

IRREGULAR FORCED ALMOST PERIODIC SOLUTIONS OF ORDINARY LINEAR DIFFERENTIAL SYSTEMS

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Abstract. Let A be an almost periodic $(n \times n)$ -matrix and let φ be an almost periodic vector. Suppose that $\text{mod}(A) \cap \text{mod}(\varphi) = \{0\}$. We say that the almost periodic solution x of the system

$$\dot{x} = A(t)x + \varphi(t), \quad t \in \mathbb{R}, \quad x \in \mathbb{R}^n,$$

is irregular with respect to $\text{mod}(A)$ (or partially irregular) if $(\text{mod}(x) + \text{mod}(\varphi)) \cap \text{mod}(A) = \{0\}$, and irregular forced if at the same time $\text{mod}(x) \subseteq \text{mod}(\varphi)$. We prove that an irregular with respect to $\text{mod}(A)$ almost periodic solution is irregular forced in non-critical and some critical cases. The necessary and sufficient conditions for existence of irregular forced solutions are obtained.

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1. INTRODUCTION

Let D be a compact subset of \mathbb{R}^n and let $\mathbb{R}^{k \times m}$ be the linear space of all matrices with k rows and m columns (k and m are positive integers). By $AP(\mathbb{R}^{k \times m})$ we denote the linear space of all almost periodic functions $h : \mathbb{R} \rightarrow \mathbb{R}^{k \times m}$. By $AP(D, \mathbb{R}^{k \times m})$ we denote the linear space of all continuous functions $h : \mathbb{R} \times D \rightarrow \mathbb{R}^{k \times m}$ such that each $h \in AP(D, \mathbb{R}^{k \times m})$ is almost periodic in $t \in \mathbb{R}$ uniformly for $x \in D$. By $\text{mod}(h)$ we denote a frequency module of $h \in AP(\mathbb{R}^{k \times m})$ (or $h \in AP(D, \mathbb{R}^{k \times m})$). Consider the almost periodic ordinary differential system

$$(1) \quad \dot{x} = f(t, x), \quad t \in \mathbb{R}, \quad x \in D,$$

where $f \in AP(D, \mathbb{R}^{n \times 1})$. The existence problem for almost periodic solutions to (1) is a significant problem both for qualitative theory of ordinary differential equations and for its applications to vibration theory (see [1], [19]). Many authors have investigated this problem, see e.g. [2], [3], [11], [13], [14], [16], [20]. Most of them have considered only the regular solutions x , i.e. the solutions with $\text{mod}(x) = \text{mod}(f)$. However, there can be various relations between $\text{mod}(x)$ and $\text{mod}(f)$. In [15], J. Kurzweil and O. Veivoda have obtained the necessary existence conditions for almost periodic solutions x to (1) such that $\text{mod}(x) \cap \text{mod}(f) = \{0\}$. We say that such solutions are irregular. The analogous problem for periodic systems was studied by H. Massera [18]. In [4], [5], [10], [12] irregular periodic, quasiperiodic, and almost periodic solutions are considered.

In [6] we have shown that some classes of quasiperiodic systems admit quasiperiodic solutions with some of the right part base frequencies. For the system (1) with

$$f(t, x) = F(t, x) + G(t, x), \quad t \in \mathbb{R}, \quad x \in D, \quad \text{mod}(F) \cap \text{mod}(G) = \{0\},$$

the existence criteria for almost periodic solutions x such that $(\text{mod}(x) + \text{mod}(G)) \cap \text{mod}(F) = \{0\}$ are given in [7]. Such solutions are called partially irregular. In [8] we have obtained the existence conditions for almost periodic partially irregular solutions of system (1) with $f(t, x) \equiv F(t, t, x)$, where $F(t_1, t_2, x)$ is almost periodic in t_j ($j = 1, 2$) uniformly for the rest of the arguments.

In this paper we consider the linear system

$$(2) \quad \dot{x} = A(t)x + \varphi(t), \quad t \in \mathbb{R}, \quad x \in \mathbb{R}^n,$$

where $A \in AP(\mathbb{R}^{n \times n})$, $\varphi \in AP(\mathbb{R}^{n \times 1})$, and

$$(3) \quad \text{mod}(A) \cap \text{mod}(\varphi) = \{0\}.$$

The almost periodic solutions x to (2) such that $\text{mod}(x) = \text{mod}(\varphi)$ are investigated in [4]. In [9] we have considered quasiperiodic system (2) with φ in the form of a trigonometric polynomial.

