rightarrow C$  is  $k$ -strictly pseudocontractive if and only if the following inequality holds:

$$\langle Tx - Ty, x - y \rangle \leq \|x - y\|^2 - \frac{1 - k}{2} \|(I - T)x - (I - T)y\|^2, \quad \forall x, y \in C.$$

This immediately implies that if  $T$  is a  $k$ -strictly pseudocontractive mapping, then  $I - T$  is  $\frac{1-k}{2}$ -inverse strongly monotone.

**Lemma 2.3.** (see [17, Proposition 2.1]) *Let  $C$  be a nonempty closed convex subset of a real Hilbert space  $H$  and  $T : C \rightarrow C$  be a mapping.*

(i) *If  $T$  is a  $k$ -strictly pseudocontractive mapping, then  $T$  satisfies the Lipschitzian condition*

$$\|Tx - Ty\| \leq \frac{1 + k}{1 - k} \|x - y\|, \quad \forall x, y \in C.$$

(ii) *If  $T$  is a  $k$ -strictly pseudocontractive mapping, then the mapping  $I - T$  is semiclosed at 0, that is, if  $\{x_n\}$  is a sequence in  $C$  such that  $x_n \rightharpoonup \tilde{x}$  and  $(I - T)x_n \rightarrow 0$ , then  $(I - T)\tilde{x} = 0$ .*

(iii) *If  $T$  is  $k$ -(quasi-)strict pseudocontraction, then the fixed-point set  $\text{Fix}(T)$  of  $T$  is closed and convex so that the projection  $P_{\text{Fix}(T)}$  is well defined.*

**Lemma 2.4.** *Let  $C$  be a nonempty closed convex subset of a real Hilbert space  $H$ . Let  $T : C \rightarrow C$  be a  $k$ -strictly pseudocontractive mapping. Let  $\gamma$  and  $\delta$  be two nonnegative real numbers such that  $(\gamma + \delta)k \leq \gamma$ . Then*

$$\|\gamma(x - y) + \delta(Tx - Ty)\| \leq (\gamma + \delta)\|x - y\|, \quad \forall x, y \in C.$$

Let  $C$  be a nonempty closed convex subset of a real Hilbert space  $H$ . We introduce some notations. Let  $\lambda$  be a number in  $(0, 1]$  and let  $\mu > 0$ . Associating with a nonexpansive mapping  $T : C \rightarrow C$ , we define the mapping  $T^\lambda : C \rightarrow H$  by

$$T^\lambda x := Tx - \lambda\mu F(Tx), \quad \forall x \in C,$$

where  $F : C \rightarrow H$  is an operator such that, for some positive constants  $\kappa, \eta > 0$ ,  $F$  is  $\kappa$ -Lipschitzian and  $\eta$ -strongly monotone on  $C$ ; that is,  $F$  satisfies the conditions:

$$\|Fx - Fy\| \leq \kappa\|x - y\| \quad \text{and} \quad \langle Fx - Fy, x - y \rangle \geq \eta\|x - y\|^2$$

for all  $x, y \in C$ .

### 3. MAIN RESULTS

Let  $C$  be a nonempty closed convex subset of a real Hilbert space  $H$ . Throughout this section, we always assume the following:

$F : C \rightarrow H$  is a  $\kappa$ -Lipschitzian and  $\eta$ -strongly monotone operator with positive constants  $\kappa, \eta > 0$ , and  $F_j : C \rightarrow H$  is  $\zeta_j$ -inverse strongly monotone for  $j = 1, 2$ ;

$A$  is a  $\bar{\gamma}$ -strongly positive bounded linear operator on  $H$  with  $\bar{\gamma} \in (1, 2)$ , i.e., there exists a constant  $\bar{\gamma} > 0$  such that

$$\langle Ax, x \rangle \geq \bar{\gamma}\|x\|^2, \quad \forall x \in H;$$

$V : C \rightarrow H$  is an  $l$ -Lipschitzian mapping with constant  $l \geq 0$ ;

$0 < \mu < \frac{2\eta}{\kappa^2}$  and  $0 \leq \gamma l < \tau$  with  $\tau = 1 - \sqrt{1 - \mu(2\eta - \mu\kappa^2)}$ ;  
 $G_t := P_C(I - \nu_1(t)F_1)P_C(I - \nu_2(t)F_2)$ ,  $t \in (0, \min\{1, \frac{2-\bar{\gamma}}{\tau-\gamma l}\})$  and  
 $G := P_C(I - \nu_1F_1)P_C(I - \nu_2F_2)$  with  $0 < \nu_j \leq \nu_j(t) \leq 2\zeta_j$  and  $\lim_{t \rightarrow 0} \nu_j(t) = \nu_j$   
 for  $j = 1, 2$ ;  
 $G_n := P_C(I - \nu_{1,n}F_1)P_C(I - \nu_{2,n}F_2)$  with  $0 < \nu_j \leq \nu_{j,n} \leq 2\zeta_j$  and  $\lim_{n \rightarrow \infty} \nu_{j,n} = \nu_j$   
 for  $j = 1, 2$ ;  
 $\Xi \neq \emptyset$  and  $P_\Xi$  is the metric projection of  $H$  onto  $\Xi$ ;  
 $\{\alpha_n\} \subset [0, 1]$  and  $\{\beta_n\} \subset (0, 1]$ .

By Proposition 2.2, we know that  $G_t$  and  $G_n$  are nonexpansive and  $\text{Fix}(G) = \text{Fix}(G_t) = \text{Fix}(G_n)$ .

In this section, we introduce the first general composite scheme that generates a net  $\{x_t\}_{t \in (0, \min\{1, \frac{2-\bar{\gamma}}{\tau-\gamma l}\})}$  implicitly as follows:

$$x_t = P_C[(I - \theta_t A)G_t x_t + \theta_t(t\gamma V x_t + (I - t\mu F)G_t x_t)]. \quad (3.1)$$

We prove the strong convergence of  $\{x_t\}$  as  $t \rightarrow 0$  to a fixed point  $\tilde{x}$  of  $G$  (i.e.,  $\tilde{x} \in \Xi$ ), which is a unique solution to the VIP

$$\langle (A - I)\tilde{x}, p - \tilde{x} \rangle \geq 0, \quad \forall p \in \Xi. \quad (3.2)$$

For arbitrarily given  $x_0 \in C$ , we also propose the second general composite explicit scheme, which generates a sequence  $\{x_n\}$  in an explicit way:

$$\begin{cases} y_n = \alpha_n \gamma V x_n + (I - \alpha_n \mu F)G_n x_n, \\ x_{n+1} = P_C[(I - \beta_n A)G_n x_n + \beta_n y_n], \quad \forall n \geq 0, \end{cases} \quad (3.3)$$

and establish the strong convergence of  $\{x_n\}$  as  $n \rightarrow \infty$  to a fixed point  $\tilde{x}$  of  $G$  (i.e.,  $\tilde{x} \in \Xi$ ), which is also the unique solution to VIP (3.2).

