# THE SET OF SOLUTIONS TO A NONLINEAR INTEGRODIFFERENTIAL EQUATION IN N VARIABLES 

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#### Abstract

In this paper, we study the existence and the compactness of the set of solutions for a nonlinear integrodifferential equation in N variables. The main tools are the fixed point theorem of Krasnosel'skii with the definition of a suitable Banach space and a sufficient condition for relative compactness of subsets in this space. An illustrative example is given. Key Words and Phrases: Nonlinear integrodifferential equation, the fixed point theorem of Krasnosel'skii. 2010 Mathematics Subject Classification: 45G10, 47H10, 47N20, 65J15.


## 1. Introduction

In this paper, we consider the following nonlinear integrodifferential equation in N variables

$$
\begin{equation*}
u(x)=g(x)+\int_{B_{x}} H\left(x, y, u(y), D_{1} u(y)\right) d y+\int_{\Omega} K\left(x, y, u(y), D_{1} u(y)\right) d y \tag{1.1}
\end{equation*}
$$

where $x=\left(x_{1}, \ldots, x_{N}\right) \in \Omega=[0,1]^{N}$ and $g: \Omega \rightarrow \mathbb{R}, H: \Delta \times \mathbb{R}^{2} \rightarrow \mathbb{R}, K: \Omega \times \Omega \times \mathbb{R}^{2} \rightarrow$ $\mathbb{R}$ are given functions, with $\Delta=\left\{(x, y) \in \Omega \times \Omega: y \in B_{x}\right\}, B_{x}=\left[0, x_{1}\right] \times \ldots \times\left[0, x_{N}\right]$. Denote by $D_{1} u=\frac{\partial u}{\partial x_{1}}$, the partial derivative of a function $u(x)$ defined on $\Omega$, with respect to the first variable.

The problem of existence of solutions with certain properties for nonlinear integral and integrodifferential equations has attracted the interest of scientists not only because of their major role in the fields of functional analysis but also because of their important role in numerous applications, for example, mechanics, physics, population dynamics, economics and other fields of science, see Corduneanu [7], Deimling [8], E.

Zeidler [18]. In general, existence results of integral and integrodifferential equations in one variable or N variables, have been obtained via the fundamental methods in which the fixed point theorems are often applied, see [2] - [18] and the references given therein. It is also known that existence theory for nonlinear integral equations, strongly related with the evolution on fixed point theory, has been boosted ahead after the remarkable work of Krasnosel'skii which signaled a new era in the research of the subject, see [17] and the references given therein. Two main results of fixed point theory are Schauder's Theorem and Banach's Theorem (also called contraction mapping principle), Krasnosel'skii combined them into the following result.
Theorem 1.1. (see [4], [8]). Let $M$ be a nonempty bounded closed convex subset of a Banach space $(X,\|\cdot\|)$. Suppose that $U: M \rightarrow X$ is a contraction and $C: M \rightarrow X$ is a completely continuous operator such that $U(x)+C(y) \in M, \forall x, y \in M$. Then $U+C$ has a fixed point in $M$.

In [5], using a fixed point theorem of Krasnosel'skii, Avramescu and Vladimirescu have proved the existence of asymptotically stable solutions to the following integral equation

$$
\begin{equation*}
u(t)=q(t)+\int_{0}^{t} K(t, s, u(s)) d s+\int_{0}^{\infty} G(t, s, u(s)) d s, t \in \mathbb{R}_{+} \tag{1.2}
\end{equation*}
$$

where the real functions are supposed to be continuous satisfying suitable conditions.
In [14], based on the well known Banach fixed point theorem coupled with Bi elecki type norm and a certain integral inequality with explicit estimate, B. G. Pachpatte proved uniqueness and other properties of solutions of the following Fredholm type integrodifferential equation

$$
\begin{equation*}
x(t)=g(t)+\int_{a}^{b} f\left(t, s, x(s), x^{\prime}(s), \ldots, x^{(n-1)}(s)\right) d s, t \in[a, b] \tag{1.3}
\end{equation*}
$$

where $x, g, f$ are real valued functions and $n \geq 2$ is an integer. With the same methods, B. G. Pachpatte studied the existence, uniqueness and some basic properties of solutions of the Fredholm type integral equation in two variables, see [15],

$$
\begin{equation*}
u(x, y)=f(x, y)+\int_{0}^{a} \int_{0}^{b} g\left(x, y, s, t, u(s, t), D_{1} u(s, t), D_{2} u(s, t)\right) d t d s \tag{1.4}
\end{equation*}
$$

yet of certain Volterra integral and integrodifferential equations in two variables, see [16].

In [6], El-Borai et al. have proved the existence of a unique solution of a nonlinear integral equation of type Volterra-Hammerstein in n-dimensions of the form

$$
\begin{equation*}
\mu \phi(x, t)=f(x, t)+\lambda \int_{0}^{t} \int_{\Omega} F(t, \tau) K(x, y) \gamma(\tau, y, \phi(y, \tau)) d y d \tau \tag{1.5}
\end{equation*}
$$

where $x=\left(x_{1}, \ldots, x_{n}\right), y=\left(y_{1}, \ldots, y_{n}\right) ; \mu, \lambda$ are constants. After that, in [2], M. A. Abdou et al. investigated the following mixed nonlinear integral equation of the
second kind in n -dimensions

$$
\begin{align*}
\mu \phi(x, t) & =\lambda \int_{\Omega} k(x, y) \gamma(t, y, \phi(y, t)) d y+\lambda \int_{0}^{t} \int_{\Omega} G(t, \tau) k(x, y) \gamma(\tau, y, \phi(y, \tau)) d y d \tau \\
& +\lambda \int_{0}^{t} F(t, \tau) \phi(x, \tau) d \tau+f(x, t) \tag{1.6}
\end{align*}
$$

where $x=\left(x_{1}, \ldots, x_{n}\right), y=\left(y_{1}, \ldots, y_{n}\right)$. Also using the Banach fixed point theorem, the existence of a unique solution of these equations was proved.
M. A. Abdou et al. also considered the existence of integrable solution of nonlinear integral equation, of type Hammerstein-Volterra of the second kind, by using the technique of measure of weak noncompactness and Schauder fixed point theorem, see [1].

In [10], M. Lauran established sufficient conditions for the existence of solutions of the integral equation of Volterra type by using the concepts of nonexpansive operators, contraction principles and the Schaefer's fixed point theorem.

In [3], A. Aghajani et al. proved some results on the existence, uniqueness and estimation of the solutions of Fredholm type integro-differential equations in two variables, by using Perov's fixed point theorem.

Recently, in [11] - [13], using tools of functional analysis and a fixed point theorem of Krasnosel'skii type, solvability and asymptotically stable of nonlinear functional integral equations in one variable or two variables, or N variables have been investigated.

Motivated by the problems in the above mentioned works, in this paper, we consider (1.1). This paper consists of four sections. The main result is given in Section 3, where we state and prove Theorem 3.1 about the existence and the compactness of the solutions set for (1.1). The proof of this theorem requires a preliminary study of an appropriate Banach space $\left(X_{1},\|\cdot\|_{X_{1}}\right)$ defined below, and a sufficient condition for relative compactness of subsets of $X_{1}$ presented in Section 2. We note more that the Banach space $X_{1}$ with the property $C^{1}(\Omega ; \mathbb{R}) \subset X_{1} \subset C(\Omega ; \mathbb{R})$ has not been used before. Finally, in Section 4, we give an illustrative example.

## 2. Preliminaries

$$
\begin{gathered}
\text { Put } \Omega=[0,1]^{N} \text { and let } B_{x}=\left[0, x_{1}\right] \times \ldots \times\left[0, x_{N}\right], x=\left(x_{1}, \ldots, x_{N}\right) \in \mathbb{R}^{N}, \\
\Delta=\left\{(x, y) \in \Omega \times \Omega: y \in B_{x}\right\}
\end{gathered}
$$

We also denote by $x=\left(x_{1}, \ldots, x_{N}\right)=\left(x_{1}, x^{\prime}\right)$, with $x^{\prime}=\left(x_{2}, \ldots, x_{N}\right)$.
First, we construct an appropriate Banach space for (1.1) as follows.
By $X=C(\Omega ; \mathbb{R})$, we denote the space of all continuous functions from $\Omega$ into $\mathbb{R}$ equipped with the standard norm:

$$
\begin{equation*}
\|u\|_{X}=\sup _{x \in \Omega}|u(x)|, u \in X \tag{2.1}
\end{equation*}
$$

Put

$$
\begin{equation*}
X_{1}=\left\{u \in X=C(\Omega ; \mathbb{R}): D_{1} u \in X\right\} \tag{2.2}
\end{equation*}
$$

and

$$
\begin{equation*}
\|u\|_{X_{1}}=\|u\|_{X}+\left\|D_{1} u\right\|_{X}, \quad u \in X_{1} \tag{2.3}
\end{equation*}
$$

It is clear that $C^{1}(\Omega ; \mathbb{R}) \subset X_{1} \subset X$ and that they do not coincide. Indeed, there exists $u(x)=u\left(x_{1}, \ldots, x_{N}\right)=\left|x_{1}-\frac{1}{2}\right|+\left|x_{2}-\frac{1}{2}\right|+e^{x_{1}+\ldots+x_{N}} \in X$, but $u \notin X_{1}$. And there exists $v(x)=v\left(x_{1}, \ldots, x_{N}\right)=x_{1}^{2}\left|x_{2}-\frac{1}{2}\right|+e^{x_{1}+\ldots+x_{N}} \in X_{1}$, but $v \notin C^{1}(\Omega ; \mathbb{R})$.