The aim of this paper is to establish the existence conditions for almost periodic irregular with respect to $\text{mod}(A)$ solutions of linear system (2) in non-critical and some critical cases. To this end we apply the results of [18] to linear systems.

2. PRELIMINARIES

DEFINITION 1. Let $f \in AP(D, \mathbb{R}^{n \times 1})$.

a) A real number γ is called a Fourier exponent (or frequency) of f , if

$$\lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T f(t, x) \exp(-i\gamma t) dt \neq 0 \quad \text{for } x \in D.$$

b) The set Γ of all Fourier exponents of f is called the frequency set of this function.

c) The frequency module $\text{mod}(f)$ of f is the smallest additive group of real numbers that contains all Fourier exponents of this function.

DEFINITION 2. Let $f \in AP(D, \mathbb{R}^{n \times 1})$ be a right side of (1) and $\text{mod}(f)$ is splitted into direct sum of two submoduli M_1, M_2 ($j = 1, 2$), i.e. $\text{mod}(f) = M_1 \oplus M_2$.

a) An almost periodic solution x of the system (1) is called irregular with respect to submodule M_2 (or partially irregular) if $(\text{mod}(x) + M_1) \cap M_2 = \{0\}$.

b) An irregular with respect to submodule M_2 almost periodic solution x of the system (1) is called weakly M_2 -irregular (or weakly irregular) if $\text{mod}(x) \subseteq M_1$.

c) Any weakly mod(A)-irregular almost periodic solution x of the linear system (2) is called irregular forced.

In what follows we shall show a construction of transformation reducing a functional matrix to a special block form. If P is a real $(n \times n)$ -matrix function defined on \mathbb{R} then by $\text{rank}_{\text{col}} P$ we denote the column rank of P , i.e. $\text{rank}_{\text{col}} P$ is the maximal number of linearly independent columns of P .

LEMMA 1. *Let P be a real $(n \times n)$ -matrix function defined on \mathbb{R} . If $\text{rank}_{\text{col}} P = n - k$, $0 < k < n$, then there exists a constant nonsingular $(n \times n)$ -matrix Q such that the first k columns of PQ are zero and remaining columns are linearly independent.*

Proof. If $P = (P_1, \dots, P_n)$, where P_1, \dots, P_n are the columns of P , and $\text{rank}_{\text{col}} P < n$ then we have $a_1 P_1 + \dots + a_n P_n = 0$ for some real numbers a_1, \dots, a_n for which $a_1^2 + \dots + a_n^2 > 0$. It follows that there exists j ($1 \leq j \leq n$) such that $a_j \neq 0$. This yields

$$a_j P_j = -a_1 P_1 - \dots - a_{j-1} P_{j-1} - a_{j+1} P_{j+1} - \dots - a_n P_n.$$

Take the constant $(n \times n)$ -matrix S_1 which arises from the unit matrix E_n of order n by the replacement of its j -th column by the column $(a_1, \dots, a_n)^\top$. Evidently, $\det S_1 = a_j \neq 0$.

Further, we take the constant $(n \times n)$ -matrix T_1 which arises from the unit matrix E_n by the exchange of its first and j -th columns. We have $\det T_1 = \pm 1 \neq 0$. Evidently, the first column of $P^{(1)} = PQ_1$ ($Q_1 = S_1 T_1$) is zero. It is clear that $\text{rank}_{\text{col}} P = \text{rank}_{\text{col}} P^{(1)}$ because $\det Q_1 = \pm a_j \neq 0$.

If $k = 1$ then there is nothing to do. If $k > 1$ and $P_1^{(1)}, \dots, P_n^{(1)}$ are the columns of $P^{(1)}$ then with regard to $P_1^{(1)} = 0$ there exist real numbers b_2, \dots, b_n , not all zero, such that $b_2 P_2^{(1)} + \dots + b_n P_n^{(1)} = 0$. We may assume that $b_r \neq 0$ for some $2 \leq r \leq n$. Then

$$b_r P_r^{(1)} = -b_2 P_2^{(1)} - \dots - b_{r-1} P_{r-1}^{(1)} - b_{r+1} P_{r+1}^{(1)} - \dots - b_n P_n^{(1)}.$$

Now we construct the constant $(n \times n)$ -matrix S_2 which arises from E_n by the replacement of its r -th column by the column $(0, b_2, \dots, b_n)^\top$. We have $\det S_2 = b_r \neq 0$. Further, we take the constant $(n \times n)$ -matrix T_2 which arises from E_n by the exchange of its second and r -th columns. Obviously, $\det T_2 \neq 0$. The first two columns of $P^{(2)} = P^{(1)} Q_2$ ($Q_2 = S_2 T_2$) are zero. Evidently, $\text{rank}_{\text{col}} P = \text{rank}_{\text{col}} P^{(2)}$ because $\det Q_2 \neq 0$.