Now, for  $t \in (0, \min\{1, \frac{2-\bar{\gamma}}{\tau-\gamma l}\})$ , and  $\theta_t \in (0, \|A\|^{-1}]$ , consider a mapping  $Q_t : C \rightarrow C$  defined by

$$Q_t x = P_C[(I - \theta_t A)G_t x + \theta_t(t\gamma V x + (I - t\mu F)G_t x)], \quad \forall x \in C.$$

It is easy to see that  $Q_t$  is a contractive mapping with constant  $1 - \theta_t(\bar{\gamma} - 1 + t(\tau - \gamma l))$ . By the Banach contraction principle,  $Q_t$  has a unique fixed point, denoted by  $x_t$ , which uniquely solves the fixed point equation (3.1).

We summarize the basic properties of  $\{x_t\}$  as follows.

**Proposition 3.1.** *Let  $\{x_t\}$  be defined via (3.1). Then*

- (i)  $\{x_t\}$  is bounded for  $t \in (0, \min\{1, \frac{2-\bar{\gamma}}{\tau-\gamma l}\})$ ;
- (ii)  $\lim_{t \rightarrow 0} \|x_t - G_t x_t\| = 0$  provided  $\lim_{t \rightarrow 0} \theta_t = 0$ ;
- (iii)  $x_t : (0, \min\{1, \frac{2-\bar{\gamma}}{\tau-\gamma l}\}) \rightarrow H$  is locally Lipschitzian provided

$$\theta_t : (0, \min\{1, \frac{2-\bar{\gamma}}{\tau-\gamma l}\}) \rightarrow (0, \|A\|^{-1}]$$

is locally Lipschitzian, and  $\nu_j(t) : (0, \min\{1, \frac{2-\bar{\gamma}}{\tau-\gamma l}\}) \rightarrow [\nu_j, 2\zeta_j]$  is locally Lipschitzian for  $j = 1, 2$ ;

- (iv)  $x_t$  defines a continuous path from  $(0, \min\{1, \frac{2-\bar{\gamma}}{\tau-\gamma l}\})$  into  $H$  provided

$$\theta_t : (0, \min\{1, \frac{2-\bar{\gamma}}{\tau-\gamma l}\}) \rightarrow (0, \|A\|^{-1}]$$

is continuous, and  $\nu_j(t) : (0, \min\{1, \frac{2-\bar{\gamma}}{\tau-\gamma l}\}) \rightarrow [\nu_j, 2\zeta_j]$  is continuous for  $j = 1, 2$ .

We are now in a position to prove the following theorem for strong convergence of the net  $\{x_t\}$  as  $t \rightarrow 0$ , which guarantees the existence of solutions of the variational inequality (3.2).

**Theorem 3.1.** *Let the net  $\{x_t\}$  be defined via (3.1). If  $\lim_{t \rightarrow 0} \theta_t = 0$ , then  $x_t$  converges strongly to a fixed point  $\tilde{x}$  of  $G$  as  $t \rightarrow 0$ , which solves the VIP (3.2). Equivalently, we have  $P_{\Xi}(2I - A)\tilde{x} = \tilde{x}$ .*

*Proof.* We first note that we have the uniqueness of solutions of the VIP (3.2) which is a consequence of the strong monotonicity of  $A - I$ . Next, we prove that  $x_t \rightarrow \tilde{x}$  as  $t \rightarrow 0$ . Observing  $\text{Fix}(G) = \text{Fix}(G_t)$  by Proposition 2.2, from (3.1), we write, for given  $p \in \Xi$ ,

$$\begin{aligned} x_t - p &= x_t - w_t + w_t - p = x_t - w_t + (I - \theta_t A)(G_t x_t - G_t p) \\ &\quad + \theta_t [t(\gamma V x_t - \mu F p) + (I - t\mu F)G_t x_t - (I - t\mu F)p] + \theta_t (I - A)p, \end{aligned}$$

where  $w_t = (I - \theta_t A)G_t x_t + \theta_t (t\gamma V x_t + (I - t\mu F)G_t x_t)$ . Then, by Proposition 2.1 (i), we have

$$\begin{aligned} \|x_t - p\|^2 &= \langle x_t - w_t, x_t - p \rangle + \langle (I - \theta_t A)(G_t x_t - G_t p), x_t - p \rangle + \theta_t [t\langle \gamma V x_t - \mu F p, x_t - p \rangle \\ &\quad + \langle (I - t\mu F)G_t x_t - (I - t\mu F)p, x_t - p \rangle] + \theta_t \langle (I - A)p, x_t - p \rangle \\ &\leq (1 - \theta_t \bar{\gamma}) \|x_t - p\|^2 + \theta_t [(1 - t\tau) \|x_t - p\|^2 + t\gamma l \|x_t - p\|^2 \\ &\quad + t\langle (\gamma V - \mu F)p, x_t - p \rangle] + \theta_t \langle (I - A)p, x_t - p \rangle \\ &= [1 - \theta_t (\bar{\gamma} - 1 + t(\tau - \gamma l))] \|x_t - p\|^2 + \theta_t (t\langle (\gamma V - \mu F)p, x_t - p \rangle + \langle (I - A)p, x_t - p \rangle). \end{aligned}$$

Therefore,

$$\|x_t - p\|^2 \leq \frac{1}{\bar{\gamma} - 1 + t(\tau - \gamma l)} (t\langle (\gamma V - \mu F)p, x_t - p \rangle + \langle (I - A)p, x_t - p \rangle). \quad (3.4)$$

