Fixed Point Theory, 20(2019), No. 1, 195-202 DOI: 10.24193/fpt-ro.2019.1.12 http://www.math.ubbcluj.ro/~nodeacj/sfptcj.html

FIXED POINTS, MULTI-VALUED UNIFORMLY LIPSCHITZIAN MAPPINGS AND UNIFORM NORMAL STRUCTURE

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Abstract. Khamsi and Kirk [11] gave the definition of multi-valued uniformly Lipschitzian mappings via generalized orbits. We will prove a fixed point theorem in metric spaces with uniform normal structure which extends Lim and Xu's theorems [13] to multi-valued uniformly Lipschitzian mappings. We also give a fixed point result for multi-valued uniformly Lipschitzian mappings in hyperconvex spaces.

Key Words and Phrases: Fixed point, convexity structure, multi-valued mapping, normal structure coefficient, uniform normal structure.

2010 Mathematics Subject Classification: 47H10, 46B20.

1. INTRODUCTION

Let C be a nonempty subset of a metric space (E, d). A mapping $T : C \to C$ is called *uniformly* k-Lipschitzian if there exists a constant k > 0 such that

$$d(T^n x, T^n y) \leqslant k \cdot d(x, y)$$

for all points $x, y \in C$ and any positive integer $n \ge 1$. It is clear that nonexpansive mappings are uniformly 1-Lipschitzian mappings. Again, when E has some "nice" geometric properties and k > 1 is not too large, we can assure that T has a fixed point (see [1]).

The first fixed point theorem for uniformly Lipschitzian mappings in uniformly convex Banach spaces was initiated by Goebel and Kirk [9]. A different and more general approach is proposed by Lifshitz [12] in metric spaces. The next fixed point theorem for uniformly Lipschitzian mappings in Banach spaces with uniform normal structure is due to Casini and Maluta [5]. Finally the work by Lim and Xu [13] links the existence of fixed points of such mappings to uniform normal structure property using the ideas developed by Baillon [3].

In [11] Khamsi and Kirk introduced the definition of multi-valued uniformly Lipschitzian mappings in metric spaces and extended the famous Lifshitz's fixed point theorem to multi-valued mappings.

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In this note we will prove a fixed point theorem for multi-valued uniformly Lipschitzian mappings in metric spaces with uniform normal stucture which extend Lim and Xu's theorem [13].

2. Preliminaries

We start by giving the definition of multi-valued uniformly Lipschitzian mappings via the generalized orbits [11].

Definition 2.1. Let (E, d) be a metric space and $T : E \to \mathcal{N}(E)$, where $\mathcal{N}(E)$ denotes the collection of all nonempty subset of E, be a multi-valued map. For any $x \in E$, the sequence $\{x_n\}$ is called a *generalized orbit of* x if $x_0 = x$ and $x_{n+1} \in T(x_n)$ for any $n \ge 0$. We will use the notion $O_T(x)$ to denote such a sequence.

It is clear that for a given $x \in E$, the map T may have many different orbits generated by x. Therefore the notation $O_T(x)$ should be used carefully.

Definition 2.2. Let (E, d) be a metric space. A multi-valued mapping $T : E \to \mathcal{N}(E)$ is called a *uniformly* k-*Lipschitzian* mapping (with k > 0) if and only if for any $x, y \in E$, and any generalized orbit $\{x_n\} \in O_T(x)$, there exists a generalized orbit $\{y_n\} \in O_T(y)$ such that

$$d(x_{n+h}, y_n) \leqslant k \cdot d(x_h, y),$$

for any $n \ge 1$, $h \ge 0$, where $x_0 = x$.

Note that when T is single-valued, then the above definition coincides with the traditional definition since any x will have only one orbit generated by iterating T.

Now we recall some convexity structure on metric spaces.

Let $\mathcal{F}(E)$ denote a nonempty family of subsets of a metric space (E, d). We say that $\mathcal{F}(E)$ defines *convexity stucture* on E if $\mathcal{F}(E)$ is satble by intersection and that $\mathcal{F}(E)$ has *property* (R) if any decreasing sequence $\{C_n\}$ of nonempty closed bounded subset of E with $C_n \in \mathcal{F}(E)$ has nonvoid intersection.

