

COURNOT EQUILIBRIUM  
IN CASE OF (-1)-CONCAVE PRICE FUNCTION

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**Abstract.** We consider a class of homogeneous Cournot oligopolies with  $(-1)$ -concave price function. We show some useful properties of the revenue function in case of  $(-1)$ -concave price function and prove the existence of an equilibrium in the continuous and non-differentiable case. A simple proof of an equilibrium uniqueness result in the smooth case with  $(-1)/N$ -concave ( $N$ -number of the firms in the market) price function is provided.

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**Key words.** Cournot games, generalized concavity, price function, pure-strategy Nash equilibrium.

1. INTRODUCTION

Various results in the literature guarantee the existence of a unique Cournot equilibrium in homogeneous Cournot oligopolies. One of the first results is in Murphy et. al (1982) [8], and employs concave revenue functions and convex cost functions. Amir (1996) [1], shows that log-concavity of the inverse demand guarantees the existence of an equilibrium and in case of convex cost functions the uniqueness of the equilibrium. Deneckere and Kovenock (1999) [4] derive an existence and uniqueness theorem using assumptions based on the direct demand function. This theorem is restated, using the concept of  $\rho$ -concavity, in [2]. Biconcavity is a condition on the inverse demand that corresponds to concavity after a simultaneous parametrization of price and quantity, the price function is  $(\alpha, \beta)$ -biconcave if and only if the demand function is  $(\beta, \alpha)$ -biconcave. Ewerhart (2014) [5] uses this concept to analyze the Cournot model. The existence theorem in his paper admits values of  $0 \leq \alpha \leq 1$  in the non-smooth case and  $\alpha < 0$  in the case of twice differentiable price function. von Mouche and Quartieri (2013) [9] define the concept of concave integrated price flexibility to provide new results about semi-uniqueness and uniqueness of Cournot equilibria.

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(-1)-concavity of the price function corresponds to  $(-1, 1)$ -biconcavity, i.e.  $\alpha < 0$ . We prove some properties of the revenue function in case of  $(-1)$ -concavity of the price function without assuming differentiability and we prove the existence theorem in the non-smooth case with convex costs functions. Employing the same approach as in [9] and [10] we derive a simple proof of the uniqueness theorem in the smooth case with  $(-1)/N$ -concave price function and convex costs functions ( $N$ -number of the firms in the market), without assuming twice differentiability. The uniqueness theorem for log-concave (0-concave) price function is a consequence of our result. We also show that the property of concave price flexibility, assumed in [9] does not entail  $(-1)$ -concavity. To the best of our knowledge the conditions we impose are not entailed by any other conditions used in the proofs of the existence and uniqueness theorems of a Cournot equilibrium so far.

The paper is organized as follows: Section 2 introduces the concept of a Cournot game and lists some results from the literature that will be used in our proofs. Section 3 introduces the concept of generalized concavity and provides some properties of the revenue function in the case of  $(-1)/N$ -concavity of the price function. In Section 4 existence and uniqueness theorems are derived. In Section 5 concluding remarks are given.

## 2. BACKGROUND AND SETTINGS

Cournot oligopoly is a game with perfect information,  $N$  players (firms) that produce a homogenous product and compete on quantities. Each firm has a cost  $c_i(x_i)$  for producing  $x_i \geq 0$ ,  $i = 1, \dots, N$ . The market price is a function of the firms' total output  $x_1 + \dots + x_N = X$ . Let  $\tilde{N} = \{1, \dots, N\}$ ; the profit of the  $i$ -th firm is given by:

$$f_i(X) = x_i P\left(x_i + \sum_{j \in \tilde{N}, j \neq i} x_j\right) - c_i(x_i).$$

A Nash equilibrium of an oligopoly is called a Cournot equilibrium.

We will provide the following results from [9] in the framework for our needs.

LEMMA 2.1. *Suppose each cost function is convex and:*

- $p$  is left and right differentiable at each point of  $R_+$ ;
- $d^+p(x) \leq d^-p(x) < 0$  ( $x \in R_+$ ).

*If there exists more than one equilibrium, then 0 is not an equilibrium.*

THEOREM 2.2. *Suppose each cost function is convex and:*

- $p$  is left and right differentiable at each point of  $R_+$ ;
- $d^-p(x) \leq d^+p(x) < 0$  ( $x \in R_+$ ).

