NONLINEAR FOURTH-ORDER DYNAMIC EQUATIONS ON UNBOUNDED TIME SCALES

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Abstract. In this paper, we investigate nonlinear fourth-order dynamic equations on unbounded time scales. The existence and uniqueness of the solutions for these problems are obtained.

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1. INTRODUCTION

It is well known that the time scale calculus is a unification of continuous and discrete calculus. It was introduced in [10]. The dynamic equations on time scales have received in recent years a considerable attention see for instance [4-7, 11, 12, 15-17].

At present, there have been some studies on fourth-order dynamic equations [6,7,11,12,15-17]. To the authors' knowledge, there is no work on the existence of solutions for singular fourth-order dynamic problems in the lim-4 case so our problem is very different from the papers in the literature. A similar way was employed earlier in the differential and difference operator cases in [1-3,9,18].

Let \mathbb{T} be a time scale which is unbounded from above such that $\sup \mathbb{T} = \infty$. We will denote \mathbb{T} also as $[0, \infty)_{\mathbb{T}}$. Some preliminary definitions and theorems on time scales can be found in [5].

The space $L^2_{\Delta}[a,\infty)_{\mathbb{T}}$ is a Hilbert space consisting of all real-valued functions y such that

$$\int_0^\infty |y(x)|^2 \Delta \xi < \infty$$

with the inner product

$$\langle f,g\rangle:=\int_0^\infty f\left(\xi\right)g\left(\xi\right)\Delta\xi,\ f,g\in L^2_\Delta[0,\infty)_{\mathbb{T}}.$$

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We consider the nonlinear fourth-order dynamic equation

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(1)
$$(\Upsilon x) (\xi) := (p_0 x^{\bigtriangleup \bigtriangledown})^{\bigtriangledown \bigtriangleup} (\xi) - (p_1 x^{\bigtriangledown})^{\bigtriangleup} (\xi) + p_2 (\xi) x (\xi)$$
$$= f (\xi, x (\xi)), \ \xi \in [0, \infty)_{\mathbb{T}},$$

and assume that p_0 , p_1 and p_2 are real-valued; p_0^{-1} , p_1 and p_2 are locally Δ -integrable functions on $[0, \infty)_{\mathbb{T}}$, and $p_0 > 0$ on $[0, \infty)_{\mathbb{T}}$.

Yardımcı and Ugurlu [18] have studied equation (1) for when $\mathbb{T} = [0, \infty)$. For simplicity of notations, we write

$$x^{[0]} = x$$

$$x^{[1]} = x^{\Delta}$$

$$x^{[2]} = p_0 x^{\Delta \nabla}$$

$$x^{[3]} = p_1 x^{\nabla} - \left(x^{[2]}\right)^{\nabla}$$

$$x^{[4]} = p_2 x - \left(x^{[3]}\right)^{\Delta}$$

Then, Green's formula for solutions x(.) and z(.) is given by

$$\int_0^\infty (\Upsilon x) (\xi) z(\xi) \Delta \xi - \int_0^\infty x(\xi) (\Upsilon z) (\xi) \Delta \xi = [x, z]_\infty - [x, z]_0,$$

where

$$[x,z]_{\xi} := x^{[0]}(\xi)z^{[3]}(\xi) - x^{[3]}(\xi)z^{[0]}(\xi) + x^{[1]}(\xi)z^{[2]}(\xi) - x^{[2]}(\xi)z^{[1]}(\xi)$$

and

$$[x,z]_{\infty} := \lim_{\xi \to \infty} [x,z]_{\xi}$$

(see [4]). It is clear that $[x, z]_{\infty}$ exists and is finite. Let

$$D_{\max} = \left\{ x \in L^2_{\Delta}[0,\infty)_{\mathbb{T}} : \begin{array}{l} \text{the first three } \Delta \text{ derivatives are} \\ \text{locally } \Delta \text{-absolutely continuous in} \\ [0,\infty)_{\mathbb{T}}, \text{ and } \Upsilon(x) \in L^2_{\Delta}[0,\infty)_{\mathbb{T}}. \end{array} \right\},$$

and

$$D_{\min} = \left\{ x \in D_{\max} : \begin{array}{c} x^{[0]}(0) = x^{[1]}(0) = x^{[2]}(0) = x^{[3]}(0) = 0, \\ [x, z]_{\infty} = 0, \ \forall z \in D_{\max}. \end{array} \right\}.$$