A subset of E is said to be *admissible* if it is an intersection of closed balls [7]. We denote by $\mathcal{A}(E)$ the family of all admissible subsets of E. It is obvious that $\mathcal{A}(E)$ defines a convexity structure on E. In this paper any other convexity structure $\mathcal{F}(E)$ is always assumed to contain $\mathcal{A}(E)$.

For $C \subset E$, we denote the following:

$$r_x(C) = \sup\{d(x, y) : y \in C\}, \ x \in C,$$

 $R(C) = \inf\{r_x(C) : x \in C\}.$

For a bounded subset C of E, we define the admissible hull of C, denoted ad(C), as the intersection of all those admissible subsets of E that contains C, i.e.

 $ad(C) = \bigcap \{ B \subset E : C \subset B \text{ with } B \text{ admissible} \}.$

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We know [1]: Let C be a bounded subset of a metric space E and $x \in E$. Then $r_x(ad(C)) = r_x(C)$.

We introduce uniformly normal structure with respect to convexity structure $\mathcal{F}(E)$ in metric space E.

Definition 2.3. A metric space (E, d) is said to have *uniformly normal structure* if there exists a convexity structure $\mathcal{F}(E)$ such that

 $R(C) \leqslant \alpha \cdot diam(C)$

for some constant $\alpha \in (0,1)$ and for all $C \in \mathcal{F}(E)$ that is bounded and consist of more than one point. We also say that $\mathcal{F}(E)$ is uniformly normal.

The number N(E) is said to be the normal structure coefficient [4] if

$$N(E) = \inf\left\{\frac{diam(C)}{R(C)} : C \in \mathcal{F}(E) \text{ bounded with } diam(C) > 0\right\}$$

It is easy to see that E has uniformly normal structure if and only if N(E) > 1.

It is known that every convexity structure with uniformly normal structure has property (R), [1].

In [13], Lim and Xu introduced so-called property (P) for metric space.

Definition 2.4. A metric space (E, d) is said to have property (P) if given two bounded sequences $\{x_n\}$ and $\{z_n\}$ in E, one can find some $z \in \bigcap_{n \ge 1} ad(\{z_j : j \ge n\})$

such that

$$\limsup_{n \to +\infty} d(z, x_n) \leq \limsup_{j \to +\infty} \limsup_{n \to +\infty} d(z_j, x_n).$$

If *E* has property (*R*), then $\bigcap_{n \ge 1} ad(\{z_j : j \ge n\}) \ne \emptyset$. Also, if *E* is a weakly compact convex subset of a normed linear space then admissible hulls are closed convex and $\bigcap_{n \ge 1} ad(\{z_j : j \ge n\}) \ne \emptyset$ by weak compactness of *E*, and that *E* possesses property

(P) follows directly from the weak lower semicontinuity of the function

$$\limsup_{n \to +\infty} \|x_n - x\|.$$

3. MAIN RESULT

Lim and Xu [13] established the following key lemma.

Lemma 3.1. Let (E, d) be a complete bounded metric space with both property (P)and uniformly normal structure. Let N(E) be the normal structure coefficient with respect to the given convexity structure $\mathcal{F}(E)$. Then for any sequence $\{x_n\}$ in E and any constant $\alpha > \tilde{N}(E) = \frac{1}{N(E)}$, there exists a point $z \in E$ satisfying the properties:

(a)
$$d(z,y) \leq \limsup_{n \to +\infty} d(x_n,y)$$
 for all $y \in E$

(b) $\limsup_{n \to +\infty} d(z, x_n) \leq \alpha \cdot diam(\{x_n\}).$

We now present the existence theorem for multi-valued uniformly Lipschitzian mappings in a metric space.