*Then the Nash-sums are injective.*

We will use the following classical existence theorem (Debreu, Glicksberg, Fan (1952) [3, 6, 7]):

**THEOREM 2.3.** Consider a game with  $N \geq 2$  players with strategies  $s_i \in S_i$ ,  $i = 1, \dots, N$ . If:

- $S_i, i = 1, \dots, N$  are nonempty, compact, convex subsets of finite dimensional Euclidean spaces,
- all pay-off functions are continuous on  $S_1 \times \dots \times S_N$ ,
- all payoff functions are quasi-concave of  $s_i$  over  $S_i$ , if all the other strategy sets are held fixed,

then there exists at least one equilibrium.

### 3. GENERALIZED CONCAVITY OF FUNCTIONS

We consider a function  $p : \Omega \rightarrow R_+$  defined on a convex set  $\Omega \subseteq R_+$ .

**DEFINITION 3.1.** A positive function defined on a convex set  $\Omega \subseteq R_+$  is said to be  $\alpha$ -concave, where  $\alpha \in [-\infty, +\infty]$ , if for all  $x, y \in \Omega$  and all  $\lambda \in [0, 1]$  the following inequality holds true:

$$p(\lambda x + (1 - \lambda)y) \geq m_\alpha(p(x), p(y), \lambda),$$

where  $m_\alpha : R_+ \times R_+ \times [0, 1] \rightarrow R$  is defined as follows:

$$m_\alpha(a, b, \lambda) = \begin{cases} a^\lambda b^{1-\lambda}, & \text{if } \alpha = 0 \\ \max\{a, b\}, & \text{if } \alpha = \infty \\ \min\{a, b\}, & \text{if } \alpha = -\infty \\ (\lambda a^\alpha + (1 - \lambda)b^\alpha)^{1/\alpha}, & \text{otherwise.} \end{cases}$$

In the case  $\alpha = 0$  the function is log-concave, in the case  $\alpha = 1$  the function is simply concave.

The following lemma is very important, because it implies that  $\alpha$ -concavity entails  $\beta$ -concavity, for all  $\beta \leq \alpha$ .

**LEMMA 3.2.** The mapping  $\alpha \rightarrow m_\alpha(a, b, \lambda)$  is non-decreasing and continuous.

We are interested especially in  $(-1)/n$ -concave functions,  $n \geq 1$ :

**DEFINITION 3.3.** A positive function defined on a convex set  $\Omega \subseteq R_+$  is said to be  $(-1)/n$ -concave,  $n \geq 1$ , if for all  $x, y \in \Omega$  and all  $\lambda \in [0, 1]$  the following inequality holds true:

$$p(\lambda x + (1 - \lambda)y) \geq (\lambda(p(x))^{-1/n} + (1 - \lambda)(p(y))^{-1/n})^{-n}.$$

From Lemma 3.2 it follows that all concave ( $\alpha = 1$ ) and log-concave ( $\alpha = 0$ ) functions are  $(-1)/n$ -concave. It is clear that a positive function  $p(\cdot)$  is  $(-1)/n$ -concave if and only if  $1/p(\cdot)^{1/n}$  is convex.

**THEOREM 3.4.** Let  $p : \Omega \subseteq R_+ \cup \{0\} \rightarrow R_+$  be a decreasing, continuous and  $(-1)/n$ -concave function and let  $n \geq 1$ . Then  $xp(x + k)^{1/n}$  is strictly concave on the interval where it is strictly increasing for all  $k \geq 0$ .

*Proof.* Let  $x_1, x_2 \in \Omega$  with  $x_1 < x_2$  and

$$(1) \quad x_1 p(x_1 + k)^{1/n} < x_2 p(x_2 + k)^{1/n}.$$

Note that convexity (concavity) is equivalent to midpoint convexity (concavity) in the case of a continuous function. The function  $p(\cdot)$  is a continuous and  $(-1)/n$ -concave function, therefore  $1/p(x+k)^{1/n}$ ,  $k \geq 0$ , is convex and midpoint convex. We get

$$\frac{1}{p\left(\frac{x_1+x_2}{2} + k\right)^{1/n}} \leq \left( \frac{1}{p(x_1+k)^{1/n}} + \frac{1}{p(x_2+k)^{1/n}} \right) / 2.$$

Hence,

$$(2) \quad p\left(\frac{x_1+x_2}{2} + k\right)^{1/n} \geq \frac{2p(x_1+k)^{1/n}p(x_2+k)^{1/n}}{p(x_1+k)^{1/n} + p(x_2+k)^{1/n}}.$$