Then, the maximal operator Γ_{\max} is defined on D_{\max} by the formula

$$\Gamma_{\max} x = \Upsilon x$$

If we restrict the operator Γ_{max} to the set D_{\min} , then we obtain the minimal operator Γ_{\min} . It is clear that $\Gamma^*_{\min} = \Gamma_{\max}$, and Γ_{\min} is a closed symmetric operator with deficiency indices (2,2), (3,3), (4,4) (see [8,14]).

We will assume that the following conditions are satisfied.

(A1) The lim-4 Case holds for $\Upsilon x = 0$ (see [8]).

(A2) $f(\xi,\zeta)$ is real-valued and continuous in $(\xi,\zeta) \in [0,\infty)_{\mathbb{T}} \times \mathbb{R}$, and, for all (ξ, ζ) in $[0, \infty)_{\mathbb{T}} \times \mathbb{R}$, $f(\xi, \zeta)$ satisfies the following condition:

(2)
$$|f(\xi,\zeta)| \le g(\xi) + \varrho|\zeta|,$$

where $g(\xi) \ge 0$, $g \in L^2_{\Delta}[0,\infty)_{\mathbb{T}}$, and $\varrho > 0$. Let $y_i, 1 \le i \le 4$, be the solutions of equation (1) subject to the following normalization conditions:

$$p_0^2(t) W_{\Delta}(y_1, y_2, y_3, y_4) = 1$$

and

$$\begin{split} y_1^{[0]}(0) &= \cos \alpha, \ y_1^{[1]}(0) = y_1^{[2]}(0) = 0, \ y_1^{[3]}(0) = -\sin \alpha, \\ y_2^{[0]}(0) &= 0, \ y_2^{[1]}(0) = \sin \beta, \ y_2^{[2]}(0) = -\cos \beta, \ y_2^{[3]}(0) = 0, \\ y_3^{[0]}(0) &= \sin \alpha, \ y_3^{[1]}(0) = y_3^{[2]}(0) = 0, \ y_3^{[3]}(0) = \cos \alpha, \\ y_4^{[0]}(0) &= 0, \ y_4^{[1]}(0) = \cos \beta, \ y_4^{[2]}(0) = \sin \beta \ y_4^{[3]}(0) = 0, \end{split}$$

where $\alpha, \beta \in \mathbb{R}$,

$$\begin{bmatrix} [y_1, y_1] & [y_2, y_1] & [y_3, y_1] & [y_4, y_1] \\ [y_1, y_2] & [y_2, y_2] & [y_3, y_2] & [y_4, y_2] \\ [y_1, y_3] & [y_2, y_3] & [y_3, y_3] & [y_4, y_3] \\ [y_1, y_4] & [y_2, y_4] & [y_3, y_4] & [y_4, y_4] \end{bmatrix} = \begin{bmatrix} 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix},$$

and

$$W_{\Delta}(y_1, y_2, y_3, y_4) = \begin{vmatrix} y_1 & y_2 & y_3 & y_4 \\ y_1^{[1]} & y_2^{[1]} & y_3^{[1]} & y_4^{[1]} \\ y_1^{[2]} & y_2^{[2]} & y_3^{[2]} & y_4^{[2]} \\ y_1^{[3]} & y_2^{[3]} & y_3^{[3]} & y_4^{[3]} \\ y_1^{[3]} & y_2^{[3]} & y_3^{[3]} & y_4^{[3]} \end{vmatrix}$$

(see [4]).