Theorem 3.2. Let (E, d) be a complete bounded metric space with both property (P)and uniformly normal structure and $T : E \to C(E)$, i.e. T(x) is a nonempty closed convex subset of E, for any $x \in E$. If T is uniformly k-Lipschitzian with

$$k < [\tilde{N}(E)]^{-\frac{1}{2}} = \sqrt{N(E)}$$

then T has a fixed point, i.e. there exists $x \in E$ such that $x \in T(x)$.

Proof. We may assume $k \ge 1$ since then k < 1, i.e. T is a set-valued contraction in the usual sense and hence has a fixed point in a complete space E, [14].

Choose constant $\alpha \in (\tilde{N}(E), 1)$ such that $k < \frac{1}{\sqrt{\alpha}}$.

Let $x \in E$ and $\{x_n\} \in O_T(x)$ be a generalized orbit of x. Using Lemma 3.1, one can construct a point z found in Lemma 3.1 associated with the sequence $\{x_n\}$. Set $\sigma^1(x) = z$. This is the notation used in [3]. Note that $\sigma^2(x)$ is a point found in Lemma 3.1 associated with the sequence $\{\sigma^1(x)_n\}$ which is the generalized orbit of $\sigma^1(x)$.

Fix $x \in E$ and $\{x_n\}$ be a generalized orbit of x. By induction, one will construct a sequence $\{\sigma^m(x)\}\$ and generalized orbit $\{\sigma^m(x)_n\}_{n\geq 1}$ of $\sigma^m(x)$ for any $m \geq 1$, such that $\sigma^{m+1}(x)$ satisfy (as a point z) the conditions from Lemma 3.1:

(a)
$$d(\sigma^{m+1}(x), y) \leq \limsup_{i \to +\infty} d(\sigma^m(x)_i, y)$$
 for all $y \in E$,
(b) $\limsup_{i \to +\infty} d(\sigma^{m+1}(x), \sigma^m(x)_i) \leq \alpha \cdot diam(\{\sigma^m(x)_i\}).$

Set

$$r_m = \limsup_{i \to +\infty} d(\sigma^{m+1}(x), \sigma^m(x)_i).$$

Note for each $i > j \ge 0$,

$$d(\sigma^{m}(x)_{i}, \sigma^{m}(x)_{j}) \leq k \cdot d(\sigma^{m}(x)_{i-j}, \sigma^{m}(x)) \leq \text{ (by (a))}$$

$$\leq k \cdot \limsup_{n \to +\infty} d(\sigma^{m-1}(x)_{n}, \sigma^{m}(x)_{i-j}) \qquad (3.1)$$

$$\leq k^{2} \cdot \limsup_{n \to +\infty} d(\sigma^{m-1}(x)_{n}, \sigma^{m}(x)) = k^{2} \cdot r_{m-1}.$$

Observe that

$$r_{m} = \limsup_{i \to +\infty} d(\sigma^{m+1}(x), \sigma^{m}(x)_{i}) \leq \text{ (by (b))}$$
$$\leq \alpha \cdot diam(\{\sigma^{m}(x)_{i}\}) \leq \text{ (by (3.1))}$$
$$\leq \alpha \cdot k^{2} \cdot r_{m-1} = h \cdot r_{m-1}$$

and

$$r_m \leqslant h \cdot r_{m-1} \leqslant \ldots \leqslant h^{m-1} \cdot r_1.$$

Our assumption on k leads to $h = \alpha \cdot k^2 < 1$. Hence for each $i \ge 1$,

$$d(\sigma^{m+1}(x), \sigma^m(x)) \leqslant d(\sigma^{m+1}(x), \sigma^m(x)_i) + d(\sigma^m(x)_i, \sigma^m(x)) \leqslant \text{ (by (a))}$$

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$$d(\sigma^{m+1}(x), \sigma^m(x)_i) + \limsup_{j \to +\infty} d(\sigma^{m-1}(x)_j, \sigma^m(x)_i) \le \le d(\sigma^{m+1}(x), \sigma^m(x)_i) + k \cdot \limsup_{j \to +\infty} d(\sigma^{m-1}(x)_j, \sigma^m(x)) = = d(\sigma^{m+1}(x), \sigma^m(x)_i) + k \cdot r_{m-1}.$$