Suppose  $xp(x+k)^{1/n}$  is not strictly midpoint concave on the interval where it is strictly increasing:

$$\frac{x_1+x_2}{2} p\left(\frac{x_1+x_2}{2} + k\right)^{1/n} \leq \frac{x_1 p(x_1+k)^{1/n} + x_2 p(x_2+k)^{1/n}}{2}.$$

From (2), we have

$$\frac{x_1+x_2}{2} \frac{2p(x_1+k)^{1/n}p(x_2+k)^{1/n}}{p(x_1+k)^{1/n} + p(x_2+k)^{1/n}} \leq \frac{x_1 p(x_1+k)^{1/n} + x_2 p(x_2+k)^{1/n}}{2},$$

which yields

$$(x_1+x_2)p(x_1+k)^{1/n}p(x_2+k)^{1/n} \leq x_1 p(x_1+k)^{2/n} + x_2 p(x_2+k)^{2/n},$$

or

$$\begin{aligned} & x_1((p(x_1+k))^{2/n} - p(x_1+k)^{1/n}p(x_2+k)^{1/n}) \\ & \geq x_2(p(x_1+k)^{1/n}(p(x_2+k)^{1/n} - p(x_2+k)^{2/n}). \end{aligned}$$

Dividing by  $p(x_1+k)^{1/n} - p(x_2+k)^{1/n} > 0$ , we obtain

$$x_1 p(x_1+k)^{1/n} \geq x_2 p(x_2+k)^{1/n}.$$

The last inequality is in contradiction with (1).  $\square$

**THEOREM 3.5.** *Let  $p : \Omega \subseteq \mathbb{R}_+ \cup \{0\} \rightarrow \mathbb{R}_+$  be a  $(-1)/n$ -concave function,  $n \geq 1$ ,  $k \geq 0$ . Then, if  $xp(x+k)^{1/n}$  has an extremum greater than 0, it is a global maximum.*

*Proof.* First we will prove  $xp(x+k)^{1/n}$  does not possess a positive local minimum  $x^*$  such that:  $x^*p(x^*+k)^{1/n} \leq xp(x+k)^{1/n}$ , where  $x$  is in a small

neighbourhood of  $x^*$  and the inequality is strict at least for  $x > x^*$  or  $x < x^*$ . Suppose  $x^* = (x_1 + x_2)/2$  is a local minimum,  $x_1, x_2 > 0$  and

$$(3) \quad \frac{x_1 + x_2}{2} p\left(\frac{x_1 + x_2}{2} + k\right)^{1/n} < p(x_1 + k)^{1/n} x_1$$

$$(4) \quad \frac{x_1 + x_2}{2} p\left(\frac{x_1 + x_2}{2} + k\right)^{1/n} \leq p(x_2 + k)^{1/n} x_2$$

From (3) we obtain:

$$0 < p\left(\frac{x_1 + x_2}{2} + k\right)^{1/n} < \frac{x_1}{x_2} \left(2p(x_1 + k)^{1/n} - p\left(\frac{x_1 + x_2}{2} + k\right)^{1/n}\right)$$

and

$$(5) \quad \frac{x_1}{x_2} > \frac{p\left(\frac{x_1 + x_2}{2} + k\right)^{1/n}}{2p(x_1 + k)^{1/n} - p\left(\frac{x_1 + x_2}{2} + k\right)^{1/n}}.$$

Using (4), we have:

$$\frac{x_1}{x_2} p\left(\frac{x_1 + x_2}{2} + k\right)^{1/n} \leq 2p(x_2 + k)^{1/n} - p\left(\frac{x_1 + x_2}{2} + k\right)^{1/n},$$

that is

$$(6) \quad \frac{x_1}{x_2} \leq \frac{2p(x_2 + k)^{1/n} - p\left(\frac{x_1 + x_2}{2} + k\right)^{1/n}}{p\left(\frac{x_1 + x_2}{2} + k\right)^{1/n}}.$$

From (5) and (6), we get

$$\frac{p\left(\frac{x_1 + x_2}{2} + k\right)^{1/n}}{2p(x_1 + k)^{1/n} - p\left(\frac{x_1 + x_2}{2} + k\right)^{1/n}} < \frac{2p(x_2 + k)^{1/n} - p\left(\frac{x_1 + x_2}{2} + k\right)^{1/n}}{p\left(\frac{x_1 + x_2}{2} + k\right)^{1/n}}$$

or

$$p\left(\frac{x_1 + x_2}{2} + k\right)^{1/n} < \frac{2p(x_1 + k)^{1/n} p(x_2 + k)^{1/n}}{p(x_1 + k)^{1/n} + p(x_2 + k)^{1/n}}.$$

The last is in contradiction with (2).