Since the net  $\{x_t\}_{t \in (0, \min\{1, \frac{2-\bar{\gamma}}{\tau-\gamma l}\})}$  is bounded (due to Proposition 3.1 (i)), we know that if  $\{t_n\}$  is a subsequence in  $(0, \min\{1, \frac{2-\bar{\gamma}}{\tau-\gamma l}\})$  such that  $t_n \rightarrow 0$  and  $x_{t_n} \rightarrow x^*$ , then from (3.4), we obtain  $x_{t_n} \rightarrow x^*$ . Let us show that  $x^* \in \Xi$ . To this end, note that  $G : C \rightarrow C$  defined by  $G := P_C(I - \nu_1 F_1)P_C(I - \nu_2 F_2)$  for  $0 < \nu_j \leq 2\zeta_j$  for  $j = 1, 2$ . Then  $G$  is nonexpansive with  $\text{Fix}(G) = \Xi$  (due to Proposition 2.2). By the definition of  $x_t$  and the nonexpansivity of  $P_C(I - \nu_j F_j)$ ,  $j = 1, 2$  we get

$$\begin{aligned} &\|Gx_{t_n} - x_{t_n}\| \\ &\leq \|Gx_{t_n} - G_{t_n}x_{t_n}\| + \|G_{t_n}x_{t_n} - x_{t_n}\| \\ &\leq \|P_C(I - \nu_1 F_1)P_C(I - \nu_2 F_2)x_{t_n} - P_C(I - \nu_1(t_n)F_1)P_C(I - \nu_2(t_n)F_2)x_{t_n}\| \\ &\quad + \|G_{t_n}x_{t_n} - (I - \theta_{t_n}A)G_{t_n}x_{t_n} - \theta_{t_n}(t_n\gamma V x_{t_n} + (I - t_n\mu F)G_{t_n}x_{t_n})\| \\ &\leq \|P_C(I - \nu_1 F_1)P_C(I - \nu_2 F_2)x_{t_n} - P_C(I - \nu_1(t_n)F_1)P_C(I - \nu_2(t_n)F_2)x_{t_n}\| \\ &\quad + \|P_C(I - \nu_1(t_n)F_1)P_C(I - \nu_2(t_n)F_2)x_{t_n} - P_C(I - \nu_1(t_n)F_1)P_C(I - \nu_2(t_n)F_2)x_{t_n}\| \\ &\quad + \theta_{t_n} \|(I - A)G_{t_n}x_{t_n} + t_n(\gamma V x_{t_n} - \mu F G_{t_n}x_{t_n})\| \\ &\leq \|(I - \nu_2 F_2)x_{t_n} - (I - \nu_2(t_n)F_2)x_{t_n}\| \\ &\quad + \|(I - \nu_1 F_1)P_C(I - \nu_2(t_n)F_2)x_{t_n} - (I - \nu_1(t_n)F_1)P_C(I - \nu_2(t_n)F_2)x_{t_n}\| \\ &\quad + \theta_{t_n} \|(I - A)G_{t_n}x_{t_n} + t_n(\gamma V x_{t_n} - \mu F G_{t_n}x_{t_n})\| \\ &= |\nu_2(t_n) - \nu_2| \|F_2 x_{t_n}\| + |\nu_1(t_n) - \nu_1| \|F_1 P_C(I - \nu_2(t_n)F_2)x_{t_n}\| \\ &\quad + \theta_{t_n} \|(I - A)G_{t_n}x_{t_n} + t_n(\gamma V x_{t_n} - \mu F G_{t_n}x_{t_n})\|. \end{aligned}$$

Since  $\theta_{t_n} \rightarrow 0$  and  $\nu_j(t_n) \rightarrow \nu_j$  as  $t_n \rightarrow 0$  for  $j = 1, 2$ , we have  $(I - G)x_{t_n} \rightarrow 0$  as  $t_n \rightarrow 0$ . Thus it follows from [12] that  $x^* \in \text{Fix}(G)$ . By Proposition 2.2 we get  $x^* \in \Xi$ .

Finally, let us show that  $x^*$  is a solution of the VIP (3.2). Since

$$x_t = x_t - w_t + (I - \theta_t A)G_t x_t + \theta_t(t\gamma V x_t + (I - t\mu F)G_t x_t),$$

we have

$$x_t - G_t x_t = x_t - w_t + \theta_t(I - A)G_t x_t + \theta_t t(\gamma V x_t - \mu F G_t x_t).$$

Since  $G_t$  is nonexpansive (due to Proposition 2.2),  $I - G_t$  is monotone. So, from the monotonicity of  $I - G_t$ , it follows that, for  $p \in \Xi = \text{Fix}(G_t)$ ,

$$\begin{aligned} 0 &\leq \langle (I - G_t)x_t - (I - G_t)p, x_t - p \rangle = \langle (I - G_t)x_t, x_t - p \rangle \\ &= \langle x_t - w_t, x_t - p \rangle + \theta_t \langle (I - A)G_t x_t, x_t - p \rangle + \theta_t t \langle \gamma V x_t - \mu F G_t x_t, x_t - p \rangle \\ &\leq \theta_t \langle (I - A)G_t x_t, x_t - p \rangle + \theta_t t \langle \gamma V x_t - \mu F G_t x_t, x_t - p \rangle \\ &= \theta_t \langle (I - A)x_t, x_t - p \rangle + \theta_t \langle (I - A)(G_t - I)x_t, x_t - p \rangle + \theta_t t \langle \gamma V x_t - \mu F G_t x_t, x_t - p \rangle. \end{aligned}$$

This implies that

$$\langle (A - I)x_t, x_t - p \rangle \leq \langle (I - A)(G_t - I)x_t, x_t - p \rangle + t \langle \gamma V x_t - \mu F G_t x_t, x_t - p \rangle. \quad (3.5)$$

Now, replacing  $t$  in (3.5) with  $t_n$  and letting  $n \rightarrow \infty$ , noticing the boundedness of  $\{\gamma V x_{t_n} - \mu F G_{t_n} x_{t_n}\}$  and the fact that  $(I - A)(G_{t_n} - I)x_{t_n} \rightarrow 0$  as  $n \rightarrow \infty$  (due to Proposition 3.1 (ii)), we obtain

$$\langle (A - I)x^*, x^* - p \rangle \leq 0.$$

That is,  $x^* \in \Xi$  is a solution of the VIP (3.2); hence  $x^* = \tilde{x}$  by uniqueness. In summary, we have proven that each cluster point of  $\{x_t\}$  (as  $t \rightarrow 0$ ) equals  $\tilde{x}$ . Consequently,  $x_t \rightarrow \tilde{x}$  as  $t \rightarrow 0$ .