We have the following lemma.
Lemma 2.1. $X_{1}$ is a Banach space with the norm defined by (2.3).
Proof. Let $\left\{u_{m}\right\} \subset X_{1}$ be a Cauchy sequence in $X_{1}$, then

$$
\begin{equation*}
\left\|u_{m}-u_{p}\right\|_{X_{1}}=\left\|u_{m}-u_{p}\right\|_{X}+\left\|D_{1} u_{m}-D_{1} u_{p}\right\|_{X} \rightarrow 0, \text { as } m, p \rightarrow \infty \tag{2.4}
\end{equation*}
$$

it implies that $\left\{u_{m}\right\}$ and $\left\{D_{1} u_{m}\right\}$ are also the Cauchy sequences in $X$. Because $X$ is a complete space, $\left\{u_{m}\right\}$ converges to $u$ and $\left\{D_{1} u_{m}\right\}$ converges to $v$ in $X$, i.e.,

$$
\left\|u_{m}-u\right\|_{X} \rightarrow 0,\left\|D_{1} u_{m}-v\right\|_{X} \rightarrow 0, \text { as } m \rightarrow \infty
$$

Clearly, it is enough to prove $\left\|u_{m}-u\right\|_{X_{1}} \rightarrow 0$, as $m \rightarrow \infty$, in the case $D_{1} u=v$. This is true, by the fact that

$$
\begin{equation*}
u_{m}\left(x_{1}, x^{\prime}\right)-u_{m}\left(0, x^{\prime}\right)=\int_{0}^{x_{1}} D_{1} u_{m}\left(s, x^{\prime}\right) d s, \forall x=\left(x_{1}, x^{\prime}\right) \in \Omega \tag{2.5}
\end{equation*}
$$

As $m \rightarrow \infty,\left\|u_{m}-u\right\|_{X} \rightarrow 0$ and $\left\|D_{1} u_{m}-v\right\|_{X} \rightarrow 0$, so

$$
\begin{equation*}
u_{m}\left(x_{1}, x^{\prime}\right)-u_{m}\left(0, x^{\prime}\right) \rightarrow u\left(x_{1}, x^{\prime}\right)-u\left(0, x^{\prime}\right), \quad \forall\left(x_{1}, x^{\prime}\right) \in \Omega \tag{2.6}
\end{equation*}
$$

and

$$
\begin{equation*}
\int_{0}^{x_{1}} D_{1} u_{m}\left(s, x^{\prime}\right) d s \rightarrow \int_{0}^{x_{1}} v\left(s, x^{\prime}\right) d s, \quad \forall\left(x_{1}, x^{\prime}\right) \in \Omega \tag{2.7}
\end{equation*}
$$

Note that (2.7) holds, since

$$
\begin{align*}
& \left|\int_{0}^{x_{1}} D_{1} u_{m}\left(s, x^{\prime}\right) d s-\int_{0}^{x_{1}} v\left(s, x^{\prime}\right) d s\right|  \tag{2.8}\\
& \leq \int_{0}^{x_{1}}\left|D_{1} u_{m}\left(s, x^{\prime}\right)-v\left(s, x^{\prime}\right)\right| d s \leq\left\|D_{1} u_{m}-v\right\|_{X} \rightarrow 0
\end{align*}
$$

It implies from (2.5)-(2.7) that

$$
\begin{equation*}
u\left(x_{1}, x^{\prime}\right)-u\left(0, x^{\prime}\right)=\int_{0}^{x_{1}} v\left(s, x^{\prime}\right) d s, \forall\left(x_{1}, x^{\prime}\right) \in \Omega \tag{2.9}
\end{equation*}
$$

Therefore, $D_{1} u=v \in X$. Hence, $u \in X_{1}$ and $u_{m} \rightarrow u$ in $X_{1}$. Lemma 2.1 is complete.
Next, we have the following lemma establishing a necessary and sufficient condition for relative compactness of subsets in $X_{1}$.
Lemma 2.2. Let $F \subset X_{1}$. Then $F$ is relatively compact in $X_{1}$ if and only if the following conditions are satisfied

$$
\begin{align*}
& \text { (i) } \exists M>0:\|u\|_{X_{1}} \leq M, \forall u \in F \text {; } \\
& \text { (ii) } \begin{aligned}
\forall \varepsilon>0 & \exists \delta>0: \forall x, \bar{x} \in \Omega,|x-\bar{x}|<\delta \\
& \Longrightarrow \sup _{u \in F}\left(|u(x)-u(\bar{x})|+\left|D_{1} u(x)-D_{1} u(\bar{x})\right|\right)<\varepsilon
\end{aligned} \tag{2.10}
\end{align*}
$$

Proof. (a) Let $F$ be relatively compact in $X_{1}$. Then $F$ is bounded, (2.10)(i) follows. It remains to show that (2.10)(ii) holds.

For every $\varepsilon>0$, considering a collection of open balls in $X_{1}$, with center at $u \in F$ and radius $\frac{\varepsilon}{3}$, as follows

$$
B_{X_{1}}\left(u, \frac{\varepsilon}{3}\right)=\left\{\bar{u} \in X_{1}:\|u-\bar{u}\|_{X_{1}}<\frac{\varepsilon}{3}\right\}, u \in F .
$$

It is not difficult to verify that $\bar{F} \subset \bigcup_{u \in F} B_{X_{1}}\left(u, \frac{\varepsilon}{3}\right)$, where $\bar{F}$ is the closure of $F$.
Since $\bar{F}$ compact in $X_{1}$, the open cover $\bigcup_{u \in F} B_{X_{1}}\left(u, \frac{\varepsilon}{3}\right)$ of $\bar{F}$ contains a finite subcover, it means that there are $u_{1}, u_{2}, \ldots, u_{s} \in F$ such that

$$
\bar{F} \subset \bigcup_{i=1}^{s} B_{X_{1}}\left(u_{i}, \frac{\varepsilon}{3}\right)
$$

The functions $u_{i}, D_{1} u_{i}, i=1, \ldots, s$, are uniformly continuous on $\Omega$, so there exists $\delta>0$ such that

$$
\forall x, \bar{x} \in \Omega,|x-\bar{x}|<\delta \Longrightarrow\left|u_{i}(x)-u_{i}(\bar{x})\right|+\left|D_{1} u_{i}(x)-D_{1} u_{i}(\bar{x})\right|<\frac{\varepsilon}{3}, \forall i=1, \ldots, s
$$

For all $u \in F$, note that $u \in B_{X_{1}}\left(u_{i}, \frac{\varepsilon}{3}\right)$ for some $i=1, \ldots, s$. Thus, for all $x, \bar{x} \in \Omega$, if $|x-\bar{x}|<\delta$ then we get

$$
\begin{aligned}
|u(x)-u(\bar{x})| & +\left|D_{1} u(x)-D_{1} u(\bar{x})\right| \\
& \leq\left|u(x)-u_{i}(x)\right|+\left|u_{i}(x)-u_{i}(\bar{x})\right|+\left|u_{i}(\bar{x})-u(\bar{x})\right| \\
& +\left|D_{1} u(x)-D_{1} u_{i}(x)\right|+\left|D_{1} u_{i}(x)-D_{1} u_{i}(\bar{x})\right|+\left|D_{1} u_{i}(\bar{x})-D_{1} u(\bar{x})\right| \\
& =\left|u(x)-u_{i}(x)\right|+\left|D_{1} u(x)-D_{1} u_{i}(x)\right|+\left|u_{i}(x)-u_{i}(\bar{x})\right| \\
& +\left|D_{1} u_{i}(x)-D_{1} u_{i}(\bar{x})\right|+\left|u_{i}(\bar{x})-u(\bar{x})\right|+\left|D_{1} u_{i}(\bar{x})-D_{1} u(\bar{x})\right| \\
& \leq 2\left\|u-u_{i}\right\|_{X_{1}}+\left|u_{i}(x)-u_{i}(\bar{x})\right|+\left|D_{1} u_{i}(x)-D_{1} u_{i}(\bar{x})\right| \\
& <\frac{2 \varepsilon}{3}+\frac{\varepsilon}{3}=\varepsilon .
\end{aligned}
$$

This implies that (2.10)(ii) holds.
(b) Conversely, let (2.10) hold.

