# CONVERGENCE ANALYSIS OF COMMON SOLUTION OF CERTAIN NONLINEAR PROBLEMS 

F.U. OGBUISI* AND O.T. MEWOMO**<br>*School of Mathematics, Statistics and Computer Science<br>University of KwaZulu-Natal Durban, South Africa<br>E-mail: 215082189@stu.ukzn.ac.za fudochukwu@yahoo.com<br>**School of Mathematics, Statistics and Computer Science<br>University of KwaZulu-Natal<br>Durban, South Africa<br>E-mail:mewomoo@ukzn.ac.za


#### Abstract

We introduce an iterative algorithm for approximating a common fixed point of an infinite family of left Bregman strongly nonexpansive mappings which is also a common solution of a finite system of generalized mixed equilibrium problems and a common zero of a finite family of maximal monotone operators in a reflexive real Banach space. A strong convergence theorem is also proved for finding an element in the intersection of the set of solution of a fixed point problem for infinite family of left Bregman strongly nonexpansive mappings, the set of solutions of a system of generalized mixed equilibrium problems and the set of zero points of a finite family of maximal monotone operators in a reflexive real Banach space. The result of this paper complement many related and important results in the literature. Key Words and Phrases: Bregman distance, Bregman projection, maximal monotone operator, generalized mixed equilibrium problem, resolvent, Legendre function, reflexive real Banach space, zero point. 2010 Mathematics Subject Classification: 47H06, 47H09, 47J05, 47J25


## 1. Introduction

Let $E$ be a reflexive real Banach space and $C$ a nonempty, closed and convex subset of $E$. Throughout this paper, we shall denote the dual space of $E$ by $E^{*}$. The norm and the duality pairing between $E$ and $E^{*}$ are respectively denoted by $\|$.$\| and \langle.,$.$\rangle .$ $\mathbb{R}$ stands for the set of real numbers.
Let $T: C \rightarrow C$ be a mapping, a point $x \in C$ is called a fixed point of $T$ if $T x=x$. The set of fixed points of $T$ is denoted by $F(T)$.
Let $g: C \times C \rightarrow \mathbb{R}$ be a bifunction, $\varphi: C \rightarrow \mathbb{R} \cup\{+\infty\}$ be a function and $B: C \rightarrow E^{*}$ be a nonlinear mapping. The Generalized mixed equilibrium problem is to find $u \in C$ such that

$$
\begin{equation*}
g(u, y)+\langle B u, y-u\rangle+\varphi(y)-\varphi(u) \geq 0, \forall y \in C \tag{1.1}
\end{equation*}
$$

Denote the set of solutions of the problem (1.1) by $\operatorname{GMEP}(g, \varphi, B)$. That is

$$
G M E P(g, \varphi, B)=\{u \in C: g(u, y)+\langle B u, y-u\rangle+\varphi(y)-\varphi(u) \geq 0, \forall y \in C\} .
$$

If $B=0$, then the generalized mixed equilibrium problem (1.1) reduces to the following mixed equilibrium problem, find $u \in C$ such that

$$
g(u, y)+\varphi(y)-\varphi(u) \geq 0, \forall y \in C .
$$

If $\varphi=0$, then the generalized mixed equilibrium problem (1.1) becomes the generalized equilibrium problem, find $u \in C$ such that

$$
g(u, y)+\langle B u, y-u\rangle \geq 0, \forall y \in C
$$

Again if $B=\varphi=0$, then the generalized mixed equilibrium problem (1.1) becomes the equilibrium problem, find $u \in C$ such that

$$
g(u, y) \geq 0, \forall y \in C
$$

Equilibrium problems and their generalizations are well known to have been important tools for solving problems arising in the fields of linear or nonlinear programming, variational inequalities, complementary problems, optimization problems, fixed point problems and have been widely applied to physics, structural analysis, management sciences and economics, etc (see, for example [9, 26, 40, 41]).

In solving equilibrium problem (1.1), the bifunction $g$ is said to satisfy the following conditions:
(A1) $g(x, x)=0$ for all $x \in C$;
(A2) $g$ is monotone, i.e., $g(x, y)+g(y, x) \geq 0$ for all $x, y \in C$;
(A3) for each $x, y \in C, \lim _{t \rightarrow 0} g(t z+(1-t) x ; y) \leq g(x ; y)$;
(A4) for each $x \in C ; y \mapsto g(x, y)$ is convex and lower semicontinuous.
Cholamjiak and Suantai [25] proposed a hybrid iterative scheme for finding a common element in the solution set of system of equilibrium problems and the common fixed points set of an infinitely countable family of quasi-nonexpansive mappings and prove the following strong convergence theorem.
Theorem 1.1. Let $E$ be a uniformly convex and uniformly smooth Banach space, and let $C$ be a nonempty, closed and convex subset of $E$. Let $\left\{f_{j}\right\}_{j=1}^{M}$ be bifunctions from $C \times C$ to $\mathbb{R}$ which satisfies conditions $(A 1)-(A 4)$, and let $\left\{T_{i}\right\}_{i=1}^{\infty}$ be an infinitely countable family of closed and relatively quasi-nonexpansive mappings from $C$ into itself. Assume that $F:=\left(\cap_{i=1}^{\infty} F\left(T_{i}\right)\right) \cap\left(\cap_{j=1}^{M} E P\left(f_{j}\right)\right) \neq \emptyset$. For any initial point $x_{0} \in E$ with $x_{1}=\Pi_{C_{0}} x_{0}$ and $C_{1}=C$, define the sequence $\left\{x_{n}\right\}$ as follows:

$$
\left\{\begin{array}{l}
y_{n, i}=J^{-1}\left(\alpha_{n} J x_{n}+\left(1-\alpha_{n}\right) J T_{i} x_{n}\right)  \tag{1.2}\\
u_{n, i}=T_{r_{M}, n}^{f_{M}} T_{r_{M-1, n}}^{f_{M-1}} \ldots T_{r_{1, n}}^{f_{1}} y_{n, i} \\
C_{n+1}=\left\{z \in C_{n}: \sup _{i \geq 1} \phi\left(z, u_{n, i}\right) \leq \phi\left(z, x_{n}\right)\right\} \\
x_{n+1}=\Pi_{C_{n+1}} x_{0}, n \geq 0
\end{array}\right.
$$

Assume that $\left\{\alpha_{n}\right\}$ and $\left\{r_{j, n}\right\}$ for $j=1,2, \ldots, M$ are sequences which satisfy the following conditions:
(B1) $\lim \sup _{n \rightarrow \infty} \alpha_{n}<1$,
(B2) $\liminf _{n \rightarrow \infty} r_{j, n}>0$.
Then the sequence $\left\{x_{n}\right\}$ converges strongly to $\Pi_{F} x_{0}$.

Many authors have contributed in developing efficient and implementable algorithms for solving equilibrium problems and some of their generalizations, (see, for example, $[1,26,33]$ and the references therein).

Let $A: E \rightarrow 2^{E^{*}}$ be a set valued mapping. The domain of $A$ is the set $\operatorname{dom} A=$ $\{x \in E: A x \neq \emptyset\}$ and the graph of $A$ is the set $G(A)=\left\{\left(x, x^{*}\right) \in E \times E^{*}: x^{*} \in A x\right\}$. A set-valued mapping $A$ is said to be monotone if $\left\langle x^{*}-y^{*}, x-y\right\rangle \geq 0$ whenever $\left(x, x^{*}\right),\left(y, y^{*}\right) \in G(A)$. If in addition that the graph of $A$ is not contained in the graph of any other monotone operator, then $A$ is said to be a maximal monotone operator on $E$. It is well known that if $A$ is maximal monotone, then the set $A^{-1}\left(0^{*}\right)=\{z \in$ $\left.E: 0^{*} \in A z\right\}$ is closed and convex.
The problem of finding the zeroes of a maximal monotone operator is very vital in optimization, because it can be reduced to a convex minimization problem and variational inequality problem.

Rockafeller [49], motivated by the work of Martinet [35], introduced in a Hilbert space $H$ the following proximal point iterative algorithm:

$$
\left\{\begin{array}{l}
x_{1}=x \in H  \tag{1.3}\\
x_{n+1}=J_{\lambda_{n}} x_{n}, \forall n \geq 1
\end{array}\right.
$$

where $\left\{\lambda_{n}\right\} \subset(0, \infty)$ and $J_{\lambda_{n}}$ is the resolvent of $A$ defined by $J_{\lambda}=(I+\lambda A)^{-1}$ for all $\lambda>0$, and $A$ is a maximal monotone operator on $H$. He proved that the sequence $\left\{x_{n}\right\}$ generated by (1.3) converges weakly to an element in $A^{-1}(0)$ provided $\liminf _{n \rightarrow \infty} \lambda_{n}>0$.
A weak convergence result was also obtained by Kamimura and Takahashi [30] in a real Hilbert space with the following iterative scheme:

$$
x_{n+1}=\alpha_{n} x_{n}+\left(1-\alpha_{n}\right) J_{\lambda_{n}} x_{n}, \forall n \geq 1
$$

where $\left\{\alpha_{n}\right\} \subset[0,1]$ and $\left\{\lambda_{n}\right\} \subset(0, \infty)$ under some suitable conditions on $\left\{\lambda_{n}\right\} \subset$ $(0, \infty)$.
Inspired by the result of Kamimura and Takahashi [30], Kohsaka and Takahashi [32], in reflexive Banach space introduced the following iterative algorithm:

$$
x_{n+1}=\nabla f^{*}\left(\alpha_{n} \nabla f\left(x_{n}\right)+\left(1-\alpha_{n}\right) \nabla f\left(J_{\lambda_{n}} x_{n}\right)\right), \forall n \geq 1,
$$

where $\left\{\alpha_{n}\right\} \subset[0,1]$ and $\left\{\lambda_{n}\right\} \subset(0, \infty), f: E \rightarrow \mathbb{R}$ is a Bregman function and $J_{\lambda}=(\nabla f+\lambda A)^{-1} \nabla f$ for all $\lambda>0$. They obtained a weak convergence result with the proposed algorithm.
For some other existing results for finding zero points of maximal monotone operators see for example $[13,14,24,29,38,44,50]$ and some of the references therein.

In 1967, Bregman [12] introduced a nice and effective method for using the so called Bregman distance function $D_{f}$ (see Definition 2.1 in Section 2) in the process of designing and analysing feasibility and optimization algorithms. This opened a growing area of research in which Bregman's technique is applied in various ways in order to design and analyze iterative algorithms for solving equilibria, for approximating equilibria, and for computing fixed points of nonlinear mappings (see, e.g., $[2,3,4,5,8,12,16,17,19,20,21,27,31,42,43,44,45,46,47,48,51,23]$ and the references therein).

Inspired and motivated by the researches going on in this direction, we propose an iterative algorithm for approximating a fixed point of an infinite family of left Bregman strongly nonexpansive mappings, which is a common solution to a finite system of equilibrium problems and also a zero point of a finite family of maximal monotone operators in a reflexive real Banach space and prove its strong convergence in this work.

## 2. Preliminaries

In this section, we present the basic notions and facts that are needed in the sequel. The pairing $\langle\xi, x\rangle$ is defined by the action of $\xi \in E^{*}$ at $x \in E$, that is, $\langle\xi, x\rangle:=\xi(x)$. The domain of a convex function $f: E \rightarrow \mathbb{R}$ is defined to be

$$
\operatorname{dom} f:=\{x \in E: f(x)<+\infty\}
$$

When $\operatorname{dom} f \neq \emptyset$, we say that $f$ is proper. The Fenchel conjugate function of $f$ is the convex function $f^{*}: E^{*} \rightarrow \mathbb{R}$ defined by

$$
f^{*}(\xi)=\sup \{\langle\xi, x\rangle-f(x): x \in E\} .
$$

It is not difficult to check that whenever $f$ is proper and lower semicontinuous, so is $f^{*}$. The function $f$ is said to be cofinite if $\operatorname{dom} f^{*}=E^{*}$.
Let $x \in \operatorname{int}(\operatorname{dom} f)$, for any $y \in E$, we define the directional derivative of f at $x$ by

$$
\begin{equation*}
f^{o}(x, y):=\lim _{t \rightarrow 0^{+}} \frac{f(x+t y)-f(x)}{t} \tag{2.1}
\end{equation*}
$$

If the limit as $t \rightarrow 0^{+}$in (2.1) exists for each $y$, then the function $f$ is said to be Gâteaux differentiable at $x$. In this case, the gradient of $f$ at $x$ is the linear function $\nabla f(x)$, which is defined by $\langle\nabla f(x), y\rangle:=f^{o}(x, y)$ for all $y \in E$ (see [22]). The function $f$ is said to be Gâteaux differentiable if it is Gâteaux differentiable at each $x \in \operatorname{int}(\operatorname{domf})$. When the limit as $t \rightarrow 0$ in (2.1) is attained uniformly for any $y \in E$ with $\|y\|=1$, we say that $f$ is Fréchet differentiable at $x$. Throughout this paper, $f: E \rightarrow \mathbb{R}$ is always an admissible function, that is, a proper, lower semicontinuous, convex and Gâteaux differentiable function. Under these conditions we know that $f$ is continuous in $\operatorname{int}(\operatorname{domf})$ (see [6]).
The function $f$ is said to be Legendre if it satisfies the following two conditions.
(L1) $\operatorname{int}(\operatorname{domf}) \neq \emptyset$, and the subdifferential $\partial f$ is single-valued on its domain.
(L2) $\operatorname{int}\left(\operatorname{dom} f^{*}\right) \neq \emptyset$, and $\partial f^{*}$ is single-valued on its domain.
The class of Legendre functions in infinite dimensional Banach spaces was first introduced and studied by Bauschke, Borwein and Combettes in [6]. Their definition is equivalent to conditions (L1) and (L2) because the space $E$ is assumed to be reflexive (see [6], Theorems 5.4 and 5.6, page 634). It is well known that in reflexive Banach spaces $\nabla f=\left(\nabla f^{*}\right)^{-1}$ (see [10], page 83). When this fact is combined with conditions (L1) and (L2), we obtain

$$
\operatorname{ran} \nabla f=\operatorname{dom} \nabla f^{*}=\operatorname{int}(\operatorname{dom} f)^{*} \text { and } \operatorname{ran} \nabla f^{*}=\operatorname{dom} \nabla f=\operatorname{int}(\operatorname{domf}) .
$$

It also follows that $f$ is Legendre if and only if $f^{*}$ is Legendre (see [6], Corollary 5.5, page 634) and that the functions $f$ and $f^{*}$ are Gateaux differentiable and strictly convex in the interior of their respective domains.