The VIP (3.2) can be rewritten as

$$\langle (2I - A)\tilde{x} - \tilde{x}, \tilde{x} - p \rangle \geq 0, \quad \forall p \in \Xi.$$

Using Proposition 2.1 (i), the last inequality is equivalent to the fixed point equation

$$P_{\Xi}(2I - A)\tilde{x} = \tilde{x}. \quad \square$$

Taking  $F = \frac{1}{2}I$ ,  $\mu = 2$  and  $\gamma = 1$  in Theorem 3.1, we get

**Corollary 3.1.** *Let  $\{x_t\}$  be defined by*

$$x_t = P_C[(I - \theta_t A)G_t x_t + \theta_t(tV x_t + (1 - t)G_t x_t)].$$

*If  $\lim_{t \rightarrow 0} \theta_t = 0$ , then  $\{x_t\}$  converges strongly as  $t \rightarrow 0$  to a fixed point  $\tilde{x}$  of  $G$  (i.e.,  $\tilde{x} \in \Xi$ ), which is the unique solution of the VIP (3.2).*

Next, we prove the following result in order to establish the strong convergence of the sequence  $\{x_n\}$  generated by the general composite explicit scheme (3.3).

**Theorem 3.2.** *Let  $\{x_n\}$  be the sequence generated by the explicit scheme (3.3), where  $\{\alpha_n\}$  and  $\{\beta_n\}$  satisfy the following condition:*

*(C1)  $\{\alpha_n\} \subset [0, 1]$ ,  $\{\beta_n\} \subset (0, 1]$  and  $\alpha_n \rightarrow 0$ ,  $\beta_n \rightarrow 0$  as  $n \rightarrow \infty$ .*

*Let LIM be a Banach limit. Then*

$$\text{LIM}_n \langle (A - I)\tilde{x}, \tilde{x} - x_n \rangle \leq 0,$$

where  $\tilde{x} = \lim_{t \rightarrow 0^+} x_t$  with  $x_t$  being defined by

$$x_t = P_C[(I - \theta_t A)Gx_t + \theta_t(t\gamma Vx_t + (I - t\mu F)Gx_t)], \quad (3.6)$$

where  $G : C \rightarrow C$  is defined by  $Gx = P_C(I - \nu_1 F_1)P_C(I - \nu_2 F_2)x$  for  $0 < \nu_j \leq 2\zeta_j, j = 1, 2$ .

*Proof.* First, note that from the condition (C1), without loss of generality, we may assume that  $0 < \beta_n \leq \|A\|^{-1}$  for all  $n \geq 0$ .

Let  $\{x_t\}$  be the net generated by (3.6). Since  $G$  is a nonexpansive self-mapping on  $C$ , by Theorem 3.1 with  $G_t = G$  and Proposition 2.2, there exists  $\lim_{t \rightarrow 0} x_t \in \text{Fix}(G) = \Xi$ . Denote it by  $\tilde{x}$ . Moreover,  $\tilde{x}$  is the unique solution of the VIP (3.2). From Proposition 3.1 (i) with  $G_t = G$ , we know that  $\{x_t\}$  is bounded and so are the nets  $\{Vx_t\}$  and  $\{FGx_t\}$ .

First of all, let us show that  $\{x_n\}$  is bounded. To this end, take  $p \in \text{Fix}(G) = \text{Fix}(G_n)$ , then we get

$$\begin{aligned} \|y_n - p\| &= \|\alpha_n \gamma Vx_n + (I - \alpha_n \mu F)G_n x_n - p\| \\ &= \|\alpha_n (\gamma Vx_n - \mu Fp) + (I - \alpha_n \mu F)G_n x_n - (I - \alpha_n \mu F)G_n p\| \\ &\leq (1 - \alpha_n (\tau - \gamma l))\|x_n - p\| + \alpha_n \|(\gamma V - \mu F)p\|, \end{aligned}$$

and hence we obtain

$$\|x_n - p\| \leq \max\{\|x_0 - p\|, \frac{\|(\gamma V - \mu F)p\| + \|I - A\|\|p\|}{\bar{\gamma} - 1}\}, \quad \forall n \geq 0.$$

This implies that  $\{x_n\}$  is bounded and so are  $\{Gx_n\}, \{G_n x_n\}, \{FG_n x_n\}, \{Vx_n\}$  and  $\{y_n\}$ . Thus, utilizing the control condition (C1), we get

$$\begin{aligned} \|x_{n+1} - G_n x_n\| &= \|P_C[(I - \beta_n A)G_n x_n + \beta_n y_n] - G_n x_n\| \\ &\leq \|(I - \beta_n A)G_n x_n + \beta_n y_n - G_n x_n\| \\ &= \beta_n \|y_n - AG_n x_n\| \rightarrow 0 \quad \text{as } n \rightarrow \infty, \end{aligned}$$

and

$$\begin{aligned} \|Gx_t - x_{n+1}\| &\leq \|Gx_t - Gx_n\| + \|Gx_n - G_n x_n\| + \|G_n x_n - x_{n+1}\| \\ &\leq \|x_t - x_n\| + \|G_n x_n - x_{n+1}\| \\ &\quad + \|P_C(I - \nu_1 F_1)P_C(I - \nu_2 F_2)x_n - P_C(I - \nu_{1,n} F_1)P_C(I - \nu_{2,n} F_2)x_n\| \\ &\leq \|x_t - x_n\| + \|G_n x_n - x_{n+1}\| \\ &\quad + \|P_C(I - \nu_1 F_1)P_C(I - \nu_2 F_2)x_n - P_C(I - \nu_1 F_1)P_C(I - \nu_{2,n} F_2)x_n\| \\ &\quad + \|P_C(I - \nu_1 F_1)P_C(I - \nu_{2,n} F_2)x_n - P_C(I - \nu_{1,n} F_1)P_C(I - \nu_{2,n} F_2)x_n\| \\ &\leq \|x_t - x_n\| + \|G_n x_n - x_{n+1}\| + \|(I - \nu_2 F_2)x_n - (I - \nu_{2,n} F_2)x_n\| \\ &\quad + \|(I - \nu_1 F_1)P_C(I - \nu_{2,n} F_2)x_n - (I - \nu_{1,n} F_1)P_C(I - \nu_{2,n} F_2)x_n\| \\ &\leq \|x_t - x_n\| + \|x_{n+1} - G_n x_n\| \\ &\quad + \|\nu_{2,n} - \nu_2\| \|F_2 x_n\| + |\nu_{1,n} - \nu_1| \|F_1 P_C(I - \nu_{2,n} F_2)x_n\| \\ &= \|x_t - x_n\| + \epsilon_n, \end{aligned} \quad (3.7)$$



where  $\epsilon_n = \|x_{n+1} - G_n x_n\| + \|\nu_{2,n} - \nu_2\| \|F_2 x_n\| + |\nu_{1,n} - \nu_1| \|F_1 P_C(I - \nu_{2,n} F_2)x_n\| \rightarrow 0$  as  $n \rightarrow \infty$ . Also observing that  $A$  is strongly positive, we have

$$\langle Ax_t - Ax_n, x_t - x_n \rangle = \langle A(x_t - x_n), x_t - x_n \rangle \geq \bar{\gamma} \|x_t - x_n\|^2. \tag{3.8}$$