In order to prove that $F$ is relatively compact in $X_{1}$, let $\left\{u_{m}\right\}$ be a sequence in $F$, we have to show that there exists a convergent subsequence of $\left\{u_{m}\right\}$.

By (2.10), $F_{1}=\left\{u_{m}: m \in \mathbb{N}\right\}$ and $F_{2}=\left\{D_{1} u_{m}: m \in \mathbb{N}\right\}$ are uniformly bounded and equicontinuous in $X$. Hence an application of the Ascoli-Arzela theorem to $F_{1}$ implies that it is relatively compact in $X$, so there exists a subsequence $\left\{u_{m_{k}}\right\}$ of $\left\{u_{m}\right\}$ and $u \in X$ such that

$$
\left\|u_{m_{k}}-u\right\|_{X} \rightarrow 0, \text { as } k \rightarrow \infty
$$

Remark that $\left\{D_{1} u_{m_{k}}: k \in \mathbb{N}\right\} \subset F_{2}$ is also uniformly bounded and equicontinuous in $X$, so it is also relatively compact in $X$. We deduce the existence of a subsequence of $\left\{D_{1} u_{m_{k}}\right\}$, denoted by the same symbol, and $v \in X$, such that

$$
\left\|D_{1} u_{m_{k}}-v\right\|_{X} \rightarrow 0, \text { as } k \rightarrow \infty
$$

By the fact that

$$
u_{m_{k}}\left(x_{1}, x^{\prime}\right)-u_{m_{k}}\left(0, x^{\prime}\right)=\int_{0}^{x_{1}} D_{1} u_{m_{k}}\left(s, x^{\prime}\right) d s, \forall\left(x_{1}, x^{\prime}\right) \in \Omega
$$

furthermore by $\left\|u_{m_{k}}-u\right\|_{X} \rightarrow 0$ and $\left\|D_{1} u_{m_{k}}-v\right\|_{X} \rightarrow 0$, we obtain

$$
u\left(x_{1}, x^{\prime}\right)-u\left(0, x^{\prime}\right)=\int_{0}^{x_{1}} v\left(s, x^{\prime}\right) d s, \forall\left(x_{1}, x^{\prime}\right) \in \Omega
$$

As $v \in X$, we see that the right hand side is continuously differentiable with respect to $x_{1}$ and this leads to $D_{1} u=v \in X$. Therefore $u \in X_{1}$ and $u_{m_{k}} \rightarrow u$ in $X_{1}$. Lemma 2.2 is proved.

## 3. The existence and the compactness of solutions set

In order to obtain the main result in section, we make the following assumptions (A1) $g \in X_{1}$;
(A2) $H \in C\left(\Delta \times \mathbb{R}^{2} ; \mathbb{R}\right), \frac{\partial H}{\partial x_{1}} \in C\left(\Delta \times \mathbb{R}^{2} ; \mathbb{R}\right)$, such that
There exist nonegative functions $h_{0}, h_{1}: \Delta \rightarrow \mathbb{R}$ with the following properties
(i) $|H(x, y, u, v)-H(x, y, \bar{u}, \bar{v})| \leq h_{0}(x, y)(|u-\bar{u}|+|v-\bar{v}|)$

$$
\forall(x, y) \in \Delta, \forall u, v, \bar{u}, \bar{v} \in \mathbb{R}
$$

(ii) $\left|\frac{\partial H}{\partial x_{1}}(x, y, u, v)-\frac{\partial H}{\partial x_{1}}(x, y, \bar{u}, \bar{v})\right| \leq h_{1}(x, y)(|u-\bar{u}|+|v-\bar{v}|)$

$$
\forall(x, y) \in \Delta, \forall u, v, \bar{u}, \bar{v} \in \mathbb{R}
$$

(A3) $K \in C\left(\Omega \times \Omega \times \mathbb{R}^{2} ; \mathbb{R}\right)$ such that $\frac{\partial K}{\partial x_{1}} \in C\left(\Omega \times \Omega \times \mathbb{R}^{2} ; \mathbb{R}\right)$ and there exist nonegative functions $k_{0}, k_{1}: \Omega \times \Omega \rightarrow \mathbb{R}$ with the following properties
(i) $|K(x, y, u, v)| \leq k_{0}(x, y)(1+|u|+|v|), \forall(x, y) \in \Omega \times \Omega, \forall u, v \in \mathbb{R}$,
(ii) $\left|\frac{\partial K}{\partial x_{1}}(x, y, u, v)\right| \leq k_{1}(x, y)(1+|u|+|v|), \forall(x, y) \in \Omega \times \Omega, \forall u, v \in \mathbb{R}$.
(A4) $\bar{\beta}_{1}+\bar{\beta}_{2}<1$, where

$$
\begin{aligned}
& \bar{\beta}_{1}=\sup _{x \in \Omega}\left[\int_{0}^{x_{2}} \cdots \int_{0}^{x_{N}} h_{0}\left(x, x_{1}, y^{\prime}\right) d y^{\prime}+\int_{B_{x}} h_{1}(x, y) d y\right]+\sup _{x \in \Omega} \int_{B_{x}} h_{0}(x, y) d y \\
& \bar{\beta}_{2}=\sup _{x \in \Omega} \int_{\Omega} k_{0}(x, y) d y+\sup _{x \in \Omega} \int_{\Omega} k_{1}(x, y) d y
\end{aligned}
$$

Theorem 3.1. Let the functions $g, H, K$ in (1.1) satisfy the assumptions (A1)-(A4). Then the equation (1.1) has a solution in $X_{1}$. Furthermore, the set of solutions is compact in $X_{1}$.
Proof. We rewrite (1.1) as follows

$$
\begin{equation*}
u(x)=(A u)(x), x \in \Omega \tag{3.1}
\end{equation*}
$$

where

$$
\begin{align*}
& (A u)(x)=(U u)(x)+(C u)(x) \\
& (U u)(x)=g(x)+\int_{B_{x}} H\left(x, y, u(y), D_{1} u(y)\right) d y  \tag{3.2}\\
& (C u)(x)=\int_{\Omega} K\left(x, y, u(y), D_{1} u(y)\right) d y \\
& x \in \Omega, u \in X_{1}
\end{align*}
$$

A simple verification shows that $U u, C u \in X_{1}, \forall u \in X_{1}$.

For $M>0$, we consider a closed ball in $X_{1}$ as follows

$$
\begin{equation*}
B_{M}=\left\{u \in X_{1}:\|u\|_{X_{1}} \leq M\right\} \tag{3.3}
\end{equation*}
$$

We will show that there exists $M>0$ such that
(i) $U u+C v \in B_{M}$, for every $u, v \in B_{M}$,
and the operators $U, C$ satisfy the conditions (ii)-(iv) below.
(ii) $U: B_{M} \rightarrow X_{1}$ is a contraction map,
(iii) $C: B_{M} \rightarrow X_{1}$ is continuous,
(iv) $F=C\left(B_{M}\right)$ is relatively compact in $X_{1}$.
$\operatorname{Proof}$ (i). Let $M>0$. For every $u \in B_{M}$, for all $x \in \Omega$, we have

$$
\begin{align*}
& |(U u)(x)| \leq\|g\|_{X}+\int_{B_{x}}\left|H\left(x, y, u(y), D_{1} u(y)\right)\right| d y \\
\leq & \|g\|_{X}+\int_{B_{x}}\left|H\left(x, y, u(y), D_{1} u(y)\right)-H(x, y, 0,0)\right| d y+\int_{B_{x}}|H(x, y, 0,0)| d y \\
\leq & \|g\|_{X}+\int_{B_{x}} h_{0}(x, y)\left(|u(y)|+\left|D_{1} u(y)\right|\right) d y+\int_{B_{x}}|H(x, y, 0,0)| d y \\
\leq & \|g\|_{X}+\|u\|_{X_{1}} \int_{B_{x}} h_{0}(x, y) d y+\int_{B_{x}}|H(x, y, 0,0)| d y \\
\leq & \|g\|_{X}+M \sup _{x \in \Omega} \int_{B_{x}} h_{0}(x, y) d y+\sup _{x \in \Omega} \int_{B_{x}}|H(x, y, 0,0)| d y \tag{3.4}
\end{align*}
$$

so

$$
\begin{equation*}
\|U u\|_{X} \leq\|g\|_{X}+M \sup _{x \in \Omega} \int_{B_{x}} h_{0}(x, y) d y+\sup _{x \in \Omega} \int_{B_{x}}|H(x, y, 0,0)| d y \tag{3.5}
\end{equation*}
$$