When the Banach space E is smooth and strictly convex, in particular, a Hilbert space, the function $\left(\frac{1}{p}\right)\|\cdot\|^{p}$ with $p \in(1, \infty)$ is Legendre (cf. [6], Lemma 6.2, page 639). For examples and more information regarding Legendre functions, see, for instance, $[5,6]$.
Definition 2.1. The bifunction $D_{f}: \operatorname{domf} \times \operatorname{int}(\operatorname{domf}) \rightarrow[0 ;+\infty)$ defined by

$$
\begin{equation*}
D_{f}(y, x):=f(y)-f(x)-\langle\nabla f(x), y-x\rangle \tag{2.2}
\end{equation*}
$$

is called the Bregman distance (cf. [12, 22]).
The Bregman distance does not satisfy the well-known properties of a metric, but it does have the following important property, which is called the three point identity: for any $x \in \operatorname{domf}$ and $y, z \in \operatorname{int}(\operatorname{domf})$

$$
\begin{equation*}
D_{f}(x, y)+D_{f}(y, z)-D_{f}(x, z)=\langle\nabla f(z)-\nabla f(y), x-y\rangle . \tag{2.3}
\end{equation*}
$$

The modulus of total convexity of $f$ is the bifunction $v_{f}: \operatorname{int}(\operatorname{dom} f) \times[0,+\infty) \rightarrow$ $[0,+\infty]$ which is defined by

$$
v_{f}(x, t):=\inf \left\{D_{f}(y, x): y \in \operatorname{dom} f,\|y-x\|=t\right\rangle
$$

The function $f$ is said to be totally convex at a point $x \in \operatorname{int}(\operatorname{dom} f)$ if $v_{f}(x ; t)>0$ whenever $t>0$. The function $f$ is said to be totally convex when it is totally convex at every point $x \in \operatorname{int}(\operatorname{dom} f)$. This property is less stringent than uniform convexity (see [16], Section 2.3, page 92). Examples of totally convex functions can be found, for instance, in $[11,16,19]$.
We remark that $f$ is totally convex on bounded subsets if and only if $f$ is uniformly convex on bounded subsets (see [19], Theorem 2.10, page 9).
The Bregman projection (cf. [12]) with respect to $f$ of $x \in \operatorname{int}(\operatorname{domf})$ onto a nonempty, closed and convex set $C \subset \operatorname{int}(\operatorname{domf})$ is defined as the necessarily unique vector $\operatorname{Proj}_{C}^{f}(x) \in C$ which satisfies

$$
\begin{equation*}
D_{f}\left(\operatorname{Proj}_{C}^{f}(x), x\right)=\inf \left\{D_{f}(y, x): y \in C\right\} \tag{2.4}
\end{equation*}
$$

Let $C$ be a nonempty, closed, and convex subset of $E$. Let $f: E \rightarrow \mathbb{R}$ be a Gâteaux differentiable and totally convex function and let $x \in E$. It is known from [19] that $z=\operatorname{Proj}_{C}^{f} x$ if and only if $\langle\nabla f(x)-\nabla f(z), y-z\rangle \leq 0$ for all $y \in C$. We also have

$$
\begin{equation*}
D_{f}\left(y, \operatorname{Proj}_{C}^{f}(x)\right)+D_{f}\left(\operatorname{Proj}_{C}^{f}(x), x\right) \leq D_{f}(y, x), \forall x \in E, y \in C \tag{2.5}
\end{equation*}
$$

Similar to the metric projection in Hilbert spaces, the Bregman projection with respect to totally convex and Gâteaux differentiable functions has a variational characterization (cf. [19], Corollary 4.4, page 23).
Proposition 2.2. (see [43]) (Characterization of Bregman Projections) Suppose that $f: E \rightarrow \mathbb{R}$ is totally convex and Gâteaux differentiable in $\operatorname{int}(\operatorname{domf})$. Let $x \in$ $\operatorname{int}(\operatorname{domf})$ and let $C \subset \operatorname{int}(\operatorname{domf})$ be a nonempty, closed and convex set. If $\hat{x} \in C$, then the following conditions are equivalent.
(i) The vector $\hat{x}$ is the Bregman projection of $x$ onto $C$ with respect to $f$.
(ii) The vector $\hat{x}$ is the unique solution of the variational inequality

$$
\langle\nabla f(x)-\nabla f(z), z-y\rangle \geq 0, \quad \forall y \in C
$$

(iii) The vector $\hat{x}$ is the unique solution of the inequality

$$
D_{f}(y, z)+D_{f}(z, x) \leq D_{f}(y, x) \forall y \in C .
$$

Recall that the function $f$ is said to be sequentially consistent [7] if for any two sequences $\left\{x_{n}\right\}$ and $\left\{y_{n}\right\}$ in $E$ such that the first is bounded,

$$
\begin{equation*}
\lim _{n \rightarrow \infty} D_{f}\left(x_{n}, y_{n}\right)=0 \Rightarrow \lim _{n \rightarrow \infty}\left\|x_{n}-y_{n}\right\|=0 \tag{2.6}
\end{equation*}
$$

The resolvent of a bifunction $g: C \times C \rightarrow \mathbb{R}$ (see, [45]) is the operator $\operatorname{Res}_{g}^{f}: E \rightarrow C$ defined by

$$
\begin{equation*}
\operatorname{Res}_{g}^{f}(x)=\{z \in C: g(z, y)+\langle\nabla f(z)-\nabla f(x), y-z\rangle \geq 0 \forall y \in C\} \tag{2.7}
\end{equation*}
$$

For any $x \in E$, there exists $z \in C$ such that $z=\operatorname{Res}_{g}^{f}(x)$, see [45].
Let $C$ be a convex subset of $\operatorname{int}(\operatorname{domf})$ and let $T$ be a self-mapping of $C$. A point $p \in C$ is said to be an asymptotic fixed point of $T$ if $C$ contains a sequence $\left\{x_{n}\right\}_{n=0}^{\infty}$ which converges weakly to $p$ and $\lim _{n \rightarrow \infty}\left\|x_{n}-T x_{n}\right\|=0$. The set of asymptotic fixed points of $T$ is denoted by $\hat{F}(T)$.

Recall that the Bregman distance is not symmetric, we define the following operators.
Definition 2.3. A mapping $T$ with a nonempty asymptotic fixed point set is said to be:
(i) left Bregman strongly nonexpansive (see [37]) with respect to a nonempty $\hat{F}(T)$ if

$$
D_{f}(p, T x) \leq D_{f}(p, x) \forall x \in C, p \in \hat{F}(T)
$$

and if whenever $\left\{x_{n}\right\} \subset C$ is bounded, $p \in \hat{F}(T)$ and

$$
\lim _{n \rightarrow \infty}\left(D_{f}\left(p, x_{n}\right)-D_{f}\left(p, T x_{n}\right)\right)=0
$$

it follows that

$$
\lim _{n \rightarrow \infty} D_{f}\left(T x_{n}, x_{n}\right)=0
$$

According to Martín-Márquez et al. [36], a left Bregman strongly nonexpansive mapping $T$ with respect to a nonempty $\hat{F}(T)$ is called strictly left Bregman strongly nonexpansive mapping.
(ii) An operator $T: C \rightarrow \operatorname{int}(\operatorname{dom} f)$ is said to be left Bregman firmly nonexpansive (L-BFNE) if

$$
\langle\nabla f(T x)-\nabla f(T y), T x-T y\rangle \leq\langle\nabla f(x)-\nabla f(y), T x-T y\rangle
$$

for any $x, y \in C$, or equivalently,

$$
D_{f}(T x, T y)+D_{f}(T y, T x)+D_{f}(T x, x)+D_{f}(T y, y) \leq D_{f}(T x, y)+D_{f}(T y, x) .
$$

See $[7,11,46]$, for more information and examples of L-BFNE operators (operators in this class are also called $D_{f}$-firm and BFNE). For two recent studies of the existence and approximation of fixed points of left Bregman firmly nonexpansive operators, see [37, 46]. It is also known that if $T$ is left Bregman firmly nonexpansive and $f$ is Legendre function which is bounded, uniformly Fréchet differentiable and totally convex on bounded subsets of $E$, then $F(T)=\hat{F}(T)$ and $F(T)$ is closed and convex
(see [46]). It also follows that every left Bregman firmly nonexpansive mapping is left Bregman strongly nonexpansive with respect to $F(T)=\hat{F}(T)$.

Let $V_{f}: E \times E^{*} \rightarrow[0, \infty)$ associated with $f$ be defined by

$$
V_{f}\left(x, x^{*}\right)=f(x)-\left\langle x^{*}, x\right\rangle+f^{*}\left(x^{*}\right), \forall x \in E, x^{*} \in E^{*} .
$$

Observe that $V_{f}$ is nonnegative and $V_{f}\left(x, x^{*}\right)=D_{f}\left(x, \nabla f^{*}\left(x^{*}\right)\right), \forall x \in E, x^{*} \in E^{*}$.
Let $f: E \rightarrow \mathbb{R}$ be a convex, Legendre and Gâteaux differentiable function. In addition, if $f: E \rightarrow(-\infty ;+\infty]$ is a proper lower semi-continuous function, then $f^{*}: E^{*} \rightarrow(-\infty,+\infty]$ is a proper weak ${ }^{*}$ lower semi-continuous and convex function (see [39]). Hence $V_{f}$ is convex in the second variable. Thus, for all $z \in E$,

$$
\begin{equation*}
D_{f}\left(z, \nabla f^{*}\left(\sum_{i=1}^{N} t_{i} \nabla f\left(x_{i}\right)\right) \leq \sum_{i=1}^{N} t_{i} D_{f}\left(z, x_{i}\right)\right. \tag{2.8}
\end{equation*}
$$

where $\left\{x_{i}\right\}_{i=1}^{N} \subset E$ and $\left\{t_{i}\right\} \subset(0,1)$ with $\sum_{i=1}^{N} t_{i}=1$.
Let $A$ be a maximal monotone operator, the resolvent of $A$ denoted by $\operatorname{Res}_{A}^{f}: E \rightarrow 2^{E}$, is defined as follows [7]:

$$
\operatorname{Res}_{A}^{f}(x)=(\nabla f+A)^{-1} \circ \nabla f(x)
$$

It is known that $F\left(\operatorname{Res}_{A}^{f}\right)=A^{-1}\left(0^{*}\right)$, and $\operatorname{Res}_{A}^{f}$ is single valued (see [7]). If $f$ is Legendre function which is bounded, uniformly Fréchet differentiable on bounded subsets of $E$, then $\hat{F}\left(\operatorname{Res}_{A}^{f}\right)=F\left(\operatorname{Res}_{A}^{f}\right)$ (see [7]). The Yosida approximation $A_{\lambda}$ : $E \rightarrow E, \lambda>0$ is also defined by

$$
A_{\lambda}(x)=\frac{1}{\lambda}\left(\nabla f(x)-\nabla f\left(\operatorname{Res}_{\lambda A}^{f}(x)\right)\right)
$$

for all $x \in E$. From Proposition 2.7 [44], it is known that $\left.\left(\operatorname{Res}_{\lambda A}^{f}(x)\right), A_{\lambda}(x)\right) \in G(A)$, and $0^{*} \in A x$ if and only if $0^{*} \in A_{\lambda} x$ for all $x \in E$ and $\lambda>0$.

The following lemmas are very useful in establishing our main results.
Lemma 2.4. (Reich and Sabach [43]) If $f: E \rightarrow \mathbb{R}$ is uniformly Fréchet differentiable and bounded on bounded subsets of $E$, then $\nabla f$ is uniformly continuous on bounded subsets of $E$ from the strong topology of $E$ to the strong topology of $E^{*}$.
Lemma 2.5. (Butnariu and Iusem [16]) The function $f$ is totally convex on bounded sets if and only if it is sequentially consistent.
Lemma 2.6. (Reich and Sabach [44]) Let $f: E \rightarrow \mathbb{R}$ be a Gâteaux differentiable and totally convex function. If $x_{0} \in E$ and the sequence $\left\{D_{f}\left(x_{n}, x_{0}\right)\right\}_{n=1}^{\infty}$ is bounded, then the sequence $\left\{x_{n}\right\}_{n=1}^{\infty}$ is also bounded.
Lemma 2.7. (Reich and Sabach [45]) Let $f: E \rightarrow(-\infty,+\infty)$ be a coercive and Gâteaux differentiable function. Let $C$ be a closed and convex subset of $E$. If the bifunction $g: C \times C \rightarrow \mathbb{R}$ satisfies conditions (A1)-(A4), then,

1. Res $_{g}^{f}$ is single-valued;
2. Res $_{g}^{f}$ is a Bregman firmly nonexpansive mapping;
3. $F\left(\right.$ Res $\left._{g}^{f}\right)=E P(g)$;
4. $E P(g)$ is a closed and convex subset of $C$;
5. for all $x \in E$ and $q \in F\left(\operatorname{Res}_{g}^{f}\right)$,

$$
D_{f}\left(q, \operatorname{Res}_{g}^{f}(x)\right)+D_{f}\left(\operatorname{Res}_{g}^{f}(x), x\right) \leq D_{f}(q, x)
$$

Lemma 2.8. ( $\mathrm{Xu}[53])$ Let $\left\{a_{n}\right\}$ be a sequence of nonnegative real numbers satisfying the following relations:

$$
a_{n+1} \leq\left(1-\alpha_{n}\right) a_{n}+\alpha_{n} \sigma_{n}+\gamma_{n}, \quad n \geq 0
$$

where,
(i) $\left\{\alpha_{n}\right\} \subset[0,1], \sum \alpha_{n}=\infty$;
(ii) $\limsup \sigma_{n} \leq 0$;
(iii) $\gamma_{n} \geq 0(n \geq 0), \sum \gamma_{n}<\infty$.