For simplicity, we write  $w_t = (I - \theta_t A)Gx_t + \theta_t(t\gamma Vx_t + (I - t\mu F)Gx_t)$ . Then we obtain that  $x_t = P_C w_t$  and

$$\begin{aligned} x_t - x_{n+1} &= x_t - w_t + (I - \theta_t A)Gx_t + \theta_t(t\gamma Vx_t + (I - t\mu F)Gx_t) - x_{n+1} \\ &= (I - \theta_t A)Gx_t - (I - \theta_t A)x_{n+1} + \theta_t(t\gamma Vx_t \\ &\quad + (I - t\mu F)Gx_t - Ax_{n+1}) + x_t - w_t. \end{aligned}$$

Applying Lemma 2.1, we have

$$\begin{aligned} \|x_t - x_{n+1}\|^2 &\leq \|(I - \theta_t A)Gx_t - (I - \theta_t A)x_{n+1}\|^2 \\ &\quad + 2\theta_t \langle Gx_t - t(\mu F Gx_t - \gamma Vx_t) - Ax_{n+1}, x_t - x_{n+1} \rangle + 2\langle x_t - w_t, x_t - x_{n+1} \rangle \\ &\leq \|(I - \theta_t A)Gx_t - (I - \theta_t A)x_{n+1}\|^2 + 2\theta_t \langle Gx_t - t(\mu F Gx_t - \gamma Vx_t) - Ax_{n+1}, x_t - x_{n+1} \rangle \\ &\quad \leq (1 - \theta_t \bar{\gamma})^2 \|Gx_t - x_{n+1}\|^2 + 2\theta_t \langle Gx_t - x_t, x_t - x_{n+1} \rangle \\ &\quad \quad - 2\theta_t t \langle \mu F Gx_t - \gamma Vx_t, x_t - x_{n+1} \rangle + 2\theta_t \langle x_t - Ax_{n+1}, x_t - x_{n+1} \rangle. \end{aligned} \tag{3.9}$$

Using (3.7) and (3.8) in (3.9), we obtain

$$\begin{aligned} &\|x_t - x_{n+1}\|^2 \tag{3.10} \\ &\leq (1 - \theta_t \bar{\gamma})^2 \|Gx_t - x_{n+1}\|^2 + 2\theta_t \langle Gx_t - x_t, x_t - x_{n+1} \rangle \\ &\quad + 2\theta_t t \langle \gamma Vx_t - \mu F Gx_t, x_t - x_{n+1} \rangle + 2\theta_t \langle x_t - Ax_{n+1}, x_t - x_{n+1} \rangle \\ &\leq (1 - \theta_t \bar{\gamma})^2 (\|x_t - x_n\| + \epsilon_n)^2 + 2\theta_t \|Gx_t - x_t\| \|x_t - x_{n+1}\| \\ &\quad + 2\theta_t t \|\gamma Vx_t - \mu F Gx_t\| \|x_t - x_{n+1}\| + 2\theta_t \langle x_t - Ax_{n+1}, x_t - x_{n+1} \rangle \\ &= (\theta_t^2 \bar{\gamma} - 2\theta_t) \bar{\gamma} \|x_t - x_n\|^2 + \|x_t - x_n\|^2 + (1 - \theta_t \bar{\gamma})^2 (2\|x_t - x_n\| \epsilon_n + \epsilon_n^2) \\ &\quad + 2\theta_t \|Gx_t - x_t\| \|x_t - x_{n+1}\| + 2\theta_t t \|\gamma Vx_t - \mu F Gx_t\| \|x_t - x_{n+1}\| \\ &\quad + 2\theta_t \langle x_t - Ax_{n+1}, x_t - x_{n+1} \rangle \\ &\leq (\theta_t^2 \bar{\gamma} - 2\theta_t) \langle Ax_t - Ax_n, x_t - x_n \rangle + \|x_t - x_n\|^2 + (1 - \theta_t \bar{\gamma})^2 (2\|x_t - x_n\| \epsilon_n + \epsilon_n^2) \\ &\quad + 2\theta_t \|Gx_t - x_t\| \|x_t - x_{n+1}\| + 2\theta_t t \|\gamma Vx_t - \mu F Gx_t\| \|x_t - x_{n+1}\| \\ &\quad + 2\theta_t \langle x_t - Ax_{n+1}, x_t - x_{n+1} \rangle \\ &= \theta_t^2 \bar{\gamma} \langle Ax_t - Ax_n, x_t - x_n \rangle + \|x_t - x_n\|^2 + (1 - \theta_t \bar{\gamma})^2 (2\|x_t - x_n\| \epsilon_n + \epsilon_n^2) \\ &\quad + 2\theta_t \|Gx_t - x_t\| \|x_t - x_{n+1}\| + 2\theta_t t \|\gamma Vx_t - \mu F Gx_t\| \|x_t - x_{n+1}\| \\ &\quad + 2\theta_t [\langle x_t - Ax_{n+1}, x_t - x_{n+1} \rangle - \langle Ax_t - Ax_n, x_t - x_n \rangle] \\ &= \theta_t^2 \bar{\gamma} \langle A(x_t - x_n), x_t - x_n \rangle + \|x_t - x_n\|^2 + (1 - \theta_t \bar{\gamma})^2 (2\|x_t - x_n\| \epsilon_n + \epsilon_n^2) \\ &\quad + 2\theta_t \|Gx_t - x_t\| \|x_t - x_{n+1}\| + 2\theta_t t \|\gamma Vx_t - \mu F Gx_t\| \|x_t - x_{n+1}\| \\ &\quad + 2\theta_t [\langle (I - A)x_t, x_t - x_{n+1} \rangle + \langle A(x_t - x_{n+1}), x_t - x_{n+1} \rangle - \langle A(x_t - x_n), x_t - x_n \rangle]. \end{aligned}$$