If $k > 2$ then we continue by the analogous way. So that we obtain the matrix $Q = S_1 T_1 \cdots S_k T_k$ such that first k columns of PQ are zero and the remaining columns are linearly independent. \square

3. THEOREMS

In this section we obtain the existence conditions for almost periodic irregular with respect to mod(A) solutions of system (2). We suppose that (3)

holds. Let x be an almost periodic solution to (2) and $(\text{mod}(x) + \text{mod}(\varphi)) \cap \text{mod}(A) = \{0\}$. It is clear that $x \neq 0$. By [7], the solution x satisfies the system

$$(4) \quad \dot{x} = \hat{A}x + \varphi(t), \quad [A(t) - \hat{A}]x = 0, \quad t \in \mathbb{R}, \quad \hat{A} = \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T A(t) dt.$$

Denote $\tilde{A} = A - \hat{A}$. Since $\text{mod}(x) \cap \text{mod}(\tilde{A}) = \{0\}$ and $x \neq 0$, it follows from $\tilde{A}(t)x = 0$, $t \in \mathbb{R}$, and [7] that

$$(5) \quad 0 < \text{rank}_{\text{col}} \tilde{A} = r < n.$$

By Lemma 1 there exists a constant nonsingular $(n \times n)$ -matrix Q such that the first s ($s = n - r$) columns of $\tilde{A}Q$ are zero and the remaining r columns are linearly independent. Then substitution

$$(6) \quad x = Qy$$

reduces system (4) to the form

$$(7) \quad \dot{y} = By + \psi(t), \quad \tilde{B}(t)y = 0, \quad t \in \mathbb{R},$$

where $B = Q^{-1}\hat{A}Q$, $\psi = Q^{-1}\varphi$, and $\tilde{B} = \tilde{A}Q$. The last r columns of \tilde{B} are linearly independent and from this and from $\tilde{B}y = 0$ follows that the last r components of y are zero. Clearly, system (7) has almost periodic solution $y = S^{-1}x$ such that $\text{mod}(y) = \text{mod}(x)$. Therefore, $y = (\tilde{y}^\top, 0, \dots, 0)^\top$, $\tilde{y} = (y_1, \dots, y_s)^\top$. Consequently, system (7) take the form

$$\dot{\tilde{y}} = B_{s,s}\tilde{y} + \psi^{(1)}(t), \quad B_{n-s,s}\tilde{y} + \psi^{(2)}(t) = 0, \quad t \in \mathbb{R},$$

$$(8) \quad \tilde{y} = (y_1, \dots, y_s)^\top, \quad y_{s+1} = \dots = y_n = 0,$$

where $B_{s,s}$ and $B_{n-s,s}$ are the upper left $(s \times s)$ -block and the lower left $((n - s) \times s)$ -block of B respectively and $\psi^{(1)} = (\psi_1, \dots, \psi_s)^\top$; $\psi^{(2)} = (\psi_{s+1}, \dots, \psi_n)^\top$, i.e.

$$B = \begin{pmatrix} B_{s,s} & B_{s,n-s} \\ B_{n-s,s} & B_{n-s,n-s} \end{pmatrix}, \quad \psi = \begin{pmatrix} \psi^{(1)} \\ \psi^{(2)} \end{pmatrix}.$$

Consider the system

$$(9) \quad \dot{\tilde{y}} = B_{s,s}\tilde{y} + \psi^{(1)}(t), \quad t \in \mathbb{R}.$$

By the above, system (9) has the almost periodic solution $\tilde{y} = Q_{s,n}^{(-1)}x$, where $Q_{s,n}^{(-1)}$ is the upper $(s \times n)$ -block of Q^{-1} . Since $y = Q^{-1}x$ and $y = (\tilde{y}^\top, 0, \dots, 0)^\top$, we have $\text{mod}(\tilde{y}) = \text{mod}(x)$. Note that \tilde{y} is also a solution of the second system in (8). This implies that \tilde{y} satisfies the identity

$$(10) \quad B_{n-s,s}\tilde{y}(t) + \psi^{(2)}(t) \equiv 0, \quad t \in \mathbb{R}.$$

Hence, if system (2) has an irregular with respect to $\text{mod}(A)$ almost periodic solution x , then conditions (5), (10) hold, where \tilde{y} is the almost periodic solution to (9) with the same frequency properties as x .