Taking the limit superior as $i \to +\infty$, we get

$$d(\sigma^{m+1}(x), \sigma^m(x)) \leqslant \limsup_{i \to +\infty} d(\sigma^{m+1}(x), \sigma^m(x)_i) + k \cdot r_{m-1} \le$$

$$\leqslant r_m + k \cdot r_{m-1} \leqslant (h^{m-1} + k \cdot h^{m-2}) \cdot r_1.$$

This implies that $\{\sigma^m(x)\}_{m \ge 1}$ is Cauchy and $\sigma^m(x) \to z \in C$ as $m \to +\infty$. Next we prove that z is a fixed point of T, i.e. $z \in T(z)$. Indeed, we have (by (a))

$$d(\sigma^{m}(x), \sigma^{m}(x)_{1}) \leq \limsup_{n \to +\infty} d(\sigma^{m-1}(x)_{n}, \sigma^{m}(x)_{1}) \leq \\ \leq k \cdot \limsup_{n \to +\infty} d(\sigma^{m-1}(x)_{n}, \sigma^{m}(x)) = k \cdot r_{m-1},$$

which implies

$$d(\sigma^m(x), \sigma^m(x)_1) \leqslant k \cdot h^{m-2} \cdot r_1$$

for any $m \ge 3$. Hence $\{\sigma^m(x)_1\}$ also converges to z:

$$d(z,\sigma^m(x)_1) \leqslant d(z,\sigma^m(x)) + d(\sigma^m(x),\sigma^m(x)_1) \to 0,$$

as $m \to +\infty$. Using the uniform Lipschitz behavior of T, for any $m \ge 1$, there exists a generalized orbit $\{z_n^m\}$ of z such that

$$d(\sigma^m(x)_n, z_n^m) \leqslant k \cdot d(\sigma^m(x), z)$$

for any $n \ge 1$. In particular, we have

$$d(\sigma^{m}(x)_{1}, z_{1}^{m}) \leq k \cdot d(\sigma^{m}(x), z) \leq$$
$$\leq k \cdot \left[d(\sigma^{m}(x), \sigma^{m}(x)_{1}) + d(\sigma^{m}(x)_{1}, z) \right] \to 0$$

as $m \to +\infty$. Hence $\{z_1^m\}$ also converges to z:

$$d(z, z_1^m) \le d(z, \sigma^m(x)) + d(\sigma^m(x), \sigma^m(x)_1) + d(\sigma^m(x)_1, z_1^m) \to 0$$

as $m \to +\infty$. But $z_1^m \in T(z)$ for any $m \ge 1$ and T(z) is closed. This will force $z \in T(z)$ as claimed. \Box

In Banach spaces we have the following multi-valued version of classical Casini and Maluta's theorem [5].

Corollary 3.3. Let C be a nonempty bounded closed convex subset of a Banach space with uniform normal structure and $T: C \to C(C)$, i.e. T(x) is a nonempty closed convex subset of C, for any $x \in C$. If T is uniformly k-Lipschitzian with $k < \sqrt{N(E)}$, then T has a fixed point, i.e. there exists $x \in C$ such that $x \in T(x)$.

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4. Remarks

A. Let (M, d) be a metric space. We recall that the Lifshitz charcteristic $\kappa(M)$ is the supremum of all positive real numbers b such that there exists a > 1 such that for every $x, y \in M$ and r > 0 with d(x, y) > r there exists $z \in M$ satisfying $\overline{B}(x, br) \cap \overline{B}(y, ar) \subset \overline{B}(z, r)$. It is clear that $\kappa(M) \ge 1$. In Banach space E we denote by $\kappa_0(E)$ the infimum of the numbers $\kappa(C)$ where C is a closed convex bounded subset of E. It is known [5] that

$$\kappa_0(E) \leqslant N(E).$$

Let E_{β} , $1 \leq \beta \leq 2$, be the space l^2 renormed by

$$||x|| = \max\{||x||_2, \beta \cdot ||x||_{\infty}\},\$$

where $\|\cdot\|_2$ is the Euclidean norm and $\|\cdot\|_{\infty}$ the supremum norm. If $1 \leq \beta \leq \frac{1}{2}\sqrt{5}$, then [6], [2],

$$\kappa_0(E_\beta) = \sqrt{1 + \frac{1}{\beta^2} - \frac{2}{\beta^2}\sqrt{\beta^2 - 1}}.$$