On the other hand, for all $x=\left(x_{1}, x^{\prime}\right) \in \Omega$,

$$
\begin{equation*}
(U u)(x)=g(x)+\int_{0}^{x_{1}}\left[\int_{0}^{x_{2}} \cdots \int_{0}^{x_{N}} H\left(x, y_{1}, y^{\prime}, u\left(y_{1}, y^{\prime}\right), D_{1} u\left(y_{1}, y^{\prime}\right)\right) d y^{\prime}\right] d y_{1} \tag{3.6}
\end{equation*}
$$

Therefore

$$
\begin{align*}
& D_{1}(U u)(x)=D_{1} g(x)+\int_{0}^{x_{2}} \ldots \int_{0}^{x_{N}} H\left(x, x_{1}, y^{\prime}, u\left(x_{1}, y^{\prime}\right), D_{1} u\left(x_{1}, y^{\prime}\right)\right) d y^{\prime} \\
+ & \int_{B_{x}} \frac{\partial H}{\partial x_{1}}\left(x, y, u(y), D_{1} u(y)\right) d y \\
= & D_{1} g(x)+\int_{0}^{x_{2}} \ldots \int_{0}^{x_{N}}\left[H\left(x, x_{1}, y^{\prime}, u\left(x_{1}, y^{\prime}\right), D_{1} u\left(x_{1}, y^{\prime}\right)\right)-H\left(x, x_{1}, y^{\prime}, 0,0\right)\right] d y^{\prime} \\
+ & \int_{0}^{x_{2}} \ldots \int_{0}^{x_{N}} H\left(x, x_{1}, y^{\prime}, 0,0\right) d y^{\prime}+\int_{B_{x}}\left[\frac{\partial H}{\partial x_{1}}\left(x, y, u(y), D_{1} u(y)\right)-\frac{\partial H}{\partial x_{1}}(x, y, 0,0)\right] d y \\
+ & \int_{B_{x}} \frac{\partial H}{\partial x_{1}}(x, y, 0,0) d y, \text { for all } x=\left(x_{1}, x^{\prime}\right) \in \Omega \tag{3.7}
\end{align*}
$$

It implies that

$$
\left|D_{1}(A u)(x)\right| \leq\left\|D_{1} g\right\|_{X}
$$

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$$
\begin{align*}
& +\int_{0}^{x_{2}} \cdots \int_{0}^{x_{N}}\left|H\left(x, x_{1}, y^{\prime}, u\left(x_{1}, y^{\prime}\right), D_{1} u\left(x_{1}, y^{\prime}\right)\right)-H\left(x, x_{1}, y^{\prime}, 0,0\right)\right| d y^{\prime} \\
& +\int_{0}^{x_{2}} \cdots \int_{0}^{x_{N}}\left|H\left(x, x_{1}, y^{\prime}, 0,0\right)\right| d y^{\prime} \\
& +\int_{B_{x}}\left|\frac{\partial H}{\partial x_{1}}\left(x, y, u(y), D_{1} u(y)\right)-\frac{\partial H}{\partial x_{1}}(x, y, 0,0)\right| d y+\int_{B_{x}}\left|\frac{\partial H}{\partial x_{1}}(x, y, 0,0)\right| d y \\
& \leq\left\|D_{1} g\right\|_{X}+\int_{0}^{x_{2}} \ldots \int_{0}^{x_{N}} h_{0}\left(x, x_{1}, y^{\prime}\right)\left(\left|u\left(x_{1}, y^{\prime}\right)\right|+\left|D_{1} u\left(x_{1}, y^{\prime}\right)\right|\right) d y^{\prime} \\
& +\int_{0}^{x_{2}} \ldots \int_{0}^{x_{N}}\left|H\left(x, x_{1}, y^{\prime}, 0,0\right)\right| d y^{\prime} \\
& +\int_{B_{x}} h_{1}(x, y)\left(|u(y)|+\left|D_{1} u(y)\right|\right) d y+\int_{B_{x}}\left|\frac{\partial H}{\partial x_{1}}(x, y, 0,0)\right| d y \\
& \leq\left\|D_{1} g\right\|_{X}+\|u\|_{X_{1}} \int_{0}^{x_{2}} \ldots \int_{0}^{x_{N}} h_{0}\left(x, x_{1}, y^{\prime}\right) d y^{\prime}+\int_{0}^{x_{2}} \ldots \int_{0}^{x_{N}}\left|H\left(x, x_{1}, y^{\prime}, 0,0\right)\right| d y^{\prime} \\
& +\|u\|_{X_{1}} \int_{B_{x}} h_{1}(x, y) d y+\int_{B_{x}}\left|\frac{\partial H}{\partial x_{1}}(x, y, 0,0)\right| d y \\
& \leq\left\|D_{1} g\right\|_{X}+M\left[\int_{0}^{x_{2}} \cdots \int_{0}^{x_{N}} h_{0}\left(x, x_{1}, y^{\prime}\right) d y^{\prime}+\int_{B_{x}} h_{1}(x, y) d y\right] \\
& +\int_{0}^{x_{2}} \ldots \int_{0}^{x_{N}}\left|H\left(x, x_{1}, y^{\prime}, 0,0\right)\right| d y^{\prime}+\int_{B_{x}}\left|\frac{\partial H}{\partial x_{1}}(x, y, 0,0)\right| d y \\
& \leq\left\|D_{1} g\right\|_{X}+M \sup _{x \in \Omega}\left[\int_{0}^{x_{2}} \ldots \int_{0}^{x_{N}} h_{0}\left(x, x_{1}, y^{\prime}\right) d y^{\prime}+\int_{B_{x}} h_{1}(x, y) d y\right] \\
& +\sup _{x \in \Omega}\left[\int_{0}^{x_{2}} \ldots \int_{0}^{x_{N}}\left|H\left(x, x_{1}, y^{\prime}, 0,0\right)\right| d y^{\prime}+\int_{B_{x}}\left|\frac{\partial H}{\partial x_{1}}(x, y, 0,0)\right| d y\right] . \tag{3.8}
\end{align*}
$$

This yields

$$
\begin{align*}
\left\|D_{1}(U u)\right\|_{X} \leq & \left\|D_{1} g\right\|_{X}+M \sup _{x \in \Omega}\left[\int_{0}^{x_{2}} \cdots \int_{0}^{x_{N}} h_{0}\left(x, x_{1}, y^{\prime}\right) d y^{\prime}+\int_{B_{x}} h_{1}(x, y) d y\right] \\
& +\sup _{x \in \Omega}\left[\int_{0}^{x_{2}} \cdots \int_{0}^{x_{N}}\left|H\left(x, x_{1}, y^{\prime}, 0,0\right)\right| d y^{\prime}+\int_{B_{x}}\left|\frac{\partial H}{\partial x_{1}}(x, y, 0,0)\right| d y\right] . \tag{3.9}
\end{align*}
$$

From (3.5) and (3.9), it gives

$$
\begin{equation*}
\|U u\|_{X_{1}}=\|U u\|_{X}+\left\|D_{1}(U u)\right\|_{X} \leq\|g\|_{X_{1}}+\bar{\alpha}_{1}+M \bar{\beta}_{1}, \tag{3.10}
\end{equation*}
$$

where

$$
\begin{align*}
\bar{\alpha}_{1} & =\sup _{x \in \Omega} \int_{B_{x}}|H(x, y, 0,0)| d y \\
& +\sup _{x \in \Omega}\left[\int_{B_{x}}\left|\frac{\partial H}{\partial x_{1}}(x, y, 0,0)\right| d y+\int_{0}^{x_{2}} \cdots \int_{0}^{x_{N}}\left|H\left(x, x_{1}, y^{\prime}, 0,0\right)\right| d y^{\prime}\right] \\
\bar{\beta}_{1} & =\sup _{x \in \Omega} \int_{B_{x}} h_{0}(x, y) d y+\sup _{x \in \Omega}\left[\int_{0}^{x_{2}} \cdots \int_{0}^{x_{N}} h_{0}\left(x, x_{1}, y^{\prime}\right) d y^{\prime}+\int_{B_{x}} h_{1}(x, y) d y\right] . \tag{3.11}
\end{align*}
$$

On the other hand, for every $v \in B_{M}$, for all $x \in \Omega$, we have

$$
\begin{align*}
|(C v)(x)| & \leq \int_{\Omega}\left|K\left(x, y, v(y), D_{1} v(y)\right)\right| d y \\
& \leq \int_{\Omega} k_{0}(x, y)\left(1+|v(y)|+\left|D_{1} v(y)\right|\right) d y  \tag{3.12}\\
& \leq \int_{\Omega} k_{0}(x, y)\left(1+\|v\|_{X_{1}}\right) d y \leq(1+M) \sup _{x \in \Omega} \int_{\Omega} k_{0}(x, y) d y
\end{align*}
$$

