

HYERS-ULAM STABILITY OF THE LAPLACE OPERATOR

DORIAN POPA AND IOAN RAȘA

Technical University of Cluj-Napoca, Department of Mathematics,
28 Memorandumului Street, 400114, Cluj-Napoca, Romania
E-mail: Popa.Dorian@math.utcluj.ro
Ioan.Rasa@math.utcluj.ro

Abstract. We investigate the Hyers-Ulam stability of the Laplace operator Δ and of a multiple of it, acting on suitable domains. Moreover, we obtain an explicit representation of the Hyers-Ulam constant.

Key Words and Phrases: Hyers-Ulam stability, Laplace operator, Digamma function.

2010 Mathematics Subject Classification: 39B82, 35J15, 47S07.

1. INTRODUCTION

Let A, B be normed spaces and $L : A \rightarrow B$ a linear operator. The following definition can be found in [11]; see also the references therein.

Definition 1.1. We say that L is Hyers-Ulam stable with constant $K > 0$ if for each $\varepsilon > 0$ and each $f \in A$ with $\|Lf\| \leq \varepsilon$ there exists $g \in A$ such that $Lg = 0$ and $\|f - g\| \leq K\varepsilon$.

Obviously, L is HU-stable with constant K if and only if for each $f \in A$ with $\|Lf\| \leq 1$ there exists g in the null space $N(L)$ of L such that $\|f - g\| \leq K$.

Hyers-Ulam stability is one of the main topics in functional equations theory. A functional equation is called HU-stable if for every approximate solution of the equation there exists an exact solution near it. In the last years in many papers the authors studied the HU-stability of ordinary differential equations and partial differential equations. Some of these papers deal with second order partial differential equations; for more details on stability of functional equations see [8].

In this paper we investigate the HU-stability of the Laplace operator Δ acting on a certain space of functions. The HU-stability of Δ on other spaces was studied with different methods in [4], [5], [7].

We investigate also the HU-stability of the operator $p(x)\Delta$, where

$$p(x) := \frac{1}{2^n}(1 - x_1^2 - \dots - x_n^2)$$

for all x in the unit ball of \mathbb{R}^n . This operator is related to the infinitesimal generator of a C_0 -semigroup systematically studied in [2], [3], [10] and the references given there. Moreover, we give explicit forms of the involved HU-constants for Δ and $p(x)\Delta$.

2. THE HU-STABILITY OF Δ

Let $G \subset \mathbb{R}^n$, $n \geq 1$, be an open and connected set bounded by a surface S of class C^1 . Consider the Laplace operator $\Delta = \frac{\partial^2}{\partial x_1^2} + \dots + \frac{\partial^2}{\partial x_n^2}$, acting on the space

$$D(\Delta) := \{u \in C^2(G) \cap C(\overline{G}) : \Delta u \in C^1(G) \cap C(\overline{G})\}.$$

On $C(\overline{G})$ and on its subspaces we consider the supremum norm denoted by $\|\cdot\|$.

In our approach we need the following result; for more details see [9, p. 68].

Theorem 2.1. *For each $f \in C^1(G) \cap C(\overline{G})$ there exists a unique $u \in D(\Delta)$ such that $\Delta u = f$ and $u|_S = 0$.*

Consequently $\Delta : D(\Delta) \rightarrow R(\Delta)$ is surjective, where the range of Δ is

$$R(\Delta) = C^1(G) \cap C(\overline{G}).$$

Moreover, according to Theorem 2.1 there exists a unique $q \in D(\Delta)$ such that

$$\begin{cases} \Delta q = -1 \\ q|_S = 0. \end{cases}$$

Theorem 2.2. *The operator $\Delta : D(\Delta) \rightarrow R(\Delta)$ is HU-stable with constant $\|q\|$.*

Proof. Let $f \in D(\Delta)$, $\|\Delta f\| \leq 1$. Then $\Delta f \in C^1(G) \cap C(\overline{G})$, and Theorem 2.1 guarantees the existence of $u \in D(\Delta)$ such that $\Delta u = \Delta f$ and $u|_S = 0$.