If  $xp(x + k)^{1/n}$  is non-increasing around 0, it will be non-increasing for all  $x > 0$ , since there is no local minimum and the function will not change its behavior. If  $xp(x + k)^{1/n}$  is increasing around 0 and there is a local maximum  $x^*$ ,  $xp(x + k)^{1/n}$  will be non-increasing for all  $x > x^*$  and  $x^*$  is a global maximum.  $\square$

**COROLLARY 3.6.** *Let  $p : \Omega \subseteq R_+ \cup \{0\} \rightarrow R_+$  be a decreasing, continuous and  $(-1)/n$ -concave function,  $n \geq 1$ . If  $0 < x_1 \leq x_2$ ,  $k \geq 0$ ,  $1 \leq s \leq n$ , then from  $x_2 d^- p(x_2 + k) + sp(x_2 + k) > 0$ , it follows that  $x_1 d^+ p(x_1 + k) + sp(x_1 + k) > x_2 d^- p(x_2 + k) + sp(x_2 + k)$ .*

*Proof.* If  $p$  is  $(-1)/n$ -concave, it is  $(-1)/s$ -concave,  $1 \leq s \leq n$  (Lemma 3.2). From Theorem 3.4 and Theorem 3.5, it follows that if there is an interval where the function  $xp(x+k)^{1/s}$  is increasing, it is unique and its left boundary point is 0; moreover,  $xp(x+k)^{1/s}$  is strictly concave in this interval, therefore, if  $0 < x_1 \leq x_2$ ,  $k \geq 0$  and

$$d^-(x_2 p(x_2 + k)^{1/s}) \geq 0 \Leftrightarrow \frac{x_2 d^- p(x_2 + k) + s p(x_2 + k)}{s} p(x_2)^{1/s-1} \geq 0,$$

which is

$$x_2 d^- p(x_2 + k) + s p(x_2 + k) \geq 0,$$

then it follows

$$d^+(xp(x+k)^{1/s})(x_1) \geq d^-(xp(x+k)^{1/s})(x_2)$$

or

$$\begin{aligned} p(x_1)^{1/s-1} \frac{x_1 d^+ p(x_1 + k) + s p(x_1 + k)}{s} \\ \geq p(x_2)^{1/s-1} \frac{x_2 d^- p(x_2 + k) + s p(x_2 + k)}{s} \end{aligned}$$

and, since  $p(x)$  is decreasing and, for  $s \geq 1$ ,  $p(x_1)^{1/s-1} \leq p(x_2)^{1/s-1}$ ,

$$x_1 d^+ p(x_1 + k) + s p(x_1 + k) \geq x_2 d^- p(x_2 + k) + s p(x_2 + k).$$

□

#### 4. EXISTENCE AND UNIQUENESS OF AN EQUILIBRIUM

**THEOREM 4.1.** *Suppose each cost function is convex and strictly increasing,  $p_i$  is a positive, strictly decreasing, continuous and  $(-1)$ -concave function on  $R_+ \cup \{0\}$  for each  $i = 1, \dots, N$ . Then there exists at least one equilibrium.*

*Proof.* From Theorem 3.4 and Theorem 3.5, it follows that  $xp_i(x+k) - c_i(x)$  is a quasi-concave function. As  $p_i(\cdot)$  is positive,  $(-1)$ -concave and decreasing,  $1/p_i(\cdot)$  is positive, convex and increasing, therefore for each  $x_0 \geq 0$  and each  $i$  there exists a supporting line  $a_i(x_0)x + b_i(x_0)$  such that:  $1/p_i(x) \geq a_i(x_0)x + b_i(x_0)$  (with an equality at  $x = x_0$ ). From the fact that  $p_i$  is positive and strictly increasing it follows that  $a_i(x_0)x + b_i(x_0) > 0$  for each  $x \geq 0$  and  $a_i(x_0) \geq 0$ . Moreover, there exists  $\bar{x}_0$  such that  $a_i(\bar{x}_0) > 0$ . Then

$$\limsup_{x \rightarrow \infty} xp_i(x+k) - c_i(x) \leq \lim_{x \rightarrow \infty} x \frac{1}{a_i(\bar{x}_0)x + b_i(\bar{x}_0)} - c_i(x) = -\infty$$

Consequently, there exists  $X_i$  such that:  $xp_i(x) - c_i(x) \leq -c_i(0)$  for all  $x \geq X_i$  and the effective strategy of each firm is contained in  $[0, X_i]$ .