Thus

$$
\begin{equation*}
\|C v\|_{X} \leq(1+M) \sup _{x \in \Omega} \int_{\Omega} k_{0}(x, y) d y \tag{3.13}
\end{equation*}
$$

Similarly,

$$
\begin{equation*}
\left|D_{1}(C v)(x)\right| \leq \int_{\Omega}\left|\frac{\partial K}{\partial x_{1}}\left(x, y, v(y), D_{1} v(y)\right)\right| d y \leq(1+M) \sup _{x \in \Omega} \int_{\Omega} k_{1}(x, y) d y \tag{3.14}
\end{equation*}
$$

therefore

$$
\begin{equation*}
\left\|D_{1}(C v)\right\|_{X} \leq(1+M) \sup _{x \in \Omega} \int_{\Omega} k_{1}(x, y) d y \tag{3.15}
\end{equation*}
$$

From (3.12) and (3.15) we take

$$
\begin{equation*}
\|C v\|_{X_{1}} \leq(1+M)\left[\sup _{x \in \Omega} \int_{\Omega} k_{0}(x, y) d y+\sup _{x \in \Omega} \int_{\Omega} k_{1}(x, y) d y\right] \equiv(1+M) \bar{\beta}_{2} \tag{3.16}
\end{equation*}
$$

From (3.10) and (3.16) we have that

$$
\begin{equation*}
\|U u+C v\|_{X_{1}} \leq\|U u\|_{X_{1}}+\|C v\|_{X_{1}} \leq\|g\|_{X_{1}}+\bar{\alpha}_{1}+\bar{\beta}_{2}+M\left(\bar{\beta}_{1}+\bar{\beta}_{2}\right) \tag{3.17}
\end{equation*}
$$

Choose $M \geq\|g\|_{X_{1}}+\bar{\alpha}_{1}+\bar{\beta}_{2}+M\left(\bar{\beta}_{1}+\bar{\beta}_{2}\right)$, i.e.,

$$
M \geq \frac{\|g\|_{X_{1}}+\bar{\alpha}_{1}+\bar{\beta}_{2}}{1-\bar{\beta}_{1}-\bar{\beta}_{2}}
$$

Then $U u+C v \in B_{M}$, for all $u, v \in B_{M}$.
Proof (ii). In view of (A4), $U: B_{M} \rightarrow X_{1}$ is a contraction map, if we show that

$$
\begin{equation*}
\|U u-U \bar{u}\|_{X_{1}} \leq \bar{\beta}_{1}\|u-\bar{u}\|_{X_{1}}, \forall u, \bar{u} \in B_{M} \tag{3.18}
\end{equation*}
$$

For every $u, \bar{u} \in B_{M}$, for all $(x, y) \in \Omega$, using (A2, $i$ ), (3.2) leads to

$$
\begin{aligned}
|(U u)(x)-(U \bar{u})(x)| & \leq \int_{B_{x}}\left|H\left(x, y, u(y), D_{1} u(y)\right)-H\left(x, y, \bar{u}(y), D_{1} \bar{u}(y)\right)\right| d y \\
& \leq \int_{B_{x}} h_{0}(x, y)\left(|u(y)-\bar{u}(y)|+\left|D_{1} u(y)-D_{1} \bar{u}(y)\right|\right) d y \\
& \leq\left(\sup _{x \in \Omega} \int_{B_{x}} h_{0}(x, y) d y\right)\|u-\bar{u}\|_{X_{1}}
\end{aligned}
$$

Thus

$$
\begin{equation*}
\|U u-U \bar{u}\|_{X} \leq\left(\sup _{x \in \Omega} \int_{B_{x}} h_{0}(x, y) d y\right)\|u-\bar{u}\|_{X_{1}} \tag{3.19}
\end{equation*}
$$

Similarly, by (3.7) we deduce that, for all $x=\left(x_{1}, x^{\prime}\right) \in \Omega$,

$$
\begin{align*}
& D_{1}(U u)(x)-D_{1}(U \bar{u})(x) \\
& =\int_{0}^{x_{2}} \cdots \int_{0}^{x_{N}}\left[H\left(x, x_{1}, y^{\prime}, u\left(x_{1}, y^{\prime}\right), D_{1} u\left(x_{1}, y^{\prime}\right)\right)\right.  \tag{3.20}\\
& +\int_{B_{x}}\left[\frac{\partial H}{\partial x_{1}}\left(x, y, u\left(x, x_{1}, y^{\prime}, \bar{u}\left(x_{1}, y^{\prime}\right), D_{1} \bar{u}\left(x_{1}, y^{\prime}\right)\right)\right] d y^{\prime}\right.
\end{align*}
$$

using (A2, ii), we get

$$
\begin{align*}
& \left|D_{1}(U u)(x)-D_{1}(U \bar{u})(x)\right| \\
& \leq \int_{0}^{x_{2}} \cdots \int_{0}^{x_{N}} \mid H\left(x, x_{1}, y^{\prime}, u\left(x_{1}, y^{\prime}\right), D_{1} u\left(x_{1}, y^{\prime}\right)\right) \\
& +\int_{B_{x}}\left|\frac{\partial H}{\partial x_{1}}\left(x, y, u(y), D_{1} u(y)\right)-\frac{\partial H}{\partial x_{1}}\left(x, y, \bar{u}(y), D_{1} \bar{u}(y)\right)\right| d y \\
& \leq \int_{0}^{x_{2}} \ldots \int_{0}^{x_{N}} h_{0}\left(x, x_{1}, y^{\prime}\right)\left[\left|u\left(x_{1}, y^{\prime}\right)-\bar{u}\left(x_{1}, y^{\prime}\right)\right|+\left|D_{1} u\left(x_{1}, y^{\prime}\right)-D_{1} \bar{u}\left(x_{1}, y^{\prime}\right)\right|\right] d y^{\prime} \\
& +\int_{B_{x}} h_{1}(x, y)\left[|u(y)-\bar{u}(y)|+\left|D_{1} u(y)-D_{1} \bar{u}(y)\right|\right] d y \\
& \leq \sup _{x \in \Omega}\left[\int_{0}^{x_{2}} \cdots \int_{0}^{x_{N}} h_{0}\left(x, x_{1}, y^{\prime}\right) d y^{\prime}+\int_{B_{x}} h_{1}(x, y) d y\right]\|u-\bar{u}\|_{X_{1}} .
\end{align*}
$$

Then

$$
\begin{align*}
& \left\|D_{1}(U u)-D_{1}(U \bar{u})\right\|_{X} \\
& \leq \sup _{x \in \Omega}\left[\int_{0}^{x_{2}} \cdots \int_{0}^{x_{N}} h_{0}\left(x, x_{1}, y^{\prime}\right) d y^{\prime}+\int_{B_{x}} h_{1}(x, y) d y\right]\|u-\bar{u}\|_{X_{1}} . \tag{3.22}
\end{align*}
$$

From (3.19) and (3.22) we take

$$
\begin{equation*}
\|U u-U \bar{u}\|_{X_{1}} \leq \bar{\beta}_{1}\|u-\bar{u}\|_{X_{1}}, \tag{3.23}
\end{equation*}
$$

where

$$
\begin{equation*}
\bar{\beta}_{1} \leq \bar{\beta}_{1}+\bar{\beta}_{2}<1 \tag{3.24}
\end{equation*}
$$

by (A4).
Proof (iii). To prove (iii), let $\left\{u_{m}\right\} \subset B_{M}, u \in B_{M},\left\|u_{m}-u\right\|_{X_{1}} \rightarrow 0$, as $m \rightarrow \infty$, we have to prove that

$$
\begin{equation*}
\left\|C u_{m}-C u\right\|_{X} \rightarrow 0 \text { and }\left\|D_{1}\left(C u_{m}\right)-D_{1}(C u)\right\|_{X} \rightarrow 0, \text { as } m \rightarrow \infty \tag{3.25}
\end{equation*}
$$

Note that

$$
\begin{equation*}
\left|\left(C u_{m}\right)(x)-(C u)(x)\right| \leq \int_{\Omega}\left|K\left(x, y, u_{m}(y), D_{1} u_{m}(y)\right)-K\left(x, y, u(y), D_{1} u(y)\right)\right| d y \tag{3.26}
\end{equation*}
$$

Give $\varepsilon>0$. Since the function $K$ is uniformly continuous on $\Omega \times \Omega \times[-M, M] \times$ $[-M, M]$, there exists $\delta>0$ such that

$$
\begin{aligned}
& \forall(x, y) \in \Omega \times \Omega, \forall u, v, \bar{u}, \bar{v} \in[-M, M] \\
& |u-\bar{u}|+|v-\bar{v}|<\delta \Longrightarrow|K(x, y, u, v)-K(x, y, \bar{u}, \bar{v})|<\varepsilon
\end{aligned}
$$

By $\left\|u_{m}-u\right\|_{X} \rightarrow 0$, and $\left\|D_{1} u_{m}-D_{1} u\right\|_{X} \rightarrow 0$, there is $m_{0} \in \mathbb{N}$ such that

$$
\forall m \in \mathbb{N}, m \geq m_{0} \Longrightarrow\left\|u_{m}-u\right\|_{X}+\left\|D_{1} u_{m}-D_{1} u\right\|_{X}<\delta
$$

It follows that $\forall m \in \mathbb{N}$, if $m \geq m_{0}$ then

$$
\left|K\left(x, y, u_{m}(y), D_{1} u_{m}(y)\right)-K\left(x, y, u(y), D_{1} u(y)\right)\right|<\varepsilon
$$

$\forall(x, y) \in \Omega \times \Omega$, so

$$
\left|\left(C u_{m}\right)(x)-(C u)(x)\right|<\varepsilon, \forall x \in \Omega, \forall m \geq m_{0}
$$

it means that

$$
\begin{equation*}
\left\|C u_{m}-C u\right\|_{X}<\varepsilon, \forall m \geq m_{0} \tag{3.27}
\end{equation*}
$$

i.e., $\left\|C u_{m}-C u\right\|_{X} \rightarrow 0$, as $m \rightarrow \infty$.