Applying the Banach limit LIM to (3.10), from  $\epsilon_n \rightarrow 0$  we have

$$\begin{aligned} & \text{LIM}_n \|x_t - x_{n+1}\|^2 \tag{3.11} \\ & \leq \theta_t^2 \gamma \text{LIM}_n \langle A(x_t - x_n), x_t - x_n \rangle + \text{LIM}_n \|x_t - x_n\|^2 \\ & \quad + 2\theta_t \|Gx_t - x_t\| \text{LIM}_n \|x_t - x_{n+1}\| + 2\theta_t t \|\gamma Vx_t - \mu FGx_t\| \text{LIM}_n \|x_t - x_{n+1}\| \\ & \quad + 2\theta_t [\text{LIM}_n \langle (I - A)x_t, x_t - x_{n+1} \rangle + \text{LIM}_n \langle A(x_t - x_{n+1}), x_t - x_{n+1} \rangle \\ & \quad - \text{LIM}_n \langle A(x_t - x_n), x_t - x_n \rangle]. \end{aligned}$$

Using the property  $\text{LIM}_n a_n = \text{LIM}_n a_{n+1}$  of the Banach limit in (3.11), we obtain

$$\begin{aligned} & \text{LIM}_n \langle (A - I)x_t, x_t - x_n \rangle \tag{3.12} \\ & = \text{LIM}_n \langle (A - I)x_t, x_t - x_{n+1} \rangle \\ & \leq \frac{\theta_t \bar{\gamma}}{2} \text{LIM}_n \langle A(x_t - x_n), x_t - x_n \rangle + \frac{1}{2\theta_t} [\text{LIM}_n \|x_t - x_n\|^2 - \text{LIM}_n \|x_t - x_{n+1}\|^2] \\ & \quad + \|Gx_t - x_t\| \text{LIM}_n \|x_t - x_n\| + t \|\gamma Vx_t - \mu FGx_t\| \text{LIM}_n \|x_t - x_n\| \\ & \quad + \text{LIM}_n \langle A(x_t - x_{n+1}), x_t - x_{n+1} \rangle - \text{LIM}_n \langle A(x_t - x_n), x_t - x_n \rangle \\ & \leq \frac{\theta_t \bar{\gamma}}{2} \text{LIM}_n \langle A(x_t - x_n), x_t - x_n \rangle + \|Gx_t - x_t\| \text{LIM}_n \|x_t - x_n\| \\ & \quad + t \|\gamma Vx_t - \mu FGx_t\| \text{LIM}_n \|x_t - x_n\|. \end{aligned}$$

Since as  $t \rightarrow 0$ ,

$$\theta_t \langle A(x_t - x_n), x_t - x_n \rangle \leq \theta_t \|A\| \|x_t - x_n\|^2 \leq \theta_t K \rightarrow 0, \tag{3.13}$$

where  $\|A\| \|x_t - x_n\|^2 \leq K$ ,

$$\|Gx_t - x_t\| \rightarrow 0 \quad \text{ans} \quad t \|\gamma Vx_t - \mu FGx_t\| \rightarrow 0 \quad \text{as } t \rightarrow 0, \tag{3.14}$$

we conclude from (3.12)-(3.14) that

$$\begin{aligned} & \text{LIM}_n \langle (A - I)\tilde{x}, \tilde{x} - x_n \rangle \\ & \leq \limsup_{t \rightarrow 0} \text{LIM}_n \langle (A - I)x_t, x_t - x_n \rangle \\ & \leq \limsup_{t \rightarrow 0} \frac{\theta_t \bar{\gamma}}{2} \text{LIM}_n \langle A(x_t - x_n), x_t - x_n \rangle + \limsup_{t \rightarrow 0} \|Gx_t - x_t\| \text{LIM}_n \|x_t - x_n\| \\ & \quad + \limsup_{t \rightarrow 0} t \|\gamma Vx_t - \mu FGx_t\| \text{LIM}_n \|x_t - x_n\| \\ & = 0. \end{aligned}$$

This completes the proof. □

Now, using Theorem 3.2, we establish the strong convergence of the sequence  $\{x_n\}$  generated by the general composite explicit scheme (3.3) to a fixed point  $\tilde{x}$  of  $G$  (i.e.,  $\tilde{x} \in \Xi$ ), which is also the unique solution of the VIP (3.2).

**Theorem 3.3.** *Let  $\{x_n\}$  be the sequence generated by the explicit scheme (3.3), where  $\{\alpha_n\}$  and  $\{\beta_n\}$  satisfy the following conditions:*

- (C1)  $\{\alpha_n\} \subset [0, 1]$ ,  $\{\beta_n\} \subset (0, 1]$  and  $\alpha_n \rightarrow 0$ ,  $\beta_n \rightarrow 0$  as  $n \rightarrow \infty$ ;
- (C2)  $\sum_{n=0}^{\infty} \beta_n = \infty$ .

*If  $\{x_n\}$  is weakly asymptotically regular (i.e.,  $x_{n+1} - x_n \rightarrow 0$ ), then  $x_n$  converges strongly to a fixed point  $\tilde{x}$  of  $G$  (i.e.,  $\tilde{x} \in \Xi$ ), which is the unique solution of the VIP (3.2).*

*Proof.* First, note that from the condition (C1), without loss of generality, we may assume that  $\alpha_n\tau < 1$  and  $\frac{2\beta_n(\bar{\gamma}-1)}{1-\beta_n} < 1$  for all  $n \geq 0$ .

Let  $x_t$  be defined by (3.6), that is,

$$x_t = P_C[(I - \theta_t A)Gx_t + \theta_t(Gx_t - t(\mu F Gx_t - \gamma Vx_t))],$$

for  $t \in (0, \min\{1, \frac{2-\bar{\gamma}}{\bar{\gamma}-\gamma_l}\})$ , where  $G = P_C(I - \nu_1 F_1)P_C(I - \nu_2 F_2)$  for  $0 < \nu_j \leq 2\zeta_j$ , and  $\lim_{t \rightarrow 0} x_t := \tilde{x} \in \text{Fix}(G) = \Xi$ . Then  $\tilde{x}$  is the unique solution of the VIP (3.2).

We divide the rest of the proof into several steps.