Now, we will impose the following conditions

(3)
$$\begin{aligned} x^{[0]}(0)\sin\alpha + x^{[3]}(0)\cos\alpha &= 0,\\ x^{[1]}(0)\cos\beta + x^{[2]}(0)\sin\beta &= 0,\\ [x, y_3]_{\infty} - d_1 [x, y_1]_{\infty} &= 0,\\ [x, y_4]_{\infty} - d_2 [x, y_2]_{\infty} &= 0, \end{aligned}$$

where $\alpha, \beta, d_1, d_2 \in \mathbb{R}$.

2. MAIN RESULTS

Let us consider the following problem

$$(\Upsilon x)(\xi) = h(\xi),$$

where $\xi \in (0, \infty)$ and $h \in L^2_{\Delta}[0, \infty)_{\mathbb{T}}$. Let

$$\varphi\left(\xi\right) = \left(\begin{array}{c} y_1\left(\xi\right)\\ y_2\left(\xi\right) \end{array}\right) \text{ and } \psi\left(\xi\right) = \left(\begin{array}{c} y_3\left(\xi\right) - d_1y_1\left(\xi\right)\\ y_4\left(\xi\right) - d_2y_2\left(\xi\right) \end{array}\right).$$

Then, the solution of the boundary-value problem (3), (4) is defined by the formula

$$x\left(\xi\right) = \int_{0}^{\infty} G\left(\xi, t\right) h\left(t\right) \Delta t,$$

where $\xi \in (0, \infty)$ and

$$G\left(\xi,t\right) = \begin{cases} \varphi^{T}\left(\xi\right)\psi\left(t\right), & \text{if } t \leq \xi, \\ \varphi^{T}\left(t\right)\psi\left(\xi\right), & \text{if } t > \xi, \end{cases}$$

where x^T denotes the transpose of the vector x.

Thus, the problem (1), (3) is equivalent to the following equation

(5)
$$x(\xi) = \int_0^\infty G(\xi, t) f(t, x(t)) \Delta t$$

From (A1), we infer that

(6)
$$\int_0^\infty \int_0^\infty |G(\xi,t)|^2 \,\Delta\xi \Delta t < \infty.$$

Now, we can define an operator

$$T: L^2_{\Delta}[0,\infty)_{\mathbb{T}} \to L^2_{\Delta}[0,\infty)_{\mathbb{T}}$$

as follows:

(7)
$$(Tx) (\xi) = \int_0^\infty G(\xi, t) f(t, x(t)) \Delta t, \ \xi \in (0, \infty),$$

where $x \in L^2_{\Delta}[0,\infty)_{\mathbb{T}}$. Hence (5) can be written as x = Tx.

THEOREM 2.1. Suppose that conditions (A1) and (A2) are satisfied. Further, let $f(\xi, y)$ satisfy the following Lipschitz condition: there exists a constant K > 0 such that

$$\int_{0}^{\infty} |f(\xi, x(\xi)) - f(\xi, z(\xi))|^{2} \Delta \xi \le K^{2} \int_{0}^{\infty} |x(\xi) - z(\xi)|^{2} \Delta \xi$$

for all $x, z \in L^2_{\Delta}[0, \infty)_{\mathbb{T}}$. If

$$K\left(\int_0^\infty \int_0^\infty |G\left(\xi,t\right)|^2 \Delta\xi \Delta t\right)^{1/2} < 1,$$

then the problem (1), (3) has a unique solution in $L^2_{\Delta}[0,\infty)_{\mathbb{T}}$.