Then $\left\{a_{n}\right\} \rightarrow 0$, as $n \rightarrow \infty$.
Lemma 2.9. (Mainge [34]) Let $\left\{a_{n}\right\}$ be a sequence of real numbers such that there exists a subsequence $\left\{n_{i}\right\}$ of $\{n\}$ such that $a_{n_{i}}<a_{n_{i}+1}$ for all $i \in \mathbb{N}$. Then there exists a nondecreasing sequence $\left\{m_{k}\right\} \subset \mathbb{N}$ such that $m_{k} \rightarrow \infty$ and the following properties are satisfied by all (sufficiently large) numbers $k \in \mathbb{N}$ :

$$
a_{m_{k}} \leq a_{m_{k}+1} \text { and } a_{k} \leq a_{m_{k}+1}
$$

In fact, $m_{k}=\max \left\{j \leq k: a_{j}<a_{j+1}\right\}$.
Lemma 2.10. (Suantai et al.[52]) Let $E$ be a reflexive real Banach space. Let $C$ be a nonempty, closed and convex function of $E$. Let $f: E \rightarrow \mathbb{R}$ be a Gâteaux differentiable and totally convex function. Suppose $T$ is a left Bregman strongly nonexpansive mappings of $C$ into $E$ such that $F(T)=\hat{F}(T) \neq 0$. If $\left\{x_{n}\right\}_{n=0}^{\infty}$ is bounded sequence such that $x_{n}-T x_{n} \rightarrow 0$ and $z:=\overleftarrow{\operatorname{P}} \operatorname{roj}_{\Omega}^{f} u$, then

$$
\limsup _{n \rightarrow \infty}\left\langle x_{n}-z, \nabla f(u)-\nabla f(z)\right\rangle \leq 0
$$

Lemma 2.11. ([44]) Let $A: E \rightarrow 2^{E^{*}}$ be a maximal monotone operator such that $A^{-1}\left(0^{*}\right)=\emptyset$. Then

$$
D_{f}\left(p, \operatorname{Res}_{\lambda A}^{f}(x)+D_{f}\left(\operatorname{Res}_{\lambda A}^{f}(x), x\right) \leq D_{f}(p, x)\right.
$$

for all $\lambda>0, p \in A^{-1}\left(0^{*}\right)$ and $x \in E$.

## 3. Main Results

Theorem 3.1. Let $E$ be a reflexive real Banach space and $C$ a nonempty, closed and convex subset of $E$. Let $\left\{T_{j}\right\}_{j=1}^{\infty}$ be an infinite family of left Bregman strongly nonexpasive mappings from $C$ into itself and $F\left(T_{j}\right)=\hat{F}\left(T_{j}\right), \forall j \geq 1$. Let $g_{k}$ : $C \times C \rightarrow \mathbb{R},(k=1,2, \ldots, N)$ be bifunctions satisfying conditions $(A 1)-(A 4)$. Let $B_{k}: E \rightarrow E^{*},(k=1,2, \ldots, N)$ be continuous and monotone mappings, $\varphi_{k}: C \rightarrow$ $\mathbb{R} \cup\{+\infty\},(k=1,2, \ldots, N)$ be proper lower semicontinuous and convex functions. Let $f: E \rightarrow \mathbb{R}$ be strongly coercive Legendre function which is bounded, uniformly Fréchet differentiable and totally convex on bounded subsets of $E$ such that $C \subset$ $\operatorname{int}(\operatorname{domf})$ and $A_{i}: E \rightarrow 2^{E^{*}}(i=1,2, \ldots, N)$ be maximal monotone operators, such
that $\Omega:=\cap_{j=1}^{\infty} F\left(T_{j}\right) \cap\left(\cap_{k=1}^{N} E P\left(G_{k}\right) \cap\left(\cap_{i=1}^{N} A_{i}^{-1}(0)\right) \neq \emptyset\right.$. Then the sequence $\left\{x_{n}\right\}$ generated for arbitrary $u, x_{1} \in E$ by

$$
\left\{\begin{array}{l}
y_{n}=\operatorname{Res}{\underset{\lambda_{n}^{N} A_{N}}{f} \circ \operatorname{Res}_{\lambda_{n}^{N-1} A_{N-1}}^{f} \circ \cdots \circ \operatorname{Res}_{\lambda_{n}^{2} A_{2}}^{f} \circ \operatorname{Res}_{\lambda_{n}^{1} A_{1}}^{f} x_{n}}^{u_{n}=\operatorname{Res}_{G_{N}}^{f} \circ \operatorname{Res} s_{G_{N-1}}^{f} \circ \ldots \circ \operatorname{Res}_{G_{2}}^{f} \circ \operatorname{Res}_{G_{1}}^{f} y_{n}}  \tag{3.1}\\
x_{n+1}=\nabla f^{*}\left(\alpha_{n} \nabla f(u)+\beta_{n} \nabla f\left(u_{n}\right)+\sum_{j=1}^{\infty} \gamma_{n j} \nabla f\left(T_{j} u_{n}\right)\right), \forall n \geq 1
\end{array}\right.
$$

converges strongly to a point $p=\overleftarrow{P} r o j_{\Omega}^{f} u \in \Omega$, where

$$
G(x, y):=g(x, y)+\langle B x, y-x\rangle+\varphi(y)-\varphi(x)
$$

and the sequences $\alpha_{n}, \beta_{n}, \gamma_{n j}$ and $\lambda_{n}$ satisfy the following conditions:
(i) $\lim _{n \rightarrow \infty} \alpha_{n}=0$;
(ii) $\sum_{n=1}^{\infty} \alpha_{n}=\infty$;
(iii) $\alpha_{n}+\beta_{n}+\sum_{j=1}^{\infty} \gamma_{n j}=1$;
(iv) $0<a<\beta_{n}, \sum_{j=1}^{\infty} \gamma_{n j}<b<1$;
(v) $\liminf _{n \rightarrow \infty} \lambda_{n}^{k}>0$ for each $k=1,2, \ldots, N$.

A prototype example of the control sequences are:

$$
\alpha_{n}=\frac{1}{n+6}, \beta_{n}=\frac{n^{2}+6 n+9}{(n+6)(n+3)} \text { and } \gamma_{n j}=\frac{1}{2^{j}(n+3)} .
$$

Proof. It is known (see [54]) that the function

$$
G(x, y):=g(x, y)+\langle B x, y-x\rangle+\varphi(y)-\varphi(x)
$$

satisfies $(A 1)-(A 4)$ and $G M E P(g, \varphi, B)$ is closed and convex.
For any $x^{*} \in \Omega$, then from (3.1), we have that

$$
\begin{align*}
D_{f}\left(x^{*}, y_{n}\right) & =D_{f}\left(x^{*}, \operatorname{Res}_{\lambda_{n}^{N} A_{N}}^{f} \circ \operatorname{Res}_{\lambda_{n}^{N-1} A_{N-1}}^{f} \circ \cdots \circ \operatorname{Res}_{\lambda_{n}^{2} A_{2}}^{f} \circ \operatorname{Res}_{\lambda_{n}^{1} A_{1}}^{f} x_{n}\right) \\
& \leq D_{f}\left(x^{*}, \operatorname{Res}_{\lambda_{n}^{N-1} A_{N-1}}^{f} \circ \cdots \circ \operatorname{Res}_{\lambda_{n}^{2} A_{2}}^{f} \circ \operatorname{Res}_{\lambda_{n}^{1} A_{1}}^{f} x_{n}\right) \\
& \vdots \\
& \leq D_{f}\left(x^{*}, x_{n}\right) . \tag{3.2}
\end{align*}
$$

Also from (3.1), we have

$$
\begin{align*}
D_{f}\left(x^{*}, u_{n}\right) & =D_{f}\left(x^{*}, \operatorname{Res}_{G_{N}}^{f} \circ \operatorname{Res}_{G_{N-1}}^{f} \circ \ldots \circ \operatorname{Res}_{G_{2}}^{f} \circ \operatorname{Res}_{G_{1}}^{f} y_{n}\right) \\
& \leq D_{f}\left(x^{*}, \operatorname{Res}_{G_{N-1}}^{f} \circ \ldots \circ \operatorname{Res}_{G_{2}}^{f} \circ \operatorname{Res}_{G_{1}}^{f} y_{n}\right) \\
& \vdots  \tag{3.3}\\
& \leq D_{f}\left(x^{*}, y_{n}\right) .
\end{align*}
$$

Again from (2.8), (3.1), (3.2) and (3.3), we have

$$
\begin{align*}
D_{f}\left(x^{*}, x_{n+1}\right) & =D_{f}\left(x^{*}, \nabla f^{*}\left(\alpha_{n} \nabla f(u)+\beta_{n} \nabla f\left(u_{n}\right)+\sum_{j=1}^{\infty} \gamma_{n j} \nabla f\left(T_{j} u_{n}\right)\right)\right) \\
& \leq \alpha_{n} D_{f}\left(x^{*}, u\right)+\beta_{n} D_{f}\left(x^{*}, u_{n}\right)+\sum_{j=1}^{\infty} \gamma_{n j} D_{f}\left(x^{*}, T_{j}\left(u_{n}\right)\right) \\
& \leq \alpha_{n} D_{f}\left(x^{*}, u\right)+\beta_{n} D_{f}\left(x^{*}, u_{n}\right)+\sum_{j=1}^{\infty} \gamma_{n j} D_{f}\left(x^{*}, u_{n}\right) \\
& =\alpha_{n} D_{f}\left(x^{*}, u\right)+\left(\beta_{n}+\sum_{j=1}^{\infty} \gamma_{n j}\right) D_{f}\left(x^{*}, u_{n}\right) \\
& \leq \alpha_{n} D_{f}\left(x^{*}, u\right)+\left(\beta_{n}+\sum_{j=1}^{\infty} \gamma_{n j}\right) D_{f}\left(x^{*}, y_{n}\right) \\
& \leq \alpha_{n} D_{f}\left(x^{*}, u\right)+\left(\beta_{n}+\sum_{j=1}^{\infty} \gamma_{n j}\right) D_{f}\left(x^{*}, x_{n}\right) \\
& =\alpha_{n} D_{f}\left(x^{*}, u\right)+\left(1-\alpha_{n}\right) D_{f}\left(x^{*}, x_{n}\right) \\
& \leq \max \left\{D_{f}\left(x^{*}, u\right), D_{f}\left(x^{*}, x_{n}\right)\right\} \\
& \vdots \\
& \leq \max \left\{D_{f}\left(x^{*}, u\right), D_{f}\left(x^{*}, x_{1}\right)\right\} . \tag{3.4}
\end{align*}
$$

Therefore $\left\{D_{f}\left(x^{*}, x_{n}\right)\right\}$ is bounded and so also are $\left\{D_{f}\left(x^{*}, u_{n}\right)\right\}$ and $\left\{D_{f}\left(x^{*}, y_{n}\right)\right\}$, and consequently, we have that the sequences $\left\{x_{n}\right\},\left\{u_{n}\right\}$ and $\left\{y_{n}\right\}$ are bounded. Moreover,

$$
\begin{aligned}
D_{f}\left(x^{*}, u_{n+1}\right) & \leq D_{f}\left(x^{*}, x_{n+1}\right) \\
& =V_{f}\left(x^{*}, \alpha_{n} \nabla f(u)+\beta_{n} \nabla f\left(u_{n}\right)+\sum_{j=1}^{\infty} \gamma_{n j} \nabla f\left(T_{j} u_{n}\right)\right) \\
& \leq V_{f}\left(x^{*}, \alpha_{n} \nabla f(u)+\beta_{n} \nabla f\left(u_{n}\right)+\sum_{j=1}^{\infty} \gamma_{n j} \nabla f\left(T_{j} u_{n}\right)\right. \\
& \left.-\alpha_{n}\left(\nabla f(u)-\nabla f\left(x^{*}\right)\right)\right)-\left\langle\nabla f ^ { * } \left(\alpha_{n} \nabla f(u)+\beta_{n} \nabla f\left(u_{n}\right)\right.\right. \\
& \left.\left.+\sum_{j=1}^{\infty} \gamma_{n j} \nabla f\left(T_{j} u_{n}\right)\right)-x^{*},-\alpha_{n}\left(\nabla f(u)-\nabla f\left(x^{*}\right)\right)\right\rangle \\
& =V_{f}\left(x^{*}, \alpha_{n} \nabla f\left(x^{*}\right)+\beta_{n} \nabla f\left(u_{n}\right)+\sum_{j=1}^{\infty} \gamma_{n j} \nabla f\left(T_{j} u_{n}\right)\right) \\
& +\alpha_{n}\left\langle x_{n+1}-x^{*}, \nabla f(u)-\nabla f\left(x^{*}\right)\right\rangle
\end{aligned}
$$

$$
\begin{align*}
& =D_{f}\left(x^{*}, \nabla f^{*}\left(\alpha_{n} \nabla f\left(x^{*}\right)+\beta_{n} \nabla f\left(u_{n}\right)+\sum_{j=1}^{\infty} \gamma_{n j} \nabla f\left(T_{j} u_{n}\right)\right)\right. \\
& +\alpha_{n}\left\langle x_{n+1}-x^{*}, \nabla f(u)-\nabla f\left(x^{*}\right)\right\rangle \\
& \leq \alpha_{n} D_{f}\left(x^{*}, x^{*}\right)+\beta_{n} D_{f}\left(x^{*}, u_{n}\right)+\sum_{j=1}^{\infty} \gamma_{n j} D_{f}\left(x^{*}, T_{j} u_{n}\right) \\
& +\alpha_{n}\left\langle x_{n+1}-x^{*}, \nabla f(u)-\nabla f\left(x^{*}\right)\right\rangle \\
& =\beta_{n} D_{f}\left(x^{*}, u_{n}\right)+\sum_{j=1}^{\infty} \gamma_{n j} D_{f}\left(x^{*}, T_{j} u_{n}\right) \\
& +\alpha_{n}\left\langle x_{n+1}-x^{*}, \nabla f(u)-\nabla f\left(x^{*}\right)\right\rangle \\
& \leq \beta_{n} D_{f}\left(x^{*}, u_{n}\right)+\sum_{j=1}^{\infty} \gamma_{n j} D_{f}\left(x^{*}, u_{n}\right) \\
& +\alpha_{n}\left\langle x_{n+1}-x^{*}, \nabla f(u)-\nabla f\left(x^{*}\right)\right\rangle \\
& =\left(1-\alpha_{n}\right) D_{f}\left(x^{*}, u_{n}\right)+\alpha_{n}\left\langle x_{n+1}-x^{*}, \nabla f(u)-\nabla f\left(x^{*}\right)\right\rangle . \tag{3.5}
\end{align*}
$$