Then $\|\Delta u\| \leq 1$, which entails $\Delta(u+q) = \Delta u - 1 \leq 0$. Since $(u+q)|_S = 0$, we get $u+q \geq 0$. Similarly, $\Delta(u-q) = \Delta u + 1 \geq 0$ and $(u-q)|_S = 0$ imply $u-q \leq 0$.

So we have $-q \leq u \leq q$, i.e., $\|u\| \leq \|q\|$.

Let $g := f - u$. Then $\Delta g = 0$ and $\|f - g\| = \|u\| \leq \|q\|$, which concludes the proof. \square

In particular, if G is the unit ball of \mathbb{R}^n , then

$$q(x) = \frac{1}{2n}(1 - x_1^2 - \dots - x_n^2) \quad \text{and} \quad \|q\| = \frac{1}{2n}.$$

Consequently we have

Corollary 2.3. *If G is the unit ball of \mathbb{R}^n , then $\Delta : D(\Delta) \rightarrow R(\Delta)$ is HU-stable with constant $\frac{1}{2n}$.*

3. THE HU-STABILITY OF $p\Delta$

In this section G will be the unit ball of \mathbb{R}^n , $n \geq 1$. Consider the function

$$p(x) = \frac{1}{2n}(1 - x_1^2 - \dots - x_n^2), \quad x \in G,$$

and the operator $W := p\Delta$ with domain

$$D(W) := \{u \in C^2(G) \cap C(\overline{G}) : \Delta u \in C^1(G) \cap C(\overline{G})\}.$$

According to Theorem 2.1, the range of W is $R(W) = \{pv : v \in C^1(G) \cap C(\overline{G})\}$.

Consider the function

$$h_n(t) := \frac{2n}{t^{n-1}} \int_0^t \frac{s^{n-1}}{1-s^2} ds, \quad t \in [0, 1).$$

For $x \in G$ let $r(x) := (x_1^2 + \dots + x_n^2)^{\frac{1}{2}}$ and $\phi_n(x) := \int_{r(x)}^1 h_n(t)dt$.

Then $p(x)\Delta\phi_n(x) = -1$, and $\phi_n|_S = 0$.

Theorem 3.1. *The operator $W : D(W) \rightarrow R(W)$ is HU-stable with constant $\|\phi_n\|$. Proof.* Let $f \in D(W)$, $\|Wf\| \leq 1$. Then $p\Delta f = Wf \in R(W)$, so that $p\Delta f = pv$, with $v \in C^1(G) \cap C(\bar{G})$. This entails $\Delta f = v$, and Theorem 2.1 guarantees the existence of $u \in C^2(G) \cap C(\bar{G})$ with $\Delta u = v$ and $u|_S = 0$. Now $p\Delta f = p\Delta u$, i.e., $\|Wu\| = \|Wf\| \leq 1$.

In particular, $p(x)\Delta u(x) \geq -1 = p(x)\Delta\phi_n(x)$, so that $\Delta(u - \phi_n) \geq 0$. Since $(u - \phi_n)|_S = 0$, we get $u - \phi_n \leq 0$. Similarly we deduce $u + \phi_n \geq 0$, and finally, $-\phi_n \leq u \leq \phi_n$. This means that $\|u\| \leq \|\phi_n\|$.

Now let $g := f - u$. Then $Wg = Wf - Wu = p\Delta f - p\Delta u = 0$, i.e., $Wg = 0$ and $\|f - g\| = \|u\| \leq \|\phi_n\|$. So the proof is finished. \square