**Step 1.** We see that

$$\|x_n - p\| \leq \max\{\|x_0 - p\|, \frac{\|(\gamma V - \mu F)p\| + \|I - A\|\|p\|}{\bar{\gamma} - 1}\}, \quad \forall n \geq 0,$$

for all  $p \in \Xi$  as in the proof of Theorem 3.2. Hence  $\{x_n\}$  is bounded and so are  $\{Gx_n\}, \{G_n x_n\}, \{FG_n x_n\}, \{Vx_n\}$  and  $\{y_n\}$ .

**Step 2.** We show that  $\limsup_{n \rightarrow \infty} \langle (I - A)\tilde{x}, x_n - \tilde{x} \rangle \leq 0$ . To this end, put

$$a_n := \langle (A - I)\tilde{x}, \tilde{x} - x_n \rangle, \quad \forall n \geq 0.$$

Then, by Theorem 3.2 we get  $\text{LIM}_n a_n \leq 0$  for any Banach limit LIM. Since  $\{x_n\}$  is bounded, there exists a subsequence  $\{x_{n_j}\}$  of  $\{x_n\}$  such that

$$\limsup_{n \rightarrow \infty} (a_{n+1} - a_n) = \limsup_{j \rightarrow \infty} (a_{n_j+1} - a_{n_j})$$

and  $x_{n_j} \rightharpoonup u \in H$ . This implies that  $x_{n_j+1} \rightharpoonup u$  since  $\{x_n\}$  is weakly asymptotically regular. Therefore, we have

$$w - \lim_{j \rightarrow \infty} (\tilde{x} - x_{n_j+1}) = w - \lim_{j \rightarrow \infty} (\tilde{x} - x_{n_j}) = \tilde{x} - u,$$

and so

$$\limsup_{n \rightarrow \infty} (a_{n+1} - a_n) = \lim_{j \rightarrow \infty} \langle (A - I)\tilde{x}, (\tilde{x} - x_{n_j+1}) - (\tilde{x} - x_{n_j}) \rangle = 0.$$

Then, by [18, Proposition 2] we obtain  $\limsup_{n \rightarrow \infty} a_n \leq 0$ , that is,

$$\limsup_{n \rightarrow \infty} \langle (I - A)\tilde{x}, x_n - \tilde{x} \rangle = \limsup_{n \rightarrow \infty} \langle (A - I)\tilde{x}, \tilde{x} - x_n \rangle \leq 0.$$

**Step 3.** We show that  $\lim_{n \rightarrow \infty} \|x_n - \tilde{x}\| = 0$ . Indeed, for simplicity, we write  $w_n = (I - \beta_n A)G_n x_n + \beta_n y_n$  for all  $n \geq 0$ . Then  $x_{n+1} = P_C w_n$ . Utilizing (3.3) and  $G_n \tilde{x} = \tilde{x}$ , we have

$$y_n - \tilde{x} = (I - \alpha_n \mu F)G_n x_n - (I - \alpha_n \mu F)G_n \tilde{x} + \alpha_n(\gamma Vx_n - \mu F\tilde{x}),$$

and

$$x_{n+1} - \tilde{x} = x_{n+1} - w_n + (I - \beta_n A)(G_n x_n - G_n \tilde{x}) + \beta_n(y_n - \tilde{x}) + \beta_n(I - A)\tilde{x}.$$

Applying Lemma 2.1 and [23, Lemma 31], we obtain

$$\begin{aligned} \|y_n - \tilde{x}\|^2 &= \|(I - \alpha_n \mu F)G_n x_n - (I - \alpha_n \mu F)G_n \tilde{x} + \alpha_n(\gamma Vx_n - \mu F\tilde{x})\|^2 \\ &\leq \|(I - \alpha_n \mu F)G_n x_n - (I - \alpha_n \mu F)G_n \tilde{x}\|^2 + 2\alpha_n \langle \gamma Vx_n - \mu F\tilde{x}, y_n - \tilde{x} \rangle \\ &\leq (1 - \alpha_n \tau)^2 \|x_n - \tilde{x}\|^2 + 2\alpha_n \|\gamma Vx_n - \mu F\tilde{x}\| \|y_n - \tilde{x}\| \\ &\leq \|x_n - \tilde{x}\|^2 + 2\alpha_n \|\gamma Vx_n - \mu F\tilde{x}\| \|y_n - \tilde{x}\|, \end{aligned}$$

and hence

$$\begin{aligned}
 & \|x_{n+1} - \tilde{x}\|^2 \tag{3.15} \\
 &= \|(I - \beta_n A)(G_n x_n - G_n \tilde{x}) + \beta_n(y_n - \tilde{x}) + \beta_n(I - A)\tilde{x} + x_{n+1} - w_n\|^2 \\
 &\leq \|(I - \beta_n A)(G_n x_n - G_n \tilde{x})\|^2 + 2\beta_n \langle y_n - \tilde{x}, x_{n+1} - \tilde{x} \rangle + 2\beta_n \langle (I - A)\tilde{x}, x_{n+1} - \tilde{x} \rangle \\
 &\quad + 2\langle x_{n+1} - w_n, x_{n+1} - \tilde{x} \rangle \\
 &\leq \|(I - \beta_n A)(G_n x_n - G_n \tilde{x})\|^2 + 2\beta_n \langle y_n - \tilde{x}, x_{n+1} - \tilde{x} \rangle + 2\beta_n \langle (I - A)\tilde{x}, x_{n+1} - \tilde{x} \rangle \\
 &\leq (1 - \beta_n \bar{\gamma})^2 \|x_n - \tilde{x}\|^2 + 2\beta_n \|y_n - \tilde{x}\| \|x_{n+1} - \tilde{x}\| + 2\beta_n \langle (I - A)\tilde{x}, x_{n+1} - \tilde{x} \rangle \\
 &\leq (1 - \beta_n \bar{\gamma})^2 \|x_n - \tilde{x}\|^2 + \beta_n (\|y_n - \tilde{x}\|^2 + \|x_{n+1} - \tilde{x}\|^2) + 2\beta_n \langle (I - A)\tilde{x}, x_{n+1} - \tilde{x} \rangle \\
 &\leq (1 - \beta_n \bar{\gamma})^2 \|x_n - \tilde{x}\|^2 + \beta_n [\|x_n - \tilde{x}\|^2 + 2\alpha_n \|\gamma V x_n - \mu F \tilde{x}\| \|y_n - \tilde{x}\|] \\
 &\quad + \beta_n \|x_{n+1} - \tilde{x}\|^2 + 2\beta_n \langle (I - A)\tilde{x}, x_{n+1} - \tilde{x} \rangle \\
 &= [(1 - \beta_n \bar{\gamma})^2 + \beta_n] \|x_n - \tilde{x}\|^2 + 2\alpha_n \beta_n \|\gamma V x_n - \mu F \tilde{x}\| \|y_n - \tilde{x}\| \\
 &\quad + \beta_n \|x_{n+1} - \tilde{x}\|^2 + 2\beta_n \langle (I - A)\tilde{x}, x_{n+1} - \tilde{x} \rangle.
 \end{aligned}$$