(4)

Proof. For $x, z \in L^2_{\Delta}[0,\infty)_{\mathbb{T}}$, we see that

$$\begin{split} &|(Tx) (\xi) - (Tz) (\xi)|^2 \\ &= \left| \int_0^\infty G(\xi, t) \left[f(t, x(t)) - f(t, z(t)) \right] \Delta t \right|^2 \\ &\leq \int_0^\infty |G(\xi, t)|^2 \Delta t \int_0^\infty |f(t, x(t)) - f(t, z(t))|^2 \Delta t \\ &\leq K^2 \, \|x - z\|^2 \int_0^\infty |G(\xi, t)|^2 \Delta t, \ \xi \in (a, \infty) \,. \end{split}$$

Thus, we get

$$\left\|Tx - Tz\right\| \le \alpha \left\|x - z\right\|,$$

where

$$\alpha = K \left(\int_0^\infty \int_0^\infty |G(\xi, t)|^2 \, \Delta\xi \Delta t \right)^{1/2} < 1. \qquad \Box$$

THEOREM 2.2. Suppose that conditions (A1) and (A2) are satisfied. Further, let us assume that the following condition holds: there exist constants M, K > 0 such that

$$\int_{0}^{\infty} |f(\xi, x(\xi)) - f(\xi, z(\xi))|^{2} \Delta \xi \le K^{2} \int_{0}^{\infty} |x(\xi) - z(\xi)|^{2} \Delta \xi$$

for all x and z in

$$S_M = \left\{ x \in L^2_\Delta[0,\infty)_{\mathbb{T}} : ||x|| \le M \right\},\$$

where K may depend on M. If

$$\left(\int_0^\infty \int_0^\infty |G\left(\xi,t\right)|^2 \Delta\xi \Delta t\right)^{1/2} \sup_{x \in S_M} \left(\int_0^\infty |f\left(t,x\left(t\right)\right)|^2 \Delta t\right)^{1/2} \le M$$

and

$$K\left(\int_0^\infty \int_0^\infty \left|G\left(\xi,t\right)\right|^2 \Delta\xi \Delta t\right)^{1/2} < 1,$$

then the problem (1), (3) has a unique solution satisfying

$$\int_0^\infty |x(\xi)|^2 \,\Delta\xi \le M^2.$$

$$\begin{aligned} \|Tx\| &= \left\| \int_0^\infty G\left(.,t\right) f\left(t,x\left(t\right)\right) \Delta t \right\| \\ &\leq \left\| \int_0^\infty G\left(.,t\right) f\left(t,x\left(t\right)\right) \Delta t \right\| \\ &\leq \left(\int_0^\infty \int_0^\infty |G\left(\xi,t\right)|^2 \Delta \xi \Delta t \right)^{1/2} \sup_{x \in S_M} \left\{ \int_0^\infty |f\left(t,x\left(t\right)\right)|^2 \Delta t \right\}^{1/2} \\ &\leq M. \end{aligned}$$

An analysis similar to that in the proof of Theorem 2.1 shows that

$$||Tx - Tz|| \leq \alpha ||x - z||$$
, where $x, z \in S_M$.

From the Banach fixed point theorem, we get the desired result.

Now, we show that nonlinear problems may have solutions without uniqueness. In order to get this result, we will use the following Schauder fixed point theorem.

DEFINITION 2.3 ([9]). An operator acting in a Banach space is said to be completely continuous if it is continuous and if it maps bounded sets into relatively compact sets.

THEOREM 2.4 ([9]). Let **B** be a Banach space and **S** a non-empty bounded, convex, and closed subset of **B**. Assume $A : \mathbf{B} \to \mathbf{B}$ is a completely continuous operator. If the operator A leaves the set **S** invariant, i.e., if $A(\mathbf{S}) \subset \mathbf{S}$, then A has at least one fixed point in **S**.

THEOREM 2.5. Suppose that conditions (A1) and (A2) are satisfied. Then T defined by (7) is a completely continuous operator.