We now consider two cases to obtain strong convergence.
Case 1. Suppose that there exists $n_{0} \in \mathbb{N}$ such that $\left\{D_{f}\left(x^{*}, u_{n}\right)\right\}_{n=1}^{\infty}$ is monotonically nonincreasing. Then $\left\{D_{f}\left(x^{*}, u_{n}\right)\right\}_{n=1}^{\infty}$ converges and

$$
D_{f}\left(x^{*}, u_{n+1}\right)-D_{f}\left(x^{*}, u_{n}\right) \rightarrow 0, n \rightarrow \infty .
$$

Let $s_{n}:=\nabla f^{*}\left(\frac{\beta_{n}}{1-\alpha_{n}} \nabla f\left(u_{n}\right)+\frac{\sum_{j=1}^{\infty} \gamma_{n j}}{1-\alpha_{n}} \nabla f\left(T_{j} u_{n}\right)\right)$. Then,

$$
\begin{align*}
D_{f}\left(x^{*}, s_{n}\right) & =D_{f}\left(x^{*}, \nabla f^{*}\left(\frac{\beta_{n}}{1-\alpha_{n}} \nabla f\left(u_{n}\right)+\frac{\sum_{j=1}^{\infty} \gamma_{n j}}{1-\alpha_{n}} \nabla f\left(T_{j} u_{n}\right)\right)\right. \\
& \leq \frac{\beta_{n}}{1-\alpha_{n}} D_{f}\left(x^{*}, u_{n}\right)+\frac{\sum_{j=1}^{\infty} \gamma_{n j}}{1-\alpha_{n}} D_{f}\left(x^{*}, T_{j} u_{n}\right) \\
& \leq \frac{\beta_{n}}{1-\alpha_{n}} D_{f}\left(x^{*}, u_{n}\right)+\frac{\sum_{j=1}^{\infty} \gamma_{n j}}{1-\alpha_{n}} D_{f}\left(x^{*}, u_{n}\right) \\
& \leq \frac{\beta_{n}+\sum_{j=1}^{\infty} \gamma_{n j}}{1-\alpha_{n}} D_{f}\left(x^{*}, u_{n}\right) \tag{3.6}
\end{align*}
$$

Thus,

$$
\begin{align*}
0 \leq & D_{f}\left(x^{*}, u_{n}\right)-D_{f}\left(x^{*}, s_{n}\right) \\
= & D_{f}\left(x^{*}, u_{n}\right)-D_{f}\left(x^{*}, u_{n+1}\right)+D_{f}\left(x^{*}, u_{n+1}\right)-D_{f}\left(x^{*}, s_{n}\right) \\
\leq & D_{f}\left(x^{*}, u_{n}\right)-D_{f}\left(x^{*}, u_{n+1}\right)+D_{f}\left(x^{*}, x_{n+1}\right)-D_{f}\left(x^{*}, s_{n}\right) \\
\leq & D_{f}\left(x^{*}, u_{n}\right)-D_{f}\left(x^{*}, u_{n+1}\right)+\alpha_{n} D_{f}\left(x^{*}, u\right) \\
& +\left(1-\alpha_{n}\right) D_{f}\left(x^{*}, s_{n}\right)-D_{f}\left(x^{*}, s_{n}\right) \\
= & D_{f}\left(x^{*}, u_{n}\right)-D_{f}\left(x^{*}, u_{n+1}\right) \\
& +\alpha_{n}\left(D_{f}\left(x^{*}, u\right)-D_{f}\left(x^{*}, s_{n}\right)\right) \rightarrow 0, n \rightarrow \infty . \tag{3.7}
\end{align*}
$$

Furthermore,

$$
\begin{align*}
D_{f}\left(x^{*}, s_{n}\right) & \leq \frac{\beta_{n}}{1-\alpha_{n}} D_{f}\left(x^{*}, u_{n}\right)+\frac{\sum_{j=1}^{\infty} \gamma_{n j}}{1-\alpha_{n}} D_{f}\left(x^{*}, T_{j} u_{n}\right) \\
& =\left(1-\frac{\sum_{j=1}^{\infty} \gamma_{n j}}{1-\alpha_{n}}\right) D_{f}\left(x^{*}, u_{n}\right)+\frac{\sum_{j=1}^{\infty} \gamma_{n j}}{1-\alpha_{n}} D_{f}\left(x^{*}, T_{j} u_{n}\right) \\
& =D_{f}\left(x^{*}, u_{n}\right)+\frac{\sum_{j=1}^{\infty} \gamma_{n j}}{1-\alpha_{n}}\left(D_{f}\left(x^{*}, T_{j} u_{n}\right)-D_{f}\left(x^{*}, u_{n}\right)\right) \tag{3.8}
\end{align*}
$$

Therefore from (3.8), we have

$$
\begin{equation*}
\frac{\sum_{j=1}^{\infty} \gamma_{n j}}{1-\alpha_{n}}\left(D_{f}\left(x^{*}, u_{n}\right)-D_{f}\left(x^{*}, T_{j} u_{n}\right)\right) \leq D_{f}\left(x^{*}, u_{n}\right)-D_{f}\left(x^{*}, s_{n}\right) \rightarrow 0, n \rightarrow \infty \tag{3.9}
\end{equation*}
$$

Since $T_{j}$ is left Bregman strongly nonexpansive, we obtain that

$$
\lim _{n \rightarrow \infty} D_{f}\left(u_{n}, T_{j} u_{n}\right)=0,
$$

which implies that

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|u_{n}-T_{j} u_{n}\right\|=0 \tag{3.10}
\end{equation*}
$$

Since $\left\{u_{n}\right\}$ is bounded and $E$ is a reflexive Banach space, there exists a subsequence $\left\{u_{n_{j}}\right\}$ of $\left\{u_{n}\right\}$ that converges weakly to $p \in C$. It then follows from (3.10) that $p \in \cap_{j=1}^{\infty} F\left(T_{j}\right)$, since $F\left(T_{j}\right)=\hat{F}\left(T_{j}\right)$.
We next show that $p \in \cap_{k=1}^{\infty} E P\left(G_{k}\right)=\cap_{k=1}^{\infty} G M E P\left(F_{k}, \varphi_{k}, B_{k}\right)$.
Denote $\Theta_{k}=\operatorname{Res}_{G_{k}}^{f} \circ \operatorname{Res}_{G_{k-1}}^{f} \circ, \ldots, \circ \operatorname{Res}_{G_{1}}^{f}$ for $k=1,2, \ldots N$ and $\Theta_{0}=I$. We note that $u_{n}=\Theta_{N} y_{n}$. Now, by using the fact that $\operatorname{Res}_{G_{k}}^{f}, k=1,2, \cdots, N$ is properly left Bregman nonexpansive mapping, we have

$$
\begin{align*}
D_{f}\left(x^{*}, u_{n}\right) & =D_{f}\left(x^{*}, \Theta_{N} y_{n}\right) \\
& =D_{f}\left(x^{*}, \operatorname{Res}_{G_{N}}^{f} \Theta_{N-1} y_{n}\right) \\
& \leq D_{f}\left(x^{*}, \Theta_{N-1} y_{n}\right) \leq \cdots \leq D_{f}\left(x^{*}, y_{n}\right) \\
& \leq D_{f}\left(x^{*}, x_{n}\right) \tag{3.11}
\end{align*}
$$

Since $x^{*} \in E P\left(G_{N}\right)=F\left(\operatorname{Res}_{G_{n}}^{f}\right)$, then from Lemma 2.7, (3.3) and (3.11), we have

$$
\begin{align*}
D_{f}\left(u_{n}, \operatorname{Res}_{G_{N}}^{f} \Theta_{N-1} y_{n}\right)= & \left.D_{f}\left(\operatorname{Res}_{G_{N}}^{f} \Theta_{N-1} y_{n}\right), \Theta_{N-1} y_{n}\right) \\
\leq & D_{f}\left(x^{*}, \Theta_{N-1} y_{n}\right)-D_{f}\left(x^{*}, u_{n}\right) \\
\leq & D_{f}\left(x^{*}, y_{n}\right)-D_{f}\left(x^{*}, u_{n}\right) \\
\leq & D_{f}\left(x^{*}, x_{n}\right)-D_{f}\left(x^{*}, u_{n}\right) \\
\leq & \left(1-\alpha_{n-1}\right) D_{f}\left(x^{*}, u_{n-1}\right) \\
& +\alpha_{n-1}\left\langle x_{n}-x^{*}, \nabla f(u)-\nabla f\left(x^{*}\right)\right\rangle-D_{f}\left(x^{*}, u_{n}\right) \\
\leq & \alpha_{n-1} M \\
& +D_{f}\left(x^{*}, u_{n-1}\right)-D_{f}\left(x^{*}, u_{n}\right) \rightarrow 0, n \rightarrow \infty, \tag{3.12}
\end{align*}
$$

where $M>0$ is such that $D_{f}\left(x^{*}, u_{n-1}\right)+\left\langle x_{n}-x^{*}, \nabla f(u)-\nabla f\left(x^{*}\right)\right\rangle \leq M$.
Therefore,

$$
\lim _{n \rightarrow \infty} D_{f}\left(\Theta_{N} y_{n}, \Theta_{N-1} y_{n}\right)=\lim _{n \rightarrow \infty} D_{f}\left(u_{n}, \Theta_{N-1} y_{n}\right)=0
$$

From Lemma 2.5, we have

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|\Theta^{N} y_{n}-\Theta^{N-1} y_{n}\right\|=\lim _{n \rightarrow \infty}\left\|u_{n}-\Theta^{N-1} y_{n}\right\|=0 \tag{3.13}
\end{equation*}
$$

Thus, we have from (3.13) that

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|\nabla f\left(\Theta^{N} y_{n}\right)-\nabla f\left(\Theta^{N-1} y_{n}\right)\right\|=0 \tag{3.14}
\end{equation*}
$$

Again, since $x^{*} \in E P\left(G_{N-1}\right)=F\left(\operatorname{Res}_{G_{N-1}}^{f}\right)$, it follows from (3.11) and Lemma 2.7 that

$$
\begin{align*}
D_{f}\left(\Theta^{N-1} y_{n}, \Theta^{N-2} y_{n}\right)= & D_{f}\left(\operatorname{Res}_{G_{N-1}}^{f} \Theta^{N-2} y_{n}, \Theta^{N-2} y_{n}\right) \\
\leq & D_{f}\left(x^{*}, \Theta^{N-2} y_{n}\right)-D_{f}\left(x^{*}, \Theta^{N-1} y_{n}\right) \\
\leq & D_{f}\left(x^{*}, y_{n}\right)-D_{f}\left(x^{*}, u_{n}\right) \\
\leq & D_{f}\left(x^{*}, x_{n}\right)-D_{f}\left(x^{*}, u_{n}\right) \\
\leq & \alpha_{n-1} M \\
& +D_{f}\left(x^{*}, u_{n-1}\right)-D_{f}\left(x^{*}, u_{n}\right) \rightarrow 0, n \rightarrow \infty \tag{3.15}
\end{align*}
$$

That is,

$$
\lim _{n \rightarrow \infty} D_{f}\left(\Theta^{N-1} y_{n}, \Theta^{N-2} y_{n}\right)=0
$$

Hence from Lemma 2.5, we have

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|\Theta^{N-1} y_{n}-\Theta^{N-2} y_{n}\right\|=0 \tag{3.16}
\end{equation*}
$$

and consequently we have

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|\nabla f\left(\Theta^{N-1} y_{n}\right)-\nabla f\left(\Theta^{N-2} y_{n}\right)\right\|=0 \tag{3.17}
\end{equation*}
$$

In a similar way, we can verify that

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|\Theta^{N-2} y_{n}-\Theta^{N-3} y_{n}\right\|=\cdots=\lim _{n \rightarrow \infty}\left\|\Theta^{1} y_{n}-y_{n}\right\|=0 \tag{3.18}
\end{equation*}
$$

It is now easily seen from (3.13),(3.16) and (3.18), that

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|\Theta^{k} y_{n}-\Theta^{k-1} y_{n}\right\|=0, k=1,2, \cdots, N \tag{3.19}
\end{equation*}
$$

and

$$
\lim _{n \rightarrow \infty}\left\|u_{n}-y_{n}\right\|=0
$$

Now since $u_{n_{j}} \rightharpoonup p$ and $\lim _{n \rightarrow \infty}\left\|u_{n}-y_{n}\right\|=0$, we have that $y_{n_{j}} \rightharpoonup p$. Also from (3.13), (3.16), (3.18) and $y_{n_{j}} \rightharpoonup p$, we have that $\Theta^{k} y_{n_{j}} \rightharpoonup p, j \rightarrow \infty$, for each $k=1,2, \cdots, N$. Again using (3.19), we get that