By the same way, we get $\left\|D_{1}\left(C u_{m}\right)-D_{1}(C u)\right\|_{X} \rightarrow 0$, as $m \rightarrow \infty$.
Proof (iv). To prove (iv), we use Lemma 2.2. Condition (2.10)(i) holds because by (i), we have that $F=C\left(B_{M}\right) \subset B_{M}$. It remains to show (2.10)(ii). We have, for all $u \in B_{M}$, for all $x, \bar{x} \in \Omega$,

$$
\begin{equation*}
(C u)(x)-(C u)(\bar{x})=\int_{\Omega}\left[K\left(x, y, u(y), D_{1} u(y)\right)-K\left(\bar{x}, y, u(y), D_{1} u(y)\right)\right] d y \tag{3.28}
\end{equation*}
$$

Let $\varepsilon>0$. By the fact that $K$ is uniformly continuous on $\Omega \times \Omega \times[-M, M] \times[-M, M]$, there exists $\delta_{1}>0$ such that $\forall x, \bar{x} \in \Omega$,

$$
|x-\bar{x}|<\delta_{1} \Longrightarrow|K(x, y, \bar{u}, \bar{v})-K(\bar{x}, y, \bar{u}, \bar{v})|<\frac{\varepsilon}{2}, \forall(y, \bar{u}, \bar{v}) \in \Omega \times[-M, M] .
$$

Then

$$
\begin{aligned}
\forall x, \bar{x} & \in \Omega,|x-\bar{x}|<\delta_{1} \\
& \Longrightarrow\left|K\left(x, y, u(y), D_{1} u(y)\right)-K\left(\bar{x}, y, u(y), D_{1} u(y)\right)\right|<\frac{\varepsilon}{2}, \forall(y, u) \in \Omega \times B_{M}
\end{aligned}
$$

so

$$
\begin{aligned}
\forall x, \bar{x} & \in \Omega,|x-\bar{x}|<\delta_{1} \\
& \Longrightarrow \int_{\Omega}\left|K\left(x, y, u(y), D_{1} u(y)\right)-K\left(\bar{x}, y, u(y), D_{1} u(y)\right)\right| d y<\frac{\varepsilon}{2}, \forall u \in B_{M}
\end{aligned}
$$

This yields

$$
\begin{equation*}
\forall x, \bar{x} \in \Omega,|x-\bar{x}|<\delta_{1} \Longrightarrow|(C u)(x)-(C u)(\bar{x})|<\frac{\varepsilon}{2}, \forall u \in B_{M} \tag{3.29}
\end{equation*}
$$

Similarly, by the uniformly continuity of $\frac{\partial K}{\partial x_{1}}, D_{1} g$, on their domains, we also have that for the $\varepsilon>0$ considered there is a $\delta_{2}>0$ such that $\forall x, \bar{x} \in \Omega$,

$$
\begin{equation*}
|x-\bar{x}|<\delta_{2} \Longrightarrow\left|D_{1}(C u)(x)-D_{1}(C u)(\bar{x})\right|<\frac{\varepsilon}{2}, \forall u \in B_{M} \tag{3.30}
\end{equation*}
$$

Consequently, choosing $\delta=\min \left\{\delta_{1}, \delta_{2}\right\}$, we obtain $\forall x, \bar{x} \in \Omega$,

$$
\begin{equation*}
|x-\bar{x}|<\delta \Longrightarrow|(C u)(x)-(C u)(\bar{x})|+\left|D_{1}(C u)(x)-D_{1}(C u)(\bar{x})\right|<\varepsilon, \forall u \in B_{M} . \tag{3.31}
\end{equation*}
$$

Lemma 2.2 implies that $F=C\left(B_{M}\right)$ is relatively compact in $X_{1}$. Applying the Krasnosel'skii fixed point theorem (Theorem 1.1), the existence of a solution is proved.

Now, we show that the set $S$ of solutions is compact in $X_{1}$ :

$$
S=\left\{u \in B_{M}: u=U u+C u\right\}=\left\{u \in B_{M}: u=(I-U)^{-1} C u\right\}
$$

From the compactness of the operator $C: B_{M} \rightarrow B_{M}$ and the continuity of $(I-U)^{-1}$ : $B_{M} \rightarrow B_{M}$, and $S=(I-U)^{-1} C(S)$, we only prove that $S$ is closed. Let $\left\{u_{m}\right\} \subset S$, $u \in X_{1},\left\|u_{m}-u\right\|_{X_{1}} \rightarrow 0$. The continuity of $(I-U)^{-1} C$ leads to

$$
\begin{aligned}
\left\|u-(I-U)^{-1} C u\right\|_{X_{1}} & \leq\left\|u-u_{m}\right\|_{X_{1}}+\left\|u_{m}-(I-U)^{-1} C u\right\|_{X_{1}} \\
& =\left\|u-u_{m}\right\|_{X_{1}}+\left\|(I-U)^{-1} C u_{m}-(I-U)^{-1} C u\right\|_{X_{1}} \rightarrow 0
\end{aligned}
$$

so $u=(I-U)^{-1} C u \in S$. Theorem 3.1 is proved.

## 4. An example

Consider (1.1), with the functions $H, K, g$ as follows

$$
\left\{\begin{array}{l}
H(x, y, u, v)=h(x)\left[y_{1}^{\sigma} \ldots y_{N}^{\sigma} \sin \left(\frac{\pi u}{2 u_{0}(y)}\right)+y_{1}^{\gamma} \ldots y_{N}^{\gamma} \cos \left(\frac{2 \pi v}{D_{1} u_{0}(y)}\right)\right]  \tag{4.1}\\
K(x, y, u, v)=h(x) K_{1}(y, u, v) \\
g(x)=u_{0}(x)-h(x)\left(\frac{2+x_{1}^{\sigma+1} \ldots x_{N}^{\sigma+1}}{(\sigma+1)^{N}}+\frac{2+x_{1}^{\gamma+1} \ldots x_{N}^{\gamma+1}}{(\gamma+1)^{N}}\right)
\end{array}\right.
$$

where

$$
\left\{\begin{array}{l}
K_{1}(y, u, v)=y_{1}^{\sigma} \ldots y_{N}^{\sigma}\left[\frac{|u|}{u_{0}(y)}+\left(\frac{u}{u_{0}(y)}\right)^{3 / 7}\right]+y_{1}^{\gamma} \ldots y_{N}^{\gamma}\left[\frac{|v|}{D_{1} u_{0}(y)}+\left(\frac{v}{D_{1} u_{0}(y)}\right)^{2 / 5}\right]  \tag{4.2}\\
u_{0}(x)=e^{x_{1}}+x_{1}^{\gamma_{1}}\left|x_{2}-\alpha\right|^{\gamma_{2}}+\sum_{i=3}^{N}\left|x_{i}-\alpha\right| \\
h(x)=x_{1}^{\tilde{\gamma}_{1}}\left|x_{2}-\tilde{\alpha}\right|^{\tilde{\gamma}_{2}}+\sum_{i=3}^{N}\left|x_{i}-\tilde{\alpha}\right|
\end{array}\right.
$$

and $\sigma, \gamma, \alpha, \gamma_{2}, \gamma_{1}, \tilde{\alpha}, \tilde{\gamma}_{2}, \tilde{\gamma}_{1}$ are positive constants satisfying

$$
\left\{\begin{array}{l}
0<\alpha<1,0<\gamma_{2} \leq 1<\gamma_{1}  \tag{4.3}\\
0<\tilde{\alpha}<1,0<\tilde{\gamma}_{2} \leq 1<\tilde{\gamma}_{1} \\
2 \pi\left(\frac{1}{(\sigma+1)^{N-1}}+\frac{1}{(\gamma+1)^{N-1}}\right)\left[\max \left\{\tilde{\alpha}^{\tilde{\gamma}_{2}},(1-\tilde{\alpha})^{\tilde{\gamma}_{2}}\right\}+(N-2) \max \{\tilde{\alpha}, 1-\tilde{\alpha}\}\right] \\
+2(1+\pi)\left(\frac{1}{(\sigma+1)^{N}}+\frac{1}{(\gamma+1)^{N}}\right) \times \\
\times\left[\left(1+\tilde{\gamma}_{1}\right) \max \left\{\tilde{\alpha} \tilde{\gamma}_{2},(1-\tilde{\alpha})^{\tilde{\gamma}_{2}}\right\}+(N-2) \max \{\tilde{\alpha}, 1-\tilde{\alpha}\}\right]<1
\end{array}\right.
$$