Proof. Let $x_0 \in L^2_{\Delta}[0,\infty)_{\mathbb{T}}$. Then, we obtain

$$|(Tx) (\xi) - (Tx_0) (\xi)|^2$$

= $\left| \int_0^\infty G(\xi, t) [f(t, x(t)) - f(t, x_0(t))] \Delta t \right|^2$
 $\leq \int_0^\infty |G(\xi, t)|^2 \Delta t \int_0^\infty |f(t, x(t)) - f(t, x_0(t))|^2 \Delta t.$

Thus

(8)
$$||Tx - Tx_0||^2 \le K \int_a^\infty |f(t, x(t)) - f(t, x_0(t))|^2 \Delta t$$

where

$$K = \left(\int_0^\infty \int_0^\infty |G(\xi, t)|^2 \,\Delta\xi \Delta t\right).$$

It is evident that an operator T defined by $Tx(\xi) = f(\xi, x(\xi))$ is continuous in $L^2_{\Delta}[0,\infty)_{\mathbb{T}}$ under the condition **(A2)** (see [13]). Hence, for the given $\epsilon > 0$, we can find a $\delta > 0$ such that $||x - x_0|| < \delta$ implies

$$\int_0^\infty \left|f\left(t, x\left(t\right)\right) - f\left(t, x_0\left(t\right)\right)\right|^2 \Delta t < \frac{\epsilon^2}{K}.$$

From (8), we get

$$\|Tx - Tx_0\| < \epsilon.$$

Let

$$Y = \left\{ x \in L^2_{\Delta}[0,\infty)_{\mathbb{T}} : \|x\| \le C \right\}.$$

By (7), we have

$$||Tx|| \le \left\{ K \int_{a}^{\infty} |f(t, x(t))|^2 \Delta t \right\}^{1/2},$$

for all $x \in Y$. Furthermore, using (2), we get

$$\begin{split} \int_0^\infty |f\left(t, x\left(t\right)\right)|^2 \Delta t &\leq \int_0^\infty \left[g\left(t\right) + \varrho \left|x\left(t\right)\right|\right]^2 \Delta t \\ &\leq 2 \int_0^\infty \left[g^2\left(t\right) + \varrho^2 \left|x\left(t\right)\right|^2\right] \Delta t \\ &= 2 \left(\left\|g\|^2 + \varrho^2 \left\|x\|^2\right) \\ &\leq 2 \left(\left\|g\|^2 + \varrho^2 C^2\right). \end{split}$$

Therefore, for all $x \in Y$, we see that

$$||Tx|| \le \left[2K\left(||g||^2 + \varrho^2 C^2\right)\right]^{1/2}.$$

Further, for all $x \in Y$, we have

$$\int_{N}^{\infty} |Tx(\xi)|^2 \Delta \xi \le 2\left(||g||^2 + \varrho^2 C^2\right) \int_{N}^{\infty} \int_{0}^{\infty} |G(\xi,t)|^2 \Delta \xi \Delta t.$$

So, from (6), we conclude that for given $\epsilon > 0$ there exists a positive number N, depending only on ϵ such that

$$\int_{N}^{\infty} |Tx(\xi)|^2 \,\Delta\xi < \epsilon^2,$$

for all $x \in Y$.

Hence T(Y) is relatively compact in the space $L^{2}_{\Delta}[0,\infty)_{\mathbb{T}}$.

THEOREM 2.6. Suppose that conditions (A1) and (A2) are satisfied. Further, we assume that there exists constant M > 0 such that

(9)
$$\left(\int_{0}^{\infty}\int_{0}^{\infty}|G(\xi,t)|^{2}\Delta\xi\Delta t\right)^{1/2}\sup_{x\in S_{M}}\left\{\int_{0}^{\infty}|f(t,x(t))|^{2}\Delta t\right\}^{1/2}\leq M,$$

where $S_M = \{x \in L^2_{\Delta}[a, \infty)_{\mathbb{T}} : ||x|| \leq M\}$. Then the problem (1), (3) has at least one solution with

$$\int_0^\infty |x(\xi)|^2 \,\Delta\xi \le M^2.$$

Proof. Let $T: L^2_{\Delta}[0,\infty)_{\mathbb{T}} \to L^2_{\Delta}[0,\infty)_{\mathbb{T}}$ be the operator defined in (7). It follows from Theorems 2.2, 2.5, and (9) that T maps the set S_M into itself. Moreover, the set S_M is bounded, convex and closed. From the Schauder fixed point theorem, we get the desired result. \Box

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