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|\nabla f\left(\Theta^{k} y_{n}\right)-\nabla f\left(\Theta^{k-1} y_{n}\right)\right\|=0, k=1,2, \cdots, N \tag{3.20}
\end{equation*}
$$

Therefore by (2.7), we have that for each $k=1,2, \cdots, N$,

$$
G_{k}\left(\Theta^{k} y_{n_{j}}, y\right)+\left\langle y-\Theta^{k} y_{n_{j}}, \nabla f\left(\Theta^{k} y_{n_{j}}\right)-\nabla f\left(\Theta^{k-1} y_{n_{j}}\right)\right\rangle \geq 0, \forall y \in C
$$

Again using (A2), we obtain

$$
\begin{equation*}
\left\langle y-\Theta^{k} y_{n_{j}}, \nabla f\left(\Theta^{k} y_{n_{j}}\right)-\nabla f\left(\Theta^{k-1} y_{n_{j}}\right)\right\rangle \geq G_{k}\left(y, \Theta^{k} y_{n_{j}}\right) . \tag{3.21}
\end{equation*}
$$

Thus, a combination of $(\mathrm{A} 4),(3.20),(3.21)$ and $\Theta^{k} y_{n_{j}} \rightharpoonup p, j \rightarrow \infty$, gives us that for each $k=1,2, \cdots, N$,

$$
G_{k}(y, p) \leq 0, \forall y \in C
$$

Then for fixed $y \in C$, let $z_{t, y}:=t y+(1-t) p$ for all $t \in(0,1]$. This implies that $z_{t, y} \in C$ and further yields that $G_{k}\left(z_{t, y}, p\right) \leq 0$. It then follows from (A1) and (A4) that

$$
\begin{aligned}
0 & =G_{k}\left(z_{t, y}, z_{t, y}\right) \\
& \leq t G_{k}\left(z_{t, y}, y\right)+(1-t) G_{k}\left(z_{t, y}, p\right) \\
& \leq t G_{k}\left(z_{t, y}, y\right)
\end{aligned}
$$

Hence, from condition (A3), we obtain $G_{k}(p, y) \geq 0, \forall y \in C$, which implies that

$$
p \in \cap_{k=1}^{N} E P\left(G_{k}\right) .
$$

Next, we show that $p \in \cap_{i=1}^{N} A_{i}^{-1}(0)=\cap_{i=1}^{N} F\left(\operatorname{Res}_{\lambda_{n}^{i} A_{i}}^{f}\right)$.
Set $\Phi^{i}=\operatorname{Res}_{\lambda_{n}^{i} A_{i}}^{f} \circ \operatorname{Res}_{\lambda_{n}^{i-1} A_{i-1}}^{f} \circ \cdots \circ \operatorname{Res}_{\lambda_{n}^{2} A_{2}}^{f} \circ \operatorname{Res}_{\lambda_{n}^{1} A_{1}}^{f}$, for each $i=1,2, \cdots, N$, and $\Phi^{0}=I$. We note that $y_{n}=\Phi^{i} x_{n}$.
Since $x^{*} \in A_{N}^{-1}(0)$, by Lemma 2.11, we have

$$
\begin{aligned}
D_{f}\left(y_{n}, \Phi^{N-1}\left(x_{n}\right)\right) \leq & D_{f}\left(x^{*}, \Phi^{N-1}\left(x_{n}\right)\right)-D_{f}\left(x^{*}, y_{n}\right) \\
\leq & D_{f}\left(x^{*}, x_{n}\right)-D_{f}\left(x^{*}, y_{n}\right) \\
= & \left(1-\alpha_{n-1}\right) D_{f}\left(x^{*}, u_{n-1}\right) \\
& +\alpha_{n-1}\left\langle z_{n-1}-x^{*}, \nabla f(u)-\nabla f\left(x^{*}\right)\right\rangle-D_{f}\left(x^{*}, y_{n}\right) \\
\leq & \alpha_{n-1} M_{1}+D_{f}\left(x^{*}, u_{n-1}-D_{f}\left(x^{*}, u_{n}\right) \rightarrow 0, n \rightarrow \infty(3.22)\right.
\end{aligned}
$$

where $M_{1}$ is such that $D_{f}\left(x^{*}, u_{n-1}\right)+\alpha_{n-1}\left\langle z_{n-1}-x^{*}, \nabla f(u)-\nabla f\left(x^{*}\right)\right\rangle \leq M_{1}$. Since $f$ is sequentially consistent, then we have from (3.22) that

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|y_{n}-\Phi^{N-1} x_{n}\right\|=0 \tag{3.23}
\end{equation*}
$$

and hence

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|\nabla f\left(x_{n}\right)-\nabla f\left(\Phi^{N-1} x_{n}\right)\right\|=0 \tag{3.24}
\end{equation*}
$$

Again, since $x^{*} \in A_{N-1}^{-1}(0)$, by Lemma 2.11, we have

$$
\begin{align*}
D_{f}\left(\Phi^{N-1}\left(x_{n}\right), \Phi^{N-2}\left(x_{n}\right)\right) \leq & D_{f}\left(x^{*}, \Phi^{N-2}\left(x_{n}\right)\right)-D_{f}\left(x^{*}, \Phi^{N-1}\left(x_{n}\right)\right) \\
\leq & D_{f}\left(x^{*}, x_{n}\right)-D_{f}\left(x^{*}, y_{n}\right) \\
\leq & \alpha_{n-1} M_{1} \\
& +D_{f}\left(x^{*}, u_{n-1}\right)-D_{f}\left(x^{*}, u_{n}\right) \rightarrow 0, n \rightarrow \infty \tag{3.25}
\end{align*}
$$

Thus since $f$ is sequentially consistent, we have

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|\Phi^{N-1}\left(x_{n}\right)-\Phi^{N-2}\left(x_{n}\right)\right\|=0 \tag{3.26}
\end{equation*}
$$

and hence

$$
\lim _{n \rightarrow \infty}\left\|\nabla f\left(\Phi^{N-1}\left(x_{n}\right)\right)-\nabla f\left(\Phi^{N-2}\left(x_{n}\right)\right)\right\|=0
$$

Following the same procedure, we have that

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|\Phi^{N-2}\left(x_{n}\right)-\Phi^{N-3}\left(x_{n}\right)\right\|=\cdots=\lim _{n \rightarrow \infty}\left\|\Phi^{1}\left(x_{n}\right)-x_{n}\right\|=0 \tag{3.27}
\end{equation*}
$$

Therefore, from (3.23),(3.26) and (3.27), we conclude that

$$
\lim _{n \rightarrow \infty}\left\|\Phi^{i}\left(x_{n}\right)-\Phi^{i-1}\left(x_{n}\right)\right\|=0, i=1,2, \cdots, N
$$

and

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|\nabla f\left(\Phi^{i}\left(x_{n}\right)\right)-\nabla f\left(\Phi^{i-1}\left(x_{n}\right)\right)\right\|=0 . \tag{3.28}
\end{equation*}
$$

Thus we have that

$$
\lim _{n \rightarrow \infty}\left\|y_{n}-x_{n}\right\|=0
$$

Since $y_{n_{j}} \rightharpoonup p$ and $\lim _{n \rightarrow \infty}\left\|y_{n}-x_{n}\right\|=0$, we have that $x_{n_{j}} \rightharpoonup p$. For each $i=$ $1,2, \cdots, N$, we note that $\Phi^{i}\left(x_{n}\right)=\operatorname{Res}_{\lambda_{n}^{i} A_{i}}^{f} \Phi^{i-1}\left(x_{n}\right)$ and therefore

$$
\left\|A_{\lambda_{n}^{i}} \Phi^{i} x_{n}\right\|=\frac{1}{\lambda_{n}^{i}}\left\|\nabla f\left(\Phi^{i-1}\left(x_{n}\right)\right)-\nabla f\left(\Phi^{i}\left(x_{n}\right)\right)\right\| .
$$

Hence from (3.28) and the condition $\lim _{n \rightarrow \infty} \lambda_{n}^{i}>0$, we have

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|A_{\lambda_{n}^{i}} \Phi^{i} x_{n}\right\|=0 \tag{3.29}
\end{equation*}
$$

Now since $\left(\Phi^{i} x_{n}, A_{\lambda_{n}^{i}} \Phi^{i-1}\left(x_{n}\right)\right) \in G\left(A_{i}\right)$ for each $i=1,2, \cdots, N$. If $\left(w, w^{*}\right) \in G\left(A_{i}\right)$ for each $i=1,2, \cdots, N$, then it follows from the monotonicity of $A_{i}, i=1,2, \cdots, N$, that

$$
\left\langle w^{*}-A_{\lambda_{n}^{i}} \Phi^{i-1}\left(x_{n}\right), w-\Phi^{i}\left(x_{n}\right)\right\rangle \geq 0 .
$$

Since $x_{n_{j}} \rightharpoonup p$, then $\Phi^{i}\left(x_{n_{j}}\right) \rightharpoonup p$ for each $i=1,2, \cdots, N$. Thus from (3.29), we have

$$
\left\langle w^{*}, w-p\right\rangle \geq 0
$$

and since $A_{i}$ is maximally monotone for each $i=1,2, \cdots, N$, we conclude that $p \in$ $\cap_{i=1}^{N} A_{i}^{-1}(0)$.
Thus we have

$$
p \in F(T) \cap\left(\cap_{k=1}^{N} E P\left(G_{k}\right)\right) \cap\left(\cap_{i=1}^{N} A_{i=1}^{-1}(0)\right),
$$

that is

$$
p \in F(T) \cap\left(\cap_{k=1}^{N} G M E P\left(g_{k}, \varphi_{k}, B_{k}\right)\right) \cap\left(\cap_{i=1}^{N} A_{i=1}^{-1}(0)\right) .
$$

We now show that $\left\{x_{n}\right\}$ converges strongly to $z:=\overleftarrow{P} r o j_{\Omega}^{f} u$

$$
\begin{aligned}
D_{f}\left(u_{n}, x_{n+1}\right) & =D_{f}\left(u_{n}, \nabla f^{*}\left(\alpha_{n} \nabla f(u)+\beta_{n} \nabla f\left(u_{n}\right)+\sum_{j=1}^{\infty} \gamma_{n j} \nabla f\left(T u_{n}\right)\right)\right) \\
& \leq \alpha_{n} D_{f}\left(u_{n}, u\right)+\beta_{n} D_{f}\left(u_{n}, u_{n}\right)+\sum_{j=1}^{\infty} \gamma_{n j} D_{f}\left(u_{n}, T u_{n}\right) \rightarrow 0, n \rightarrow \infty .
\end{aligned}
$$

Therefore, by Lemma 2.5, it follows that

$$
\left\|u_{n}-x_{n+1}\right\| \rightarrow 0, n \rightarrow \infty
$$

Now,

$$
\left\|x_{n}-x_{n+1}\right\| \leq\left\|x_{n}-y_{n}\right\|+\left\|y_{n}-u_{n}\right\|+\left\|u_{n}-x_{n+1}\right\| \rightarrow 0, n \rightarrow \infty
$$

Let $z:=\overleftarrow{P} r o j_{\Omega}^{f} u$, we now show that

$$
\limsup _{n \rightarrow \infty}\left\langle x_{n+1}-z, \nabla f(u)-\nabla f(z)\right\rangle \leq 0
$$

Choose a subsequence $\left\{x_{n_{j}}\right\}$ of $\left\{x_{n}\right\}$ such that

$$
\limsup _{n \rightarrow \infty}\left\langle x_{n}-z, \nabla f(u)-\nabla f(z)\right\rangle=\lim _{j \rightarrow \infty}\left\langle x_{n_{j}}-z, \nabla f(u)-\nabla f(z)\right\rangle
$$

Then, from $\left\|x_{n}-x_{n+1}\right\| \rightarrow 0, n \rightarrow \infty$ and Lemma 2.10, we have

$$
\limsup _{n \rightarrow \infty}\left\langle x_{n+1}-z, \nabla f(u)-\nabla f(z)\right\rangle=\limsup _{n \rightarrow \infty}\left\langle x_{n}-z, \nabla f(u)-\nabla f(z)\right\rangle \leq 0
$$

Now, from (3.5),

$$
\begin{aligned}
D_{f}\left(z, x_{n+1}\right) & \leq\left(1-\alpha_{n}\right) D_{f}\left(z, u_{n}\right)+\alpha_{n}\left\langle x_{n+1}-z, \nabla f(u)-\nabla f(z)\right\rangle \\
& \leq\left(1-\alpha_{n}\right) D_{f}\left(z, y_{n}\right)+\alpha_{n}\left\langle x_{n+1}-z, \nabla f(u)-\nabla f(z)\right\rangle \\
& \leq\left(1-\alpha_{n}\right) D_{f}\left(z, x_{n}\right)+\alpha_{n}\left\langle x_{n+1}-z, \nabla f(u)-\nabla f(z)\right\rangle
\end{aligned}
$$

Hence by Lemma 2.8, we obtain $D_{f}\left(z, x_{n}\right) \rightarrow 0, n \rightarrow \infty$ and so

$$
\left\|x_{n}-z\right\| \rightarrow 0
$$

That is $\left\{x_{n}\right\}$ converges strongly to $z:=\overleftarrow{P} r o j_{\Omega}^{f} u$
Case 2. Suppose there exists a subsequence $\left\{n_{\iota}\right\}$ of $\left\{x_{n}\right\}$ such that

$$
D_{f}\left(x^{*}, x_{n_{\iota}}\right) \leq D_{f}\left(x^{*}, x_{n_{\iota}+1}\right) \forall \iota \in \mathbb{N} .
$$