Note that

$$
\begin{gathered}
u_{0}(x)=e^{x_{1}}+x_{1}^{\gamma_{1}}\left|x_{2}-\alpha\right|^{\gamma_{2}}+\sum_{i=3}^{N}\left|x_{i}-\alpha\right| \\
D_{1} u_{0}(x)=e^{x_{1}}+\gamma_{1} x_{1}^{\gamma_{1}-1}\left|x_{2}-\alpha\right|^{\gamma_{2}}
\end{gathered}
$$

so $u_{0} \in X_{1}$ and $u_{0}(x) \geq 1, D_{1} u_{0}(x) \geq 1$.

We can prove that (A1), (A2) hold. It is easy to see that (A1) holds, since $u_{0}$, $h \in X_{1}$.

Assumption (A2) holds, by the following. First, $H \in C\left(\Omega \times \Omega \times \mathbb{R}^{2} ; \mathbb{R}\right)$. On the other hand,

$$
\frac{\partial h}{\partial x_{1}} \in X
$$

and

$$
\frac{\partial H}{\partial x_{1}}=\frac{\partial h}{\partial x_{1}}(x)\left[y_{1}^{\sigma} \ldots y_{N}^{\sigma} \sin \left(\frac{\pi u}{2 u_{0}(y)}\right)+y_{1}^{\gamma} \ldots y_{N}^{\gamma} \cos \left(\frac{2 \pi v}{D_{1} u_{0}(y)}\right)\right]
$$

hence

$$
\frac{\partial H}{\partial x_{1}} \in C\left(\Omega \times \Omega \times \mathbb{R}^{2} ; \mathbb{R}\right)
$$

Next, it is obviously that

$$
\begin{align*}
|H(x, y, u, v)-H(x, y, \bar{u}, \bar{v})| & \leq h(x)\left[y_{1}^{\sigma} \ldots y_{N}^{\sigma} \frac{\pi|u-\bar{u}|}{2 u_{0}(y)}+y_{1}^{\gamma} \ldots y_{N}^{\gamma} \frac{2 \pi|v-\bar{v}|}{D_{1} u_{0}(y)}\right] \\
& \leq 2 \pi h(x)\left(y_{1}^{\sigma} \ldots y_{N}^{\sigma}+y_{1}^{\gamma} \ldots y_{N}^{\gamma}\right)[|u-\bar{u}|+|v-\bar{v}|]  \tag{4.4}\\
& \equiv h_{0}(x, y)(|u-\bar{u}|+|v-\bar{v}|)
\end{align*}
$$

with

$$
\begin{equation*}
h_{0}(x, y)=2 \pi h(x)\left(y_{1}^{\sigma} \ldots y_{N}^{\sigma}+y_{1}^{\gamma} \ldots y_{N}^{\gamma}\right) \tag{4.5}
\end{equation*}
$$

Similarly

$$
\begin{equation*}
\left|\frac{\partial H}{\partial x_{1}}(x, y, u, v)-\frac{\partial H}{\partial x_{1}}(x, y, \bar{u}, \bar{v})\right| \leq h_{1}(x, y)(|u-\bar{u}|+|v-\bar{v}|), \tag{4.6}
\end{equation*}
$$

where

$$
\begin{equation*}
h_{1}(x, y)=2 \pi\left|\frac{\partial h}{\partial x_{1}}(x)\right|\left(y_{1}^{\sigma} \ldots y_{N}^{\sigma}+y_{1}^{\gamma} \ldots y_{N}^{\gamma}\right) \tag{4.7}
\end{equation*}
$$

Assumption (A3) holds, by the following. First, $K \in C\left(\Omega \times \Omega \times \mathbb{R}^{2} ; \mathbb{R}\right)$. On the other hand,

$$
\begin{gathered}
\frac{\partial h}{\partial x_{1}} \in X, \quad \frac{\partial K}{\partial x_{1}}=\frac{\partial h}{\partial x_{1}}(x) K_{1}(y, u, v) \\
\frac{\partial K}{\partial x_{1}} \in C\left(\Omega \times \Omega \times \mathbb{R}^{2} ; \mathbb{R}\right)
\end{gathered}
$$

Next, applying the inequality

$$
\begin{equation*}
x \leq 1+x^{q}, \forall x \geq 0, \forall q \geq 1 \tag{4.8}
\end{equation*}
$$

we have

$$
\begin{align*}
\left|K_{1}(y, u, v)\right| & \leq y_{1}^{\sigma} \ldots y_{N}^{\sigma}\left[1+\frac{2|u|}{u_{0}(y)}\right]+y_{1}^{\gamma} \ldots y_{N}^{\gamma}\left[1+\frac{2|v|}{D_{1} u_{0}(y)}\right]  \tag{4.9}\\
& \leq 2\left(y_{1}^{\sigma} \ldots y_{N}^{\sigma}+y_{1}^{\gamma} \ldots y_{N}^{\gamma}\right)(1+|u|+|v|) .
\end{align*}
$$

It follows that

$$
\begin{equation*}
|K(x, y, u, v)|=h(x)\left|K_{1}(y, u, v)\right| \leq k_{0}(x, y)(1+|u|+|v|) \tag{4.10}
\end{equation*}
$$

with

$$
\begin{equation*}
k_{0}(x, y)=2 h(x)\left(y_{1}^{\sigma} \ldots y_{N}^{\sigma}+y_{1}^{\gamma} \ldots y_{N}^{\gamma}\right) \tag{4.11}
\end{equation*}
$$

Similarly

$$
\begin{equation*}
\left|\frac{\partial K}{\partial x_{1}}(x, y, u, v)\right| \leq k_{1}(x, y)(1+|u|+|v|) \tag{4.12}
\end{equation*}
$$

in which

$$
\begin{equation*}
k_{1}(x, y)=2\left|\frac{\partial h}{\partial x_{1}}(x)\right|\left(y_{1}^{\sigma} \ldots y_{N}^{\sigma}+y_{1}^{\gamma} \ldots y_{N}^{\gamma}\right) . \tag{4.13}
\end{equation*}
$$

To see that assumption (A4) holds, we make the following estimations.
(i) Estimating the term $\bar{\beta}_{1}$.

We have

$$
\begin{gather*}
\int_{B_{x}} h_{0}(x, y) d y=2 \pi h(x) \int_{B_{x}}\left(y_{1}^{\sigma} \ldots y_{N}^{\sigma}+y_{1}^{\gamma} \ldots y_{N}^{\gamma}\right) d y \\
=2 \pi\left(\frac{x_{1}^{\sigma+1} \ldots x_{N}^{\sigma+1}}{(\sigma+1)^{N}}+\frac{x_{1}^{\gamma+1} \ldots x_{N}^{\gamma+1}}{(\gamma+1)^{N}}\right) h(x) \leq 2 \pi\left(\frac{1}{(\sigma+1)^{N}}+\frac{1}{(\gamma+1)^{N}}\right) h(x) \\
\int_{B_{x}} h_{1}(x, y) d y=2 \pi\left|\frac{\partial h}{\partial x_{1}}(x)\right| \int_{B_{x}}\left(y_{1}^{\sigma} \ldots y_{N}^{\sigma}+y_{1}^{\gamma} \ldots y_{N}^{\gamma}\right) d y \\
\leq 2 \pi\left(\frac{1}{(\sigma+1)^{N}}+\frac{1}{(\gamma+1)^{N}}\right)\left|\frac{\partial h}{\partial x_{1}}(x)\right| \tag{4.14}
\end{gather*}
$$

and

$$
\begin{gather*}
\int_{0}^{x_{2}} \ldots \int_{0}^{x_{N}} h_{0}\left(x, x_{1}, y^{\prime}\right) d y^{\prime}=2 \pi h(x) \int_{0}^{x_{2}} \ldots \int_{0}^{x_{N}}\left(x_{1}^{\sigma} y_{2}^{\sigma} \ldots y_{N}^{\sigma}+x_{1}^{\gamma} y_{2}^{\gamma} \ldots y_{N}^{\gamma}\right) d y^{\prime} \\
=2 \pi h(x)\left(\frac{x_{1}^{\sigma} x_{2}^{\sigma+1} \ldots x_{N}^{\sigma+1}}{(\sigma+1)^{N-1}}+\frac{x_{1}^{\gamma} x_{2}^{\gamma+1} \ldots x_{N}^{\gamma+1}}{(\gamma+1)^{N-1}}\right) \\
\leq 2 \pi h(x)\left(\frac{1}{(\sigma+1)^{N-1}}+\frac{1}{(\gamma+1)^{N-1}}\right) \tag{4.15}
\end{gather*}
$$