Now let's evaluate the constant $\|\phi_n\|$. Since h_n is nonnegative, we have

$$\|\phi_n\| = \int_0^1 h_n(t)dt,$$

and it is easy to infer that

$$h_n(t) = 2n \sum_{k=0}^{\infty} \frac{t^{2k+1}}{n + 2k}, n \geq 1.$$

Therefore,

$$\|\phi_n\| = n \sum_{k=0}^{\infty} \frac{1}{(k + 1)(n + 2k)}, n \geq 1.$$

It follows immediately that

$$\|\phi_1\| = \log 4, \quad \|\phi_2\| = \frac{\pi^2}{6}.$$

Let $n \geq 3$. By using [1, (6.3.16)] with $z = \frac{n}{2} - 1$ we get

$$\psi\left(\frac{n}{2}\right) = -\gamma + (n - 2) \sum_{k=0}^{\infty} \frac{1}{(k + 1)(n + 2k)},$$

where ψ is the Digamma function and $\gamma = -\psi(1)$ is Euler's constant. So we have

$$\|\phi_n\| = \frac{n}{n - 2}(\psi\left(\frac{n}{2}\right) + \gamma).$$

According to [1, (6.3.4)] and [1, (6.3.6)],

$$\psi\left(n + \frac{1}{2}\right) = 2 \sum_{k=1}^n \frac{1}{2k - 1} - \log 4 - \gamma,$$

$$\psi(n) = \sum_{k=1}^{n-1} \frac{1}{k} - \gamma.$$

Therefore we get the following result.

Theorem 3.2. *A HU-constant of W is $\|\phi_n\|$, where:*

$$\|\phi_1\| = \log 4, \quad \|\phi_2\| = \frac{\pi^2}{6},$$

$$\|\phi_{2m}\| = \frac{m}{m-1} \sum_{k=1}^{m-1} \frac{1}{k}, \quad m \geq 2,$$

$$\|\phi_{2m+1}\| = \frac{2m+1}{2m-1} \left(2 \sum_{k=1}^m \frac{1}{2k-1} - \log 4 \right), \quad m \geq 1.$$

Remark 3.3. It is known (see, e.g., [6]) that the infimum of the set of HU-constants for an operator is not necessarily a HU-constant. It would be interesting to find, for Δ and $p(x)\Delta$, the corresponding infima and to see if they are HU-constants.

REFERENCES

- [1] M. Abramowitz, I.A. Stegun, *Handbook of Mathematical Functions and Formulas*, Graphs and Mathematical Tables, New-York, Dover, 1972.
- [2] F. Altomare and M. Campiti, *Korovkin-type Approximation Theory and its Applications*, W. De Gruyter, Berlin - New York, 1994.
- [3] F. Altomare, M. Cappelletti Montano, V. Leonessa, I. Rașa, *Markov Operators, Positive Semigroups and Approximation Processes*, W. De Gruyter Studies in Mathematics, Vol. 61, 2014.
- [4] Sz. András, A.R. Mészáros, *Ulam-Hyers stability of elliptic partial differential equations in Sobolev spaces*, Appl. Math. Comput., **229**(2014), 131-138.
- [5] E. Gselmann, *Stability properties in some classes of second order partial differential equations*, Results Math., **65**(2014), 95-103.
- [6] O. Hatori, K. Kobayasi, T. Miura, H. Takagi, S.E. Takahasi, *On the best constant of Hyers-Ulam stability*, J. Nonlinear Convex Anal., **5**(2004), 387-393.
- [7] B. Hegyi, S.-M. Jung, *On the stability of Laplace's equation*, Appl. Math. Lett., **26**(2013), 549-552.
- [8] D.H. Hyers, G. Isac, Th. M. Rassias, *Stability of Functional Equations in Several Variables*, Birkhäuser, Basel, 1998.
- [9] R. Precup, *Linear and semilinear partial differential equations*, W. De Gruyter, 2013.
- [10] I. Rașa, *Positive operators, Feller semigroups and diffusion equations associated with Altomare projections*, Conf. Sem. Mat. Univ. Bari, **284**(2002), 26 pp.
- [11] H. Takagi, T. Miura, S.-E. Takahasi, *Essential norms and stability constants of weighted composition operators on $C(X)$* , Bull. Korean Math. Soc., **40**(2003), 583-591.

Received: May 8, 2015; Accepted: July 2, 2015.