Then by Lemma 2.9, there exists a nondecreasing sequence $\left\{m_{\tau}\right\} \subset \mathbb{N}$ such that $m_{\tau} \rightarrow \infty, \tau \rightarrow \infty$,

$$
D_{f}\left(x^{*}, x_{m_{\tau}}\right) \leq D_{f}\left(x^{*}, x_{m_{\tau}+1}\right)
$$

and

$$
D_{f}\left(x^{*}, x_{\tau}\right) \leq D_{f}\left(x^{*}, x_{m_{\tau}+1}\right) \forall \tau \in \mathbb{N}
$$

Again, let

$$
s_{n_{\tau}}:=\nabla f^{*}\left(\frac{\beta_{n_{\tau}}}{1-\alpha_{n_{\tau}}} \nabla f\left(u_{n_{\tau}}\right)+\frac{\sum_{j=1}^{\infty} \gamma_{n_{\tau} j}}{1-\alpha_{n_{\tau}}} \nabla f\left(T_{j} u_{n_{\tau}}\right)\right) .
$$

Then

$$
\begin{aligned}
D_{f}\left(x^{*}, s_{n_{\tau}}\right) & +D_{f}\left(x^{*}, \nabla f^{*}\left(\frac{\beta_{n_{\tau}}}{1-\alpha_{n_{\tau}}} \nabla f\left(u_{n_{\tau}}\right)+\frac{\sum_{j=1}^{\infty} \gamma_{n_{\tau} j}}{1-\alpha_{n_{\tau}}} \nabla f\left(T_{j} u_{n_{\tau}}\right)\right)\right) \\
& \left.\leq\left(\frac{\beta_{n_{\tau}}}{1-\alpha_{n_{\tau}}}\right) D_{f}\left(x^{*}, u_{n_{\tau}}\right)+\frac{\sum_{j=1}^{\infty} \gamma_{n_{\tau} j}}{1-\alpha_{n_{\tau}}}\right) D_{f}\left(x^{*}, T_{j} u_{n_{\tau}}\right) \\
& \leq\left(\frac{\beta_{n_{\tau}}+\sum_{j=1}^{\infty} \gamma_{n_{\tau} j}}{1-\alpha_{n_{\tau}}}\right) D_{f}\left(x^{*}, u_{n_{\tau}}\right) \\
& \leq D_{f}\left(x^{*}, u_{n_{\tau}}\right)
\end{aligned}
$$

Therefore,

$$
\begin{aligned}
0 \leq & D_{f}\left(x^{*}, u_{n_{\tau}}\right)-D_{f}\left(x^{*}, s_{n_{\tau}}\right) \\
= & D_{f}\left(x^{*}, u_{n_{\tau}}\right)-D_{f}\left(x^{*}, u_{n_{\tau}+1}\right)+D_{f}\left(x^{*}, u_{n_{\tau}+1}\right)-D_{f}\left(x^{*}, s_{n_{\tau}}\right) \\
\leq & D_{f}\left(x^{*}, u_{n_{\tau}}\right)-D_{f}\left(x^{*}, u_{n_{\tau}+1}\right)+D_{f}\left(x^{*}, x_{n_{\tau}+1}\right)-D_{f}\left(x^{*}, s_{n_{\tau}}\right) \\
\leq & D_{f}\left(x^{*}, u_{n_{\tau}}\right)-D_{f}\left(x^{*}, u_{n_{\tau}+1}\right)+\alpha_{n_{\tau}} D_{f}\left(x^{*}, u\right) \\
& +\left(1-\alpha_{n_{\tau}}\right) D_{f}\left(x^{*}, s_{n_{\tau}}\right)-D_{f}\left(x^{*}, s_{n_{\tau}}\right) \\
= & D_{f}\left(x^{*}, u_{n_{\tau}}\right)-D_{f}\left(x^{*}, u_{n_{\tau}+1}\right)+\alpha_{n_{\tau}}\left(D_{f}\left(x^{*}, u\right)-D_{f}\left(x^{*}, s_{n_{\tau}}\right) \rightarrow 0, n \rightarrow \infty .\right.
\end{aligned}
$$

Furthermore,

$$
\begin{align*}
D_{f}\left(x^{*}, s_{n_{\tau}}\right) & \leq \frac{\beta_{n_{\tau}}}{1-\alpha_{n_{\tau}}} D_{f}\left(x^{*}, u_{n_{\tau}}\right)+\frac{\sum_{j=1}^{\infty} \gamma_{n_{\tau} j}}{1-\alpha_{n_{\tau}}} D_{f}\left(x^{*}, T_{j} u_{n_{\tau}}\right) \\
& =\left(1-\frac{\sum_{j=1}^{\infty} \gamma_{n_{\tau} j}}{1-\alpha_{n_{\tau}}}\right) D_{f}\left(x^{*}, u_{n_{\tau}}\right)+\frac{\sum_{j=1}^{\infty} \gamma_{n_{\tau} j}}{1-\alpha_{n_{\tau}}} D_{f}\left(x^{*}, T_{j} u_{n_{\tau}}\right) \\
& =D_{f}\left(x^{*}, u_{n_{\tau}}\right)+\frac{\sum_{j=1}^{\infty} \gamma_{n_{\tau} j}}{1-\alpha_{n_{\tau}}}\left(D_{f}\left(x^{*}, T_{j} u_{n_{\tau}}\right)-D_{f}\left(x^{*}, u_{n_{\tau}}\right)\right) \tag{3.30}
\end{align*}
$$

Thus from (3.30), we have

$$
\begin{equation*}
\frac{\sum_{j=1}^{\infty} \gamma_{n_{\tau} j}}{1-\alpha_{n_{\tau}}}\left(D_{f}\left(x^{*}, u_{n_{\tau}}\right)-D_{f}\left(x^{*}, T_{j} u_{n_{\tau}}\right)\right) \leq D_{f}\left(x^{*}, u_{n_{\tau}}\right)-D_{f}\left(x^{*}, s_{n_{\tau}}\right) \rightarrow 0, n \rightarrow \infty \tag{3.31}
\end{equation*}
$$

Since $T$ is left Bregman strongly nonexpansive, we obtain that

$$
\lim _{\tau \rightarrow \infty} D_{f}\left(u_{n_{\tau}}, T_{j} u_{n \tau}\right)=0
$$

which implies that

$$
\begin{equation*}
\lim _{\tau \rightarrow \infty}\left\|u_{n_{\tau}}-T_{j} u_{n_{\tau}}\right\|=0 \tag{3.32}
\end{equation*}
$$

By the same arguments as in Case 1, we obtain that

$$
\begin{equation*}
\limsup _{\tau \rightarrow \infty}\left\langle x_{n_{\tau}+1}-z, \nabla f(u)-\nabla f(z)\right\rangle \leq 0 \tag{3.33}
\end{equation*}
$$

and

$$
D_{f}\left(z, x_{n_{\tau}+1}\right) \leq\left(1-\alpha_{n_{\tau}}\right) D_{f}\left(z, x_{n_{\tau}}\right)+\alpha_{n_{\tau}}\left\langle x_{n_{\tau}+1}-z, \nabla f(u)-\nabla f(z)\right\rangle
$$

which since $D_{f}\left(z, x_{n_{\tau}}\right) \leq D_{f}\left(z, x_{n_{\tau}+1}\right)$ implies

$$
\begin{aligned}
\alpha_{n_{\tau}} D_{f}\left(z, x_{n_{\tau}}\right) & \leq D_{f}\left(z, x_{n_{\tau}}\right)-D_{f}\left(z, x_{n_{\tau}+1}\right)+\alpha_{n_{\tau}}\left\langle x_{n_{\tau}+1}-z, \nabla f(u)-\nabla f(z)\right\rangle \\
& \leq \alpha_{n_{\tau}}\left\langle x_{n_{\tau}+1}-z, \nabla f(u)-\nabla f(z)\right\rangle .
\end{aligned}
$$

Thus since $\alpha_{n_{\tau}}>0$, we have

$$
D_{f}\left(z, x_{n_{\tau}}\right) \leq\left\langle x_{n_{\tau}+1}-z, \nabla f(u)-\nabla f(z)\right\rangle
$$

Hence it follows from (3.33) that

$$
\lim _{\tau \rightarrow \infty} D_{f}\left(z, x_{n_{\tau}}\right)=0
$$

Since $D_{f}\left(z, x_{\tau}\right) \leq D_{f}\left(z, x_{m_{\tau}+1}\right)$ for all $\tau \in \mathbb{N}$, we conclude that $x_{\tau} \rightarrow z, \tau \rightarrow \infty$. This implies that $x_{n} \rightarrow z, n \rightarrow \infty$, which completes the proof.
Corollary 3.2. Let $E$ be a reflexive real Banach space and $C$ a nonempty, closed and convex subset of $E$. Let $\left\{T_{j}\right\}_{j=1}^{\infty}$ be an infinite family of left Bregman nonexpasive mappings from $C$ into itself and $F\left(T_{j}\right)=\hat{F}\left(T_{j}\right), \forall j \geq 1$. Let $f: E \rightarrow \mathbb{R}$ be strongly coercive Legendre function which is bounded, uniformly Fréchet differentiable and totally convex on bounded subsets of $E$ such that $C \subset$ int(domf) and $A_{i}: E \rightarrow 2^{E^{*}}(i=1,2, \ldots, N)$ be maximal monotone operators, such that $\Omega:=\cap_{j=1}^{\infty} F\left(T_{j}\right) \cap\left(\cap_{i=1}^{N} A_{i}^{-1}(0)\right) \neq \emptyset$. Then the sequence $\left\{x_{n}\right\}$ generated for arbitrary $u, x_{1} \in E$ by

$$
\left\{\begin{array}{l}
y_{n}=\operatorname{Res}_{\lambda_{n}^{N} A_{N}}^{f} \circ \operatorname{Res}_{\lambda_{n}^{N-1} A_{N-1}}^{f} \circ \cdots \circ \operatorname{Res}_{\lambda_{n}^{2} A_{2}}^{f} \circ \operatorname{Res}_{\lambda_{n}^{1} A_{1}}^{f} x_{n},  \tag{3.34}\\
x_{n+1}=\nabla f^{*}\left(\alpha_{n} \nabla f(u)^{2}+\beta_{n} \nabla f\left(y_{n}\right)+\sum_{j=1}^{\infty} \gamma_{n j} \nabla f\left(T_{j} y_{n}\right)\right), \forall n \geq 1,
\end{array}\right.
$$

converges strongly to a point $p=\overleftarrow{P} r o j_{\Omega}^{f} u \in \Omega$, where the sequences $\alpha_{n}, \beta_{n}, \gamma_{n j}$ and $\lambda_{n}$ satisfy the following conditions:
(i) $\lim _{n \rightarrow \infty} \alpha_{n}=0$;
(ii) $\sum_{n=1}^{\infty} \alpha_{n}=\infty$;
(iii) $\alpha_{n}+\beta_{n}+\sum_{j=1}^{\infty} \gamma_{n j}=1$;
(iv) $0<a<\beta_{n}, \sum_{j=1}^{\infty} \gamma_{n j}<b<1$;
(v) $\liminf _{n \rightarrow \infty} \lambda_{n}^{k}>0$ for each $k=1,2, \ldots, N$.

Corollary 3.3. Let $E$ be a reflexive real Banach space and $C$ a nonempty, closed and convex subset of $E$. Let $\left\{T_{j}\right\}_{j=1}^{\infty}$ be an infinite family of left Bregman nonexpasive mappings from $C$ into itself and $F\left(T_{j}\right)=\hat{F}\left(T_{j}\right), \forall j \geq 1$. Let $g_{k}$ : $C \times C \rightarrow \mathbb{R},(k=1,2, \ldots, N)$ be bifunctions satisfying conditions $(A 1)-(A 4)$. Let $B_{k}: E \rightarrow E^{*},(k=1,2, \ldots, N)$ be continuous and monotone mappings, $\varphi_{k}: C \rightarrow$ $\mathbb{R} \cup+\infty,(k=1,2, \ldots, N)$ be proper lower semicontinuous and convex functions. Let $f: E \rightarrow \mathbb{R}$ be strongly coercive Legendre function which is bounded, uniformly Fréchet differentiable and totally convex on bounded subsets of $E$ such that $C \subset \operatorname{int}(\operatorname{domf})$, such that $\Omega:=\cap_{j=1}^{\infty} F\left(T_{j}\right) \cap\left(\cap_{k=1}^{N} E P\left(G_{k}\right) \neq \emptyset\right.$. Then the sequence $\left\{x_{n}\right\}$ generated for arbitrary $u, x_{1} \in E$ by

$$
\left\{\begin{array}{l}
u_{n}=\operatorname{Res}_{G_{N}}^{f} \circ \operatorname{Res}_{G_{N-1}}^{f} \circ \ldots \circ \operatorname{Res}_{G_{2}}^{f} \circ \operatorname{Res}_{G_{1}}^{f} x_{n}  \tag{3.35}\\
x_{n+1}=\nabla f^{*}\left(\alpha_{n} \nabla f(u)+\beta_{n} \nabla f\left(u_{n}\right)+\sum_{j=1}^{\infty} \gamma_{n j} \nabla f\left(T_{j} u_{n}\right)\right), \forall n \geq 1
\end{array}\right.
$$

converges strongly to a point $p=\overleftarrow{P} r o j_{\Omega}^{f} u \in \Omega$, where $G(x, y):=g(x, y)+\langle B x, y-$ $x\rangle+\varphi(y)-\varphi(x)$ and the sequences $\alpha_{n}, \beta_{n}$, and $\gamma_{n j}$ satisfies the following conditions:
(i) $\lim _{n \rightarrow \infty} \alpha_{n}=0$;
(ii) $\sum_{n=1}^{\infty} \alpha_{n}=\infty$;
(iii) $\alpha_{n}+\beta_{n}+\sum_{j=1}^{\infty} \gamma_{n j}=1$;
(iv) $0<a<\beta_{n}, \sum_{j=1}^{\infty} \gamma_{n j}<b<1$.