In order to continue, we need the following lemma, its proof is not difficult so we omit it.
Lemma 4.1. Let positive constants $\alpha, \gamma_{2}, \gamma_{1}$ satisfy $0<\alpha<1,0<\gamma_{2} \leq 1<\gamma_{1}$. Then

$$
\begin{align*}
& 0 \leq x_{1}^{\gamma_{1}}\left|x_{2}-\alpha\right|^{\gamma_{2}} \leq \max \left\{\alpha^{\gamma_{2}},(1-\alpha)^{\gamma_{2}}\right\}, \forall x_{1}, x_{2} \in[0,1] \\
& 0 \leq x_{1}^{\gamma_{1}-1}\left|x_{2}-\alpha\right|^{\gamma_{2}} \leq \max \left\{\alpha^{\gamma_{2}},(1-\alpha)^{\gamma_{2}}\right\}, \forall x_{1}, x_{2} \in[0,1] . \tag{4.16}
\end{align*}
$$

Using Lemma 4.1, we get

$$
\left\{\begin{array}{l}
0 \leq h(x)=x_{1}^{\tilde{\gamma}_{1}}\left|x_{2}-\tilde{\alpha}\right|^{\tilde{\gamma}_{2}}+\sum_{i=3}^{N}\left|x_{i}-\tilde{\alpha}\right|  \tag{4.17}\\
h(x) \leq \max \left\{\tilde{\alpha}^{\tilde{\gamma}_{2}},(1-\tilde{\alpha})^{\tilde{\gamma}_{2}}\right\}+(N-2) \max \{\tilde{\alpha}, 1-\tilde{\alpha}\} \\
0 \leq \frac{\partial h}{\partial x_{1}}(x)=\tilde{\gamma}_{1} x_{1}^{\tilde{\gamma}_{1}-1}\left|x_{2}-\tilde{\alpha}\right|^{\tilde{\gamma}_{2}} \leq \tilde{\gamma}_{1} \max \left\{\tilde{\alpha}^{\tilde{\gamma}_{2}},(1-\tilde{\alpha})^{\tilde{\gamma}_{2}}\right\}, \forall x \in \Omega
\end{array}\right.
$$

Then

$$
\begin{align*}
& \int_{B_{x}} h_{0}(x, y) d y \\
& \leq 2 \pi\left(\frac{1}{(\sigma+1)^{N}}+\frac{1}{(\gamma+1)^{N}}\right)\left[\max \left\{\tilde{\alpha}^{\tilde{\gamma}_{2}},(1-\tilde{\alpha})^{\tilde{\gamma}_{2}}\right\}+(N-2) \max \{\tilde{\alpha}, 1-\tilde{\alpha}\}\right] \\
& \int_{B_{x}} h_{1}(x, y) d y \leq 2 \pi\left(\frac{1}{(\sigma+1)^{N}}+\frac{1}{(\gamma+1)^{N}}\right) \tilde{\gamma}_{1} \max \left\{\tilde{\alpha}^{\tilde{\gamma}_{2}},(1-\tilde{\alpha})^{\tilde{\gamma}_{2}}\right\}, \\
& \int_{0}^{x_{2}} \cdots \int_{0}^{x_{N}} h_{0}\left(x, x_{1}, y^{\prime}\right) d y^{\prime} \\
& \leq 2 \pi\left(\frac{1}{(\sigma+1)^{N-1}}+\frac{1}{(\gamma+1)^{N-1}}\right)\left[\max \left\{\tilde{\alpha}^{\tilde{\gamma}_{2}},(1-\tilde{\alpha})^{\tilde{\gamma}_{2}}\right\}+(N-2) \max \{\tilde{\alpha}, 1-\tilde{\alpha}\}\right] . \tag{4.18}
\end{align*}
$$

Therefore

$$
\begin{align*}
& \bar{\beta}_{1}=\sup _{x \in \Omega} \int_{B_{x}} h_{0}(x, y) d y+\sup _{x \in \Omega}\left[\int_{B_{x}} h_{1}(x, y) d y+\int_{0}^{x_{2}} \ldots \int_{0}^{x_{N}} h_{0}\left(x, x_{1}, y^{\prime}\right) d y^{\prime}\right] \\
& \leq 2 \pi\left(\frac{1}{(\sigma+1)^{N-1}}+\frac{1}{(\gamma+1)^{N-1}}\right)\left[\max \left\{\tilde{\alpha}^{\tilde{\gamma}_{2}},(1-\tilde{\alpha})^{\tilde{\gamma}_{2}}\right\}+(N-2) \max \{\tilde{\alpha}, 1-\tilde{\alpha}\}\right] \\
& +2 \pi\left(\frac{1}{(\sigma+1)^{N}}+\frac{1}{(\gamma+1)^{N}}\right)\left[\left(1+\tilde{\gamma}_{1}\right) \max \left\{\tilde{\alpha}^{\tilde{\gamma}_{2}},(1-\tilde{\alpha})^{\tilde{\gamma}_{2}}\right\}+(N-2) \max \{\tilde{\alpha}, 1-\tilde{\alpha}\}\right] . \tag{4.19}
\end{align*}
$$

(ii) Estimating the term $\bar{\beta}_{2}$.

Similarly, using Lemma 4.1, we get

$$
\begin{align*}
& \int_{\Omega} k_{0}(x, y) d y=2 h(x) \int_{\Omega}\left(y_{1}^{\sigma} \ldots y_{N}^{\sigma}+y_{1}^{\gamma} \ldots y_{N}^{\gamma}\right) d y=2\left(\frac{1}{(\sigma+1)^{N}}+\frac{1}{(\gamma+1)^{N}}\right) h(x) \\
& \leq 2\left(\frac{1}{(\sigma+1)^{N}}+\frac{1}{(\gamma+1)^{N}}\right)\left[\max \left\{\tilde{\alpha}^{\tilde{\gamma}_{2}},(1-\tilde{\alpha})^{\tilde{\gamma}_{2}}+(N-2) \max \{\tilde{\alpha}, 1-\tilde{\alpha}\}\right]\right. \\
& \int_{\Omega} k_{1}(x, y) d y=2\left|\frac{\partial h}{\partial x_{1}}(x)\right| \int_{\Omega}\left(y_{1}^{\sigma} \ldots y_{N}^{\sigma}+y_{1}^{\gamma} \ldots y_{N}^{\gamma}\right) d y \\
& =2\left(\frac{1}{(\sigma+1)^{N}}+\frac{1}{(\gamma+1)^{N}}\right)\left|\frac{\partial h}{\partial x_{1}}(x)\right| \\
& \leq 2\left(\frac{1}{(\sigma+1)^{N}}+\frac{1}{(\gamma+1)^{N}}\right) \tilde{\gamma}_{1} \max \left\{\tilde{\alpha}^{\tilde{\gamma}_{2}},(1-\tilde{\alpha})^{\tilde{\gamma}_{2}}\right. \tag{4.20}
\end{align*}
$$

where

$$
\begin{align*}
& \bar{\beta}_{2}=\sup _{x \in \Omega} \int_{\Omega} k_{0}(x, y) d y+\sup _{x \in \Omega} \int_{\Omega} k_{1}(x, y) d y \\
& \leq 2\left(\frac{1}{(\sigma+1)^{N}}+\frac{1}{(\gamma+1)^{N}}\right)\left[\left(1+\tilde{\gamma}_{1}\right) \max \left\{\tilde{\alpha}^{\tilde{\gamma}_{2}},(1-\tilde{\alpha})^{\tilde{\gamma}_{2}}+(N-2) \max \{\tilde{\alpha}, 1-\tilde{\alpha}\}\right] .\right. \tag{4.21}
\end{align*}
$$

It follows from (4.3), (4.19) and (4.21) that

$$
\begin{equation*}
\bar{\beta}_{1}+\bar{\beta}_{2}<1 \tag{4.22}
\end{equation*}
$$

Theorem 3.1 is fulfilled in this case. Furthermore, $u_{0} \in X_{1}$ is also a solution of (1.1).
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