If $\beta \ge \frac{1}{2}\sqrt{5}$ it is known [2] that $\kappa_0(E_\beta) = 1$. Since [5] $N(E_\beta) = \frac{1}{\beta}\sqrt{2}$, so $\sqrt{N(E_\beta)}$ converges to $\frac{1}{5}\sqrt[4]{1000} \approx 1.1246$ and

$$\frac{1}{2}\left(1+\sqrt{1+4\cdot N(E_{\beta})\cdot(\kappa_{0}(E_{\beta})-1)}\right)$$

converges to 1 as $\beta \nearrow \frac{1}{2}\sqrt{5} \approx 1.118$. Therefore, for β close to $\frac{1}{2}\sqrt{5}$, more precisely $\beta > 1.0556$, the constant which appears in Corollary 3.3 is strictly bigger than the constant

$$\frac{1}{2}\left(1+\sqrt{1+4\cdot N(E_{\beta})\cdot(\kappa_{0}(E_{\beta})-1)}\right)$$

which appears in the fixed point theorem for uniformly Lipschitzian mappings due to Domínguez Benavides [6] and its multi-valued version [10].

B. Metric hyperconvexity was introduced in 1956. A metric space (E, d) is called *hyperconvex* if

$$\bigcap_{\alpha \in \Gamma} B(x_{\alpha}, r_{\alpha}) \neq \emptyset$$

for any collection of closed balls $\{B(x_{\alpha}, r_{\alpha})\}_{\alpha \in \Gamma}$ such that

$$d(x_{\alpha}, x_{\beta}) \leqslant r_{\alpha} + r_{\beta}, \ \alpha, \beta \in \Gamma.$$

The space C(S) of continuous real function on a Stonian space with "supremum" norm, the classical spaces l_{∞} , L_{∞} are examples of hyperconvex spaces. Two facts are pertinent to what follows: any hyperconvex metric space is complete and N(E) = 2if E is hyperconvex, [8].

Thus, Theorem 3.2 implies the following corollary for hyperconvex spaces.

Corollary 4.1. Let (E, d) be a bounded hyperconvex metric space with property (P)and $T: E \to C(E)$, i.e. T(x) is a nonempty closed convex subset of E, for any $x \in E$. If T is uniformly k-Lipschitzian with $k < \sqrt{2}$, then T has a fixed point, i.e. there exists $x \in E$ such that $x \in T(x)$. **Remark 4.2.** In the classical Kirk's fixed point theorem, having a bounded orbit implies the existence of a fixed point. The following example of Prus [8] shows that boundedness of orbits does not imply the existence of a fixed point even for non-expansive mappings. Indeed, consider the classical Banach space l_{∞} and the map $T: l_{\infty} \to l_{\infty}$ defined by

$$T((x_n)) = (1 + LIMx_n, x_1, x_2, \ldots),$$

where LIM denotes a Banach limit. Then $||T^n x|| \leq 1 + ||x||$ and

$$||T^n x - T^n y|| = ||x - y||$$

for every $x, y \in l_{\infty}$. If $z = (z_1, z_2, \ldots) \in l_{\infty}$ satisfies Tz = z, then

$$z_1 = 1 + LIM z_n, z_2 = z_1, z_3 = z_2, \dots,$$

and hence $LIMz_n = 1 + LIMz_n$, a contradiction, which shows that $Fix(T) = \emptyset$. On the other hand, we have $T^n(0) = (1, 1, ..., 1, 0, 0, ...)$ where the first block of length n has all entries equal 1 and then 0 after that. So T has bounded orbits.

Question 4.3. Does every hyperconvex space have the property (P)?

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Received: September 22, 2016; Accepted: April 21, 2017.

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