## 4. Applications

4.1. Convex feasibility problem. Let $\left\{K_{j}\right\}_{j=1}^{\infty}$ be nonempty closed and convex subsets of $E$ such that $\cap_{j=1}^{\infty} K_{j} \neq \emptyset$. The convex feasibility problem (CFP) is to find
$x \in \cap_{j=1}^{\infty} K_{j}$. Obviously $F\left(\overleftarrow{P} \operatorname{roj}_{K_{j}}^{f}\right)=K_{j}$ for all $j \geq 1$. If the Legendre function is uniformly Fréchet differentiable and bounded on bounded subsets of $E$, then the Bregman projection $\overleftarrow{P} r o j_{K_{j}}^{f}$ is BFNE, hence BSNE and $F\left(\overleftarrow{P} r o j_{K_{j}}^{f}\right)=\hat{F}\left(\overleftarrow{P} r o j_{K_{j}}^{f}\right)$ (see, [46] Lemma 1.2.3). Thus, if we take $T_{j}=\overleftarrow{P} r o j_{K_{j}}^{f}$ in Theorem 3.1, we get a strong convergence theorem for approximating the solution of convex feasibility problems, a common solution to a finite system of generalized mixed equilibrium problems and a common element of the set of zeros of a finite family of maximal monotone operators. Theorem 4.1. Let $E$ be a reflexive real Banach space and $C$ a nonempty, closed and convex subset of $E$. Let $T_{j}=\overleftarrow{P} \operatorname{roj}_{K_{j}}^{f}$, where $\left\{K_{j}\right\}_{j=1}^{\infty}$, are nonempty closed and convex subsets of $C$. Let $g_{k}: C \times C \rightarrow \mathbb{R},(k=1,2, \ldots, N)$ be a bifunction satisfying conditions $(A 1)-(A 4)$. Let $B_{k}: E \rightarrow E^{*},(k=1,2, \ldots, N)$ be a continuous and monotone mappings, $\varphi_{k}: C \rightarrow \mathbb{R} \cup\{+\infty\},(k=1,2, \ldots, N)$ be a proper lower semicontinuous and convex functions. Let $f: E \rightarrow \mathbb{R}$ be strongly coercive Legendre function which is bounded, uniformly Fréchet differentiable and totally convex on bounded subsets of $E$ such that $C \subset \operatorname{int}($ domf $)$ and $A_{i}: E \rightarrow 2^{E^{*}}(i=1,2, \ldots, N)$ be maximal monotone operators, such that $\Omega:=\cap_{j=1}^{\infty} F\left(T_{j}\right) \cap\left(\cap_{k=1}^{N} E P\left(G_{k}\right) \cap\left(\cap_{i=1}^{N} A_{i}\right) \neq \emptyset\right.$. Then the sequence $\left\{x_{n}\right\}$ generated for arbitrary $u, x_{1} \in E$ by

$$
\left\{\begin{array}{l}
y_{n}=\operatorname{Res}_{\lambda_{n}^{N} A_{N}}^{f} \circ \operatorname{Res}_{\lambda_{n}^{N-1} A_{N-1}}^{f} \circ \cdots \circ \operatorname{Res}_{\lambda_{n}^{2} A_{2}}^{f} \circ \operatorname{Res}_{\lambda_{n}^{1} A_{1}}^{f} x_{n},  \tag{4.1}\\
u_{n}=\operatorname{Res}_{G_{N}}^{f} \circ \operatorname{Res}_{G_{N-1}}^{f} \circ \ldots \circ \operatorname{Res}_{G_{2}}^{f} \circ \operatorname{Res}_{G_{1}}^{f} y_{n}, \\
x_{n+1}=\nabla f^{*}\left(\alpha_{n} \nabla f(u)+\beta_{n} \nabla f\left(u_{n}\right)+\sum_{j=1}^{\infty} \gamma_{n j} \nabla f\left(T_{j} u_{n}\right)\right), \forall n \geq 1,
\end{array}\right.
$$

converges strongly to a point $p=\overleftarrow{P} r o j_{\Omega}^{f} u \in \Omega$, where $G(x, y):=g(x, y)+\langle B x, y-$ $x\rangle+\varphi(y)-\varphi(x)$ and the sequences $\alpha_{n}, \beta_{n}, \gamma_{n j}$ and $\lambda_{n}$ satisfy the following conditions:
(i) $\lim _{n \rightarrow \infty} \alpha_{n}=0$;
(ii) $\sum_{n=1}^{\infty} \alpha_{n}=\infty$;
(iii) $\alpha_{n}+\beta_{n}+\sum_{j=1}^{\infty} \gamma_{n j}=1$;
(iv) $0<a<\beta_{n}, \sum_{j=1}^{\infty} \gamma_{n j}<b<1$;
(v) $\liminf _{n \rightarrow \infty} \lambda_{n}^{k}>0$ for each $k=1,2, \ldots, N$.
4.2. Zeroes of Bregman inversely strongly monotone operators. Let the Legendre function $f$ be such that

$$
\begin{equation*}
\operatorname{ran}(\nabla f-A) \subseteq \operatorname{ran}(\nabla f) \tag{4.2}
\end{equation*}
$$

The operator $A: E \rightarrow 2^{E^{*}}$ is called Bregman inversly strongly monotone (BISM) if

$$
(\operatorname{dom} A) \cap(\operatorname{int}(\operatorname{domf}) \neq \emptyset
$$

and for any $x, y \in \operatorname{int}(\operatorname{domf})$, and each $\xi \in A x, \eta \in A y$, we have

$$
\left\langle\xi-\eta, \nabla f^{*}(\nabla f(x)-\xi)-\nabla f^{*}(\nabla f(y)-\eta)\right\rangle \geq 0
$$

This class of operators was introduced by Butnariu and Kassey (see [18]). For any operator $A: E \rightarrow 2^{E^{*}}$, the anti resolvent $A^{f}: E \rightarrow 2^{E}$ of $A$ is defined by

$$
A^{f}:=\nabla f^{*} \circ(\nabla f-A)
$$

Observe that $\operatorname{dom} A^{f} \subseteq(\operatorname{dom} A) \cap\left(\operatorname{int}(\operatorname{domf})\right.$ and $\operatorname{ran} A^{f} \subseteq \operatorname{int}(\operatorname{domf})$. The operator $A[18]$ is BISM if and only if the anti-resolvent $A^{f}$ is a single valued BFNE operator. Some examples of BISM operator can be seen in [18]. From the definition of antiresolvent and ([18], Lemma 3.5), we obtain the following proposition.
Proposition 4.2. Let $f: E \rightarrow(-\infty,+\infty]$ be a Legendre function and let $A: E \rightarrow$ $2^{E^{*}}$ be a BISM operator such that $A^{-1}(0)^{*} \neq \emptyset$. Then the following statements holds;
(i) $A^{-1}(0)^{*}=F\left(A^{f}\right)$,
(ii) For any $u \in A^{-1}(0)^{*}$ and $x \in \operatorname{dom} A^{f}$, we have

$$
D_{f}\left(u, A^{f}\right)+D_{f}\left(A^{f} x, x\right) \leq D_{f}(u, x)
$$

So, if the Legendre function f is uniformly Fréchet differentiable and bounded on bounded subsets of $E$, then the resolvent of $A^{f}$ of $A$ is a single-valued BSNE operator which satisfies $F\left(A^{f}\right)=\hat{F}\left(A^{f}\right)$ ([46] Lemma 1.3.2).

In Theorem 3.1, if we let $T_{i}=A_{i}^{f}$ and let $f$ be the Legendre function such that (4.2) is satisfied then we obtain the following result for approximating a common zeroes of infinite family Bregman Inversely Strongly Monotone Operators, a common solution to a finite system of generalized mixed equilibrium problems and a common element of the set of zeros of a finite family of maximal monotone operators.
Theorem 4.3. Let $E$ be a reflexive real Banach space and $C$ a nonempty, closed and convex subset of $E$. Let $\left\{T_{j}\right\}_{j=1}^{\infty}=\left\{A_{j}^{f}\right\}_{j=1}^{\infty}$. Let $g_{k}: C \times C \rightarrow \mathbb{R},(k=1,2, \ldots, N)$ be bifunctions satisfying conditions $(A 1)-(A 4)$. Let $B_{k}: E \rightarrow E^{*},(k=1,2, \ldots, N)$ be continuous and monotone mappings, $\varphi_{k}: C \rightarrow \mathbb{R} \cup\{+\infty\},(k=1,2, \ldots, N)$ be proper lower semicontinuous and convex functions. Let $f: E \rightarrow \mathbb{R}$ be a strongly coercive Legendre function which is bounded, uniformly Fréchet differentiable and totally convex on bounded subsets of $E$ such that $C \subset$ int(domf) and $A_{i}: E \rightarrow 2^{E^{*}}(i=1,2, \ldots, N)$ be maximal monotone operators, such that $\Omega:=$ $\cap_{j=1}^{\infty} F\left(T_{j}\right) \cap\left(\cap_{k=1}^{N} E P\left(G_{k}\right) \cap\left(\cap_{i=1}^{N} A_{i}^{-1}(0)\right) \neq \emptyset\right.$. Then the sequence $\left\{x_{n}\right\}$ generated for arbitrary $u, x_{1} \in E$ by

$$
\left\{\begin{array}{l}
y_{n}=\operatorname{Res}_{\lambda_{n}^{N} A_{N}}^{f} \circ \operatorname{Res}_{\lambda_{n}^{N-1} A_{N-1}}^{f} \circ \cdots \circ \operatorname{Res}_{\lambda_{n}^{2} A_{2}}^{f} \circ \operatorname{Res}_{\lambda_{n}^{1} A_{1}}^{f} x_{n},  \tag{4.3}\\
u_{n}=\operatorname{Res}_{G_{N}}^{f} \circ \operatorname{Res}_{G_{N-1}}^{f} \circ \ldots \circ \operatorname{Res}_{G_{2}}^{f} \circ \operatorname{Res}_{G_{1}}^{f} y_{n}, \\
x_{n+1}=\nabla f^{*}\left(\alpha_{n} \nabla f(u)+\beta_{n} \nabla f\left(u_{n}\right)+\sum_{j=1}^{\infty} \gamma_{n j} \nabla f\left(T_{j} u_{n}\right)\right), \forall n \geq 1,
\end{array}\right.
$$

converges strongly to a point $p=\overleftarrow{P} r o j_{\Omega}^{f} u \in \Omega$, where $G(x, y):=g(x, y)+\langle B x, y-$ $x\rangle+\varphi(y)-\varphi(x)$ and the sequences $\alpha_{n}, \beta_{n}, \gamma_{n j}$ and $\lambda_{n}$ satisfy the following conditions:
(i) $\lim _{n \rightarrow \infty} \alpha_{n}=0$;
(ii) $\sum_{n=1}^{\infty} \alpha_{n}=\infty$;
(iii) $\alpha_{n}+\beta_{n}+\sum_{j=1}^{\infty} \gamma_{n j}=1$;
(iv) $0<a<\beta_{n}, \sum_{j=1}^{\infty} \gamma_{n j}<b<1$;
(v) $\liminf _{n \rightarrow \infty} \lambda_{n}^{k}>0$ for each $k=1,2, \ldots, N$.
4.3. Variational inequalities. Let $A: E \rightarrow E^{*}$ be a BISM operator and let $C$ be a nonempty, closed and convex subset of domA. The variational inequality problem corresponding to $A$ is to find $\bar{x} \in C$ such that

$$
\begin{equation*}
\langle A \bar{x}, y-\bar{x}\rangle \geq 0, \forall y \in C \tag{4.4}
\end{equation*}
$$

The set of solutions of (4.4) is denoted by $\mathrm{VI}(\mathrm{A}, \mathrm{C})$.
Proposition 4.4. ([45]Proposition 8) Let $f: E \rightarrow(-\infty,+\infty]$ be a Legendre and totally convex function which satisfies the range condition (4.2). Let $A: E \rightarrow E^{*}$ be a BISM operator. If $C$ is a nonempty, closed and convex subset of $\operatorname{dom} A \cap \operatorname{int}(\operatorname{domf})$, then $V I(A, C)=F\left(\overleftarrow{P} r o j_{C}^{f} \circ A^{f}\right)$
So, if the Legendre function $f$ is uniformly Fréchet differentiable and bounded on bounded subsets of $E$, the anti-resolvent $A^{f}$ is single-valued ([18], Lemma 3.5(d)) and BSNE operator (see Section 2 and [18] Lemma 3.5(c)) which satisfy $F\left(A^{f}\right)=\hat{F}\left(A^{f}\right)$. Since the Bregman projection $\overleftarrow{P} r o j_{C}^{f}$ is a BFNE operator, it is a BSNE which satisfy $F\left(\overleftarrow{P} r o j_{C}^{f}\right)=\hat{F}\left(\overleftarrow{P} r o j_{C}^{f}\right)$. It now follows (see [42] Lemma 2) that $\overleftarrow{P} r o j_{C}^{f} \circ A^{f}$ is also a BSNE operator which satisfies $F\left(\overleftarrow{P} r o j_{C}^{f} \circ A^{f}\right)=\hat{F}\left(\overleftarrow{P} r o j_{C}^{f} \circ A^{f}\right)$. From Proposition 4.4, we know that $F\left(\overleftarrow{P} \operatorname{roj}_{C}^{f} \circ A^{f}\right)=V(A, C)$. Therefore in Theorem 3.1, if we let $T_{i}=\overleftarrow{P} \operatorname{roj}_{C}^{f} \circ A^{f}$, we get an algorithm for finding a common solution to the variational inequality problem corresponding to infinitely many BISM operators and system of equilibrium problem.
Theorem 4.5. Let $E$ be a reflexive real Banach space and $C$ a nonempty, closed and convex subset of $E$. Let $A_{j}: E \rightarrow E^{*}, j \geq 1$, be an infinite family of BISM operators such that $C \subset \operatorname{dom} A_{j}$ and $\left\{T_{j}\right\}_{n=1}^{\infty}=\left\{\overleftarrow{\operatorname{Pr}} \operatorname{roj}_{C}^{f} \circ A_{j}^{f}\right\}_{j=1}^{\infty}$. Let $g_{k}: C \times$ $C \rightarrow \mathbb{R},(k=1,2, \ldots, N)$ be bifunctions satisfying conditions $(A 1)-(A 4)$. Let $B_{k}$ : $E \rightarrow E^{*},(k=1,2, \ldots, N)$ be continuous and monotone mappings, $\varphi_{k}: C \rightarrow \mathbb{R} \cup$ $\{+\infty\},(k=1,2, \ldots, N)$ be proper lower semicontinuous and convex functions. Let $f: E \rightarrow \mathbb{R}$ be a strongly coercive Legendre function which is bounded, uniformly Fréchet differentiable and totally convex on bounded subsets of $E$ such that $C \subset$ int(domf) and $A_{i}: E \rightarrow 2^{E^{*}}(i=1,2, \ldots, N)$ be maximal monotone operators, such that $\Omega:=\cap_{j=1}^{\infty} F\left(T_{j}\right) \cap\left(\cap_{k=1}^{N} E P\left(G_{k}\right) \cap\left(\cap_{i=1}^{N} A_{i}^{-1}(0)\right) \neq \emptyset\right.$. Then the sequence $\left\{x_{n}\right\}$ generated for arbitrary $u, x_{1} \in E$ by