The conditions of Theorem 2.3 are fulfilled and there exists at least one equilibrium. □

**THEOREM 4.2.** *Suppose each cost function is convex and increasing,  $p_i$  is a positive, strictly decreasing, continuous and  $(-1)/N$ -concave function on  $R_+$ , for each  $i = 1, \dots, N$   $N \geq 2$ . Then the Nash-sums  $\sigma$  are constant.*

*Proof.* As in [9], Theorem 2, suppose  $a, b$  are equilibria with:

$$x_a = \sum_{l \in N} a_l < \sum_{l \in N} b_l = x_b.$$

Let  $J = \{l \in N | a_l < b_l\}$ ,  $\tilde{x}_a = \sum_{l \in J} a_l$ ,  $\tilde{x}_b = \sum_{l \in J} b_l$ ,  $s$  – the number of elements of  $J$ . Note that  $x_a \neq 0$  (Lemma 2.1),  $x_b > 0$ ,  $s \geq 1$ ,  $\tilde{x}_a \leq x_a$ ,  $\tilde{x}_b \leq x_b$ ,  $\tilde{x}_a < \tilde{x}_b$ ,  $\tilde{x}_b - \tilde{x}_a \geq x_b - x_a$ .

As  $a$  and  $b$  are equilibria,  $d^+ \pi_i(a) \leq 0 \leq d^- \pi_i(b)$  ( $i \in J$ ), i.e.

$$d^+ p(x_a) a_i + p(x_a) - d^+ c_i(a_i) \leq 0 \leq d^- p(x_b) b_i + p(x_b) - d^- c_i(b_i),$$

or

$$d^+ p(x_a) \tilde{x}_a + sp(x_a) - \sum_{i \in J} d^+ c_i(a_i) \leq 0 \leq d^- p(x_b) \tilde{x}_b + sp(x_b) - \sum_{i \in J} d^- c_i(b_i).$$

As each  $c_i$  is convex this inequality implies:

$$(7) \quad d^+ p(x_a) \tilde{x}_a + sp(x_a) \leq d^- p(x_b) \tilde{x}_b + sp(x_b).$$

Consider the two points  $x_1 = x_a - (x_b - \tilde{x}_b) > 0$ ,  $x_2 = \tilde{x}_b > 0$ ,  $x_1 < x_2$ ,  $k = x_b - \tilde{x}_b > 0$ . From Corollary 3.6:

$$(x_a - (x_b - \tilde{x}_b)) d^+ p(x_a) + sp(x_a) > \tilde{x}_b d^- p(x_b) + sp(x_b) \geq 0.$$

From  $\tilde{x}_b - \tilde{x}_a \geq x_b - x_a$  it follows  $x_a - (x_b - \tilde{x}_b) \geq \tilde{x}_a$ ; furthermore,  $p_i$  is strictly decreasing and consequently:

$$\tilde{x}_a d^+ p(x_a) > (x_a - (x_b - \tilde{x}_b)) d^+ p(x_a),$$

therefore

$$\tilde{x}_a d^+ p(x_a) + sp(x_a) > \tilde{x}_b d^- p(x_b) + sp(x_b),$$

in contradiction with (7).  $\square$

**COROLLARY 4.3.** *Suppose each cost function is convex and increasing,  $p_i$  is a positive, strictly decreasing, continuous, differentiable and  $(-1)/N$ -concave function on  $R_+ \cup \{0\}$ , for each  $i = 1, \dots, N$ ,  $N \geq 2$ . Then there exists a unique equilibrium.*

*Proof.* This is a direct consequence of Theorems 2.2, 4.2 and 4.1.  $\square$

## 5. CONCLUDING REMARKS

As noticed in the Introduction, our results are not equivalent to the results presented in [9]. An example of a function that is  $(-1)$ -concave, but without concave integrated price flexibility, is  $p(x) = \frac{1}{(x+1) \ln(x+2)}$ . In this case the revenue function is quasi-concave (but not concave). There are examples of functions that are with concave integrated price flexibility, but not  $(-1)$ -concave ( $(x+1)^\alpha$ ,  $0 < \alpha < 1$ ), therefore, our results neither imply, nor are

implied by the results in [9]. The existence theorem [5, Theorem 3.3] supposes the payoff and costs functions are twice differentiable. The existence theorem 4.1 is in the non-smooth case. So, to the best of our knowledge, the results presented here are new.

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