It then follows from (3.15) that

$$\begin{aligned}
 \|x_{n+1} - \tilde{x}\|^2 &\leq \frac{(1 - \beta_n \bar{\gamma})^2 + \beta_n}{1 - \beta_n} \|x_n - \tilde{x}\|^2 + \frac{\beta_n}{1 - \beta_n} [2\alpha_n \|\gamma V x_n - \mu F \tilde{x}\| \|y_n - \tilde{x}\| \\
 &\quad + 2\langle (I - A)\tilde{x}, x_{n+1} - \tilde{x} \rangle] \\
 &= (1 - \frac{2\beta_n(\bar{\gamma} - 1)}{1 - \beta_n}) \|x_n - \tilde{x}\|^2 \\
 &\quad + \frac{2\beta_n(\bar{\gamma} - 1)}{1 - \beta_n} \cdot \frac{1}{2(\bar{\gamma} - 1)} [2\alpha_n \|\gamma V x_n - \mu F \tilde{x}\| \|y_n - \tilde{x}\| \\
 &\quad + \beta_n \bar{\gamma}^2 \|x_n - \tilde{x}\|^2 + 2\langle (I - A)\tilde{x}, x_{n+1} - \tilde{x} \rangle] \\
 &= (1 - \omega_n) \|x_n - \tilde{x}\|^2 + \omega_n \delta_n,
 \end{aligned}$$

where  $\omega_n = \frac{2\beta_n(\bar{\gamma}-1)}{1-\beta_n}$  and

$$\delta_n = \frac{1}{2(\bar{\gamma} - 1)} [2\alpha_n \|\gamma V x_n - \mu F \tilde{x}\| \|y_n - \tilde{x}\| + \beta_n \bar{\gamma}^2 \|x_n - \tilde{x}\|^2 + 2\langle (I - A)\tilde{x}, x_{n+1} - \tilde{x} \rangle].$$

It can be readily seen from Step 2 and conditions (C1) and (C2) that  $\omega_n \rightarrow 0$ ,  $\sum_{n=0}^\infty \omega_n = \infty$  and  $\limsup_{n \rightarrow \infty} \delta_n \leq 0$ . By [22, Lemma 2.1] with  $r_n = 0$ , we conclude that  $\lim_{n \rightarrow \infty} \|x_n - \tilde{x}\| = 0$ . This completes the proof.  $\square$

**Corollary 3.2.** *Let  $\{x_n\}$  be the sequence generated by the explicit scheme (3.3). Assume that the sequences  $\{\alpha_n\}$  and  $\{\beta_n\}$  satisfy the conditions (C1) and (C2) in Theorem 3.3. If  $\{x_n\}$  is asymptotically regular, then  $\{x_n\}$  converges strongly to a fixed point  $\tilde{x}$  of  $G$  which is the unique solution of the VIP (3.2).*

Putting  $\mu = 2$ ,  $F = \frac{1}{2}I$  and  $\gamma = 1$  in Theorem 3.3, we obtain the following.

**Corollary 3.3.** *Let  $\{x_n\}$  be generated by the following iterative scheme:*

$$\begin{cases} y_n = \alpha_n V x_n + (1 - \alpha_n) G_n x_n, \\ x_{n+1} = P_C[(I - \beta_n A)G_n x_n + \beta_n y_n], \quad \forall n \geq 0. \end{cases}$$

Assume that the sequences  $\{\alpha_n\}$  and  $\{\beta_n\}$  satisfy the conditions (C1) and (C2) in Theorem 3.3. If  $\{x_n\}$  is weakly asymptotically regular, then  $\{x_n\}$  converges strongly to a fixed point  $\tilde{x}$  of  $G$  which is the unique solution of the VIP (3.2).

**Remark 3.1.** If  $\{\alpha_n\}, \{\beta_n\}$  in Corollary 3.2 and  $\{\nu_{j,n}\}_{j=1}^2$  in  $G_n$  satisfy conditions (C2) and

(C3)  $\sum_{n=0}^{\infty} |\alpha_{n+1} - \alpha_n| < \infty$  and  $\sum_{n=0}^{\infty} |\beta_{n+1} - \beta_n| < \infty$ ; or

(C4)  $\sum_{n=0}^{\infty} |\alpha_{n+1} - \alpha_n| < \infty$  and  $\lim_{n \rightarrow \infty} \frac{\beta_n}{\beta_{n+1}} = 1$  or, equivalently,  $\lim_{n \rightarrow \infty} \frac{\alpha_n - \alpha_{n+1}}{\alpha_{n+1}} = 0$  and  $\lim_{n \rightarrow \infty} \frac{\beta_n - \beta_{n+1}}{\beta_{n+1}} = 0$ ; or,

(C5)  $\sum_{n=0}^{\infty} |\alpha_{n+1} - \alpha_n| < \infty$  and  $|\beta_{n+1} - \beta_n| \leq o(\beta_{n+1}) + \sigma_n$ ,  $\sum_{n=0}^{\infty} \sigma_n < \infty$  (the perturbed control condition);

(C6)  $\sum_{n=0}^{\infty} |\nu_{j,n+1} - \nu_{j,n}| < \infty$  for  $j = 1, 2$ ,

then the sequence  $\{x_n\}$  generated by (3.3) is asymptotically regular.

In view of the above remark, we have the following corollary.

**Corollary 3.4.** Let  $\{x_n\}$  be the sequence generated by the explicit scheme (3.3), where the sequences  $\{\alpha_n\}, \{\beta_n\}$  and  $\{\nu_{j,n}\}_{j=1}^2$  satisfy the conditions (C1), (C2), (C5) and (C6) (or the conditions (C1), (C2), (C3) and (C6), or the conditions (C1), (C2), (C4) and (C6)). Then  $\{x_n\}$  converges strongly to a fixed point  $\tilde{x}$  of  $G$  (i.e.,  $\tilde{x} \in \Xi$ ), which is the unique solution of the VIP (3.2).

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