$$
\left\{\begin{array}{l}
y_{n}=\operatorname{Res}_{\lambda_{n}^{N} A_{N}}^{f} \circ \operatorname{Res}_{\lambda_{n}^{N-1} A_{N-1}}^{f} \circ \cdots \circ \operatorname{Res}_{\lambda_{n}^{2} A_{2}}^{f} \circ \operatorname{Res}_{\lambda_{n}^{1} A_{1}}^{f} x_{n},  \tag{4.5}\\
u_{n}=\operatorname{Res} s_{G_{N}}^{f} \circ \operatorname{Res}_{G_{N-1}}^{f} \circ \ldots \circ \operatorname{Res}_{G_{2}}^{f} \circ \operatorname{Res}_{G_{1}}^{f} y_{n}, \\
x_{n+1}=\nabla f^{*}\left(\alpha_{n} \nabla f(u)+\beta_{n} \nabla f\left(u_{n}\right)+\sum_{j=1}^{\infty} \gamma_{n j} \nabla f\left(T_{j} u_{n}\right)\right), \forall n \geq 1,
\end{array}\right.
$$

converges strongly to a point $p=\overleftarrow{P} r o j_{\Omega}^{f} u \in \Omega$, where $G(x, y):=g(x, y)+\langle B x, y-$ $x\rangle+\varphi(y)-\varphi(x)$ and the sequences $\alpha_{n}, \beta_{n}, \gamma_{n j}$ and $\lambda_{n}$ satisfy the following conditions:
(i) $\lim _{n \rightarrow \infty} \alpha_{n}=0$;
(ii) $\sum_{n=1}^{\infty} \alpha_{n}=\infty$;
(iii) $\alpha_{n}+\beta_{n}+\sum_{j=1}^{\infty} \gamma_{n j}=1$;
(iv) $0<a<\beta_{n}, \sum_{j=1}^{\infty} \gamma_{n j}<b<1$;
(v) $\liminf _{n \rightarrow \infty} \lambda_{n}^{k}>0$ for each $k=1,2, \ldots, N$.

Acknowledgement. The first author acknowledge with thanks the bursary and financial support from Department of Science and Technology and National Re- search Foundation, Republic of South Africa Center of Excellence in Mathematical and Statistical Sciences (DST-NRF COE-MaSS) Doctoral Bursary. Opinions ex- pressed and
conclusions arrived are those of the authors and are not necessarily to be attributed to the CoE-MaSS.

## References

[1] R.P. Agarwal, J.W. Chen, Y.J. Cho, Z. Wan, Stability analysis for parametric generalized vector quasivariational-like inequality problems, J. Inequal. Appl., 57 (2012) 15 pp.
[2] Y.I. Alber, Generalized projection operators in Banach spaces: properties and applications, In: Proceedings of the Israel Seminar Ariel, Israel, Function Differential Equation, 1(1994), 1-21.
[3] Y.I. Alber, Metric and generalized projection operators in Banach spaces: properties and applications, In Kartsatos, A.G. (ed.) Theory and Applications of Nonlinear Operators of Monotonic and Accretive Type, M. Dekker New York, 1996, 15-50.
[4] Y.I. Alber, D. Butnariu, Convergence of Bregman projection methods for solving consistent convex feasibility problems in reflexive Banach spaces, J. Optim. Theory Appl., 92(1997), 3361.
[5] H.H. Bauschke, J.M. Borwein, Legendre functions and the method of random Bregman projections, J. Convex Anal., 4(1997), 27-67.
[6] H.H. Bauschke, J.M. Borwein, P.L. Combettes, Essential smoothness, essential strict convexity, and Legendre functions in Banach spaces, Commun. Contemp. Math., 3(2001), 615-647.
[7] H.H. Bauschke, J.M. Borwein, P.L. Combettes, Bregman monotone optimization algorithms, SIAM J. Control Optim., 42(2003), 596-636.
[8] H.H. Bauschke, A.S. Lewis, Dykstra's algorithm with Bregman projections: a convergence proof, Optimization, 48(2000), 409-427.
[9] E. Blum, W. Oettli, From optimization and variational inequalities to equilibrium problems, Math. Student, 63(1994), 123-145.
[10] J.F. Bonnans, A. Shapiro, Perturbation Analysis of Optimization Problems, Springer, New York, 2000.
[11] J.M. Borwein, S. Reich, S. Sabach, A characterization of Bregman firmly nonexpansive operators using a new monotonicity concept, J. Nonlinear Convex Anal., 12(2011), 161-184.
12] L.M. Bregman, The relaxation method for finding common points of convex sets and its application to the solution of problems in convex programming, USSR Comput. Math. Math. 17 Phys., 7(1967), 200-217.
[13] H. Brézis, P.L. Lions, Produits infinis de résolventes, Israel J. Math., 29(1978), 329-345.
[14] R.S. Burachik, A.N. Iusem, A generalized proximal point algorithm for the variational inequality problem in Hilbert space, SIAM J. Optim., 8(1998), 197-216.
[15] D. Butnariu, Y. Censor, S. Reich, Iterative averaging of entropic projections for solving stochastic convex feasibility problems, Comput. Optim. Appl., 8(1997), 21-39.
[16] D. Butnariu, A.N. Iusem, Totally Convex Functions for Fixed Points Computation and Infinite Dimensional Optimization, Applied Optimization, vol. 40, Kluwer Academic, Dordrecht, 2000.
[17] D. Butnariu, A.N. Iusem, C. Zalinescu, On uniform convexity, total convexity and con-vergence of the proximal point and outer Bregman projection algorithms in Banach spaces, J. Convex Anal., 10(2003), 35-61.
[18] D. Butnariu, G. Kassay, A proximal-Projection method for finding zeroes of set valued operators, SIAM J. Control Optim., 47(2008), 2096-2136.
[19] D. Butnariu, E. Resmerita, Bregman distances, totally convex functions, and a method for solving operator equations in Banach spaces, Abstr. Appl. Anal., (2006), 1-39.
[20] R.S. Burachik, Generalized proximal point methods for the variational inequality problem, Ph.D. Thesis, Instituto de Mathematica Pura e Aplicada (IMPA), Rio de Janeiro, 1995.
[21] R.S. Burachik, S. Scheimberg, A proximal point method for the variational inequality problem in Banach spaces, SIAM J. Control Optim., 39(2000), 1633-1649.
[22] Y. Censor, A. Lent, An iterative row-action method for interval convex programming, J. Optim. Theory Appl., 34(1981), 321-353.
[23] J.W. Chen, Z. Wan, L. Yuan et al., Approximation of fixed points of weak Bregman relatively nonexpansive mappings in Banach spaces, Int. J. Math. Math. Sci., (2011), 1-23.
[24] P. Cholamjiak, Y.J. Cho, S. Suantai, Composite iterative schemes for maximal monotone operators in reflexive Banach spaces, Fixed Point Theory Appl., 2011.
[25] P. Cholamjiak, S. Suantai, Convergence analysis for a system of equilibrium problems and a countable family of relatively quasi-nonexpansive mappings in Banach spaces, Abstr. Appl. Anal., vol. 2010, Article ID 141376, 17 pages.
[26] P.L. Combettes, S.A. Hirstoaga, Equilibrium programming in Hilbert spaces, J. Nonlinear Convex Anal., 6(2005), 117-136.
[27] I. Eckstein, Nonlinear proximal point algorithms using Bregman function, with applications to convex programming, Math. Oper. Res., 18(1993), 202-226.
[28] F. Giannessi, A. Maugeri, P.M. Pardalos (Eds.), Equilibrium Problems: Nonsmooth Optimization and Variational Inequality Models, Springer, 58(2002).
[29] O. Güler, On the convergence of the proximal point algorithm for convex minimisation, SIAM J. Control Optim., 29(1991), 403-419.
[30] S. Kamimura, W. Takahashi, Approximating solutions of maximal monotone operators in Hilbert spaces, J. Approx. Theory, 106(2000), 226-240.
[31] K.C. Kiwiel, Proximal minimization methods with generalized Bregman functions, SIAM J. Control Optim., 35(1997), 1142-1168.
[32] F. Kohsaka, W. Takahashi, Proximal point algorithms with Bregman functions in Banach spaces, J. Nonlinear Convex Anal., 6(2005), 505-523.
[33] Y. Liu, A general iterative method for equilibrium problems and strict pseudo-contractions in Hilbert spaces, Nonlinear Anal., 71(2009), 4852-4861.
[34] P.E. Maingé, Strong convergence of projected subgradient methods for nonsmooth and nonstrictly convex minimization, Set-Valued Anal., 16(2008), 899-912.
[35] B. Martinet, Régularisation d'inéquations variationelles par approximations successives, Rev. Francaise d'Informatique et de Recherche Opérationelle, 4(1970), 154-159.
[36] V. Martin-Márquez, S. Reich, S. Sabach, Right Bregman nonexpansive operators in Banach spaces, Nonlinear Anal., 75(2012), 5448-5465.
[37] V. Martin-Márquez, S. Reich, S. Sabach, Iterative methods for approximating fixed points of Bregman nonexpansive operators, Discrete and Continuous Dynamical Systems S-series, 6(2013), no. 4, 1043-1063
[38] G.B. Passty, Ergodic convergence to zero of the sum of monotone operators in Hilbert space, J. Math. Anal. Appl., 72(1979), 383-390.
[39] R.P. Phelps, Convex Functions, Monotone Operators, and Differentiability, 2nd Edition, in: Lecture Notes in Mathematics, vol. 1364, Springer Verlag, Berlin, 1993.
[40] X. Qin, S.M. Kang, Y.J. Cho, Convergence theorems on generalized equilibrium problems and fixed point problems with applications, Proc. Estonian Acad. Sci., 58(2009), 170-318.
[41] X. Qin, Y.J. Cho, S.M. Kang, Convergence theorems of common elements for equilibrium problems and fixed point problems in Banach spaces, J. Comput. Appl. Math., 225(2009), 20-30.
[42] S. Reich, A weak convergence theorem for the alternating method with Bregman distances, Theory and Applications of Nonlinear Operators of Accretive and Monotone Type, Lecture Notes in Pure and Appl. Math., vol. 178, Dekker, New York, 1996, 313-318.
[43] S. Reich, S. Sabach, A strong convergence theorem for a proximal-type algorithm in reflexive Bnanch spaces, J. Nonlinear Convex Anal., 10(2009), 471-485.
[44] S. Reich, S. Sabach, Two strong convergence theorems for a proximal method in reflexive Banach spaces, Numer. Funct. Anal. Optim., 31(2010), 22-44.
[45] S. Reich, S. Sabach, Two strong convergence theorems for Bregman strongly nonexpansive operators in reflexive Banach spaces, Nonlinear Anal., 73(2010), 122-135.
[46] S. Reich, S. Sabach, Existence and approximation of fixed points of Bregman firmly nonexpansive mappings in reflexive Banach spaces, in: Fixed-Point Algorithms for Inverse Problems in Science and Engineering, Springer, New York, 2011, 299-314.
[47] S. Reich, S. Sabach, A projection method for solving nonlinear problems in reflexive Banach spaces, J. Fixed Point Theory Appl., 9(2011), 101-116.
[48] E. Resmerita, On total convexity, Bregman projections and stability in Banach spaces, J. Convex Anal., 11(2004), 1-16.
[49] R.T. Rockafellar, Monotone operators and the proximal point algorithm, SIAM J. Control Optim., 14(1976), 877-898.
50] M.V. Solodov, B.F. Svaiter, Forcing strong convergence of proximal point iterations in a Hilbert space, Math. Program., 87(2000), 189-202.
51] M.V. Solodov, B.F. Svaiter, An inexact hybrid generalized proximal point algorithm and some new results on the theory of Bregman functions, Math. Oper. Res., 25(2000), 214-230.
[52] S. Suantai, Y.J. Cho, P. Cholamjiak, Halpern's iteration for Bregman strongly nonexpansive mappings in reflexive Banach spaces, Comp. Math. Appl., 64 (2012), 489-499.
[53] H.K. Xu, Iterative algorithms for nonlinear operators, J. London Math. Soc., 66(2002), no. 2 , 240-256.
[54] S. Zhang, Generalized mixed equilibrium problem in Banach spaces, Applied Math. Mechanics (English Edition), 30(2009), 1105-1112.

Received: September 22, 2015; Accepted: July 28, 2016.