Let us show that the opposite assertion also holds. Indeed, if (5) is valid, then by Lemma 1 there exists constant nonsingular $(n \times n)$ -matrix Q such that transformation (6) reduces system (2) to (7). Since the last r columns of \tilde{B} are linearly independent, it follows from [7] that $y_{s+1} = \dots = y_n = 0$. Therefore, system (7) is reduced to system (8). System (8) has the almost periodic solution \tilde{y} , $(\text{mod}(\tilde{y}) + \text{mod}(\varphi)) \cap \text{mod}(A) = \{0\}$ by assumption. Now the identity (10) provides the existence of the almost periodic solution \tilde{y} to system (8), and from (6) we get

$$(11) \quad x = Q(\tilde{y}^\top, 0, \dots, 0)^\top.$$

It is clear that (11) is a solution to (4) and $\text{mod}(x) = \text{mod}(\tilde{y})$. By [7], (11) is a solution of system (2) as well.

Thus, we have proved

THEOREM 1. *Suppose that $A \in AP(\mathbb{R}^{n \times n})$ and $\varphi \in AP(\mathbb{R}^{n \times 1})$ and that (3) holds. The system (2) has the irregular with respect to $\text{mod}(A)$ almost periodic solution (11) if and only if*

- 1) $\text{rank}_{\text{col}} A = r$ ($0 < r < n$);
- 2) the system (8) has the almost periodic solution \tilde{y} such that $(\text{mod}(\tilde{y}) + \text{mod}(\varphi)) \cap \text{mod}(A) = \{0\}$;
- 3) the identity (10) is valid.

Thus, the problem of existence of an almost periodic partially irregular solutions to (2) is equivalent to a similar problem for system (8).

Now assume that all eigenvalues $\lambda_1(B_{ss}), \dots, \lambda_s(B_{ss})$ of B_{ss} have nonzero real parts

$$(12) \quad \text{Re } \lambda_j(B_{ss}) \neq 0 \quad (j = \overline{1, s}).$$

THEOREM 2. *Suppose that the conditions (3), (12) hold and the system (2) has an almost periodic irregular with respect to $\text{mod}(A)$ solution x ; then this solution is irregular forced.*

Proof. Let x be an almost periodic solution of system (2) and $(\text{mod}(x) + \text{mod}(\varphi)) \cap \text{mod}(A) = \{0\}$. By Theorem 1, system (9) has an almost periodic solution \tilde{y} such that $\text{mod}(\tilde{y}) = \text{mod}(x)$. It follows from (12) and [11, p. 91] that $\text{mod}(\tilde{y}) \subseteq \text{mod}(\psi^{(1)})$. Since $\text{mod}(\psi^{(1)}) \subseteq \text{mod}(\varphi)$, we obtain $\text{mod}(\tilde{y}) \subseteq \text{mod}(\varphi)$. This means that $\text{mod}(x) \subseteq \text{mod}(\varphi)$, i.e. the solution x is irregular forced. \square

It should be stressed that Theorem 2 is not valid in critical case when some of $\text{Re } \lambda_j(B_{ss})$ is zero. However, some critical cases can be considered in similar way. Let $\lambda_j(B_{ss}) = \alpha_j + i\beta_j$ ($i^2 = -1$; $j = \overline{1, s}$). Suppose that

$$(13) \quad \begin{aligned} \alpha_l = 0, \quad \beta_l \in \text{mod}(\varphi) \quad (l = \overline{1, p}; \quad p \leq n), \quad \alpha_q \neq 0 \quad (q = \overline{p+1, s}); \\ \beta_k \neq \beta_m \quad \text{for all } k \neq m, \quad k, m = \{1, \dots, p\}. \end{aligned}$$

Then the conjugate system

$$(14) \quad \dot{z} = -B_{ss}^\top z, \quad z \in \mathbb{R}^s$$

has p linearly independent quasiperiodic solutions

$$(15) \quad z^{(1)}, \dots, z^{(p)}, \quad \text{mod}(z^{(j)}) \subseteq \text{mod}(\varphi) \quad (j = \overline{1, p}).$$

THEOREM 3. *Suppose that $A \in AP(\mathbb{R}^{n \times n})$, $\varphi \in AP(\mathbb{R}^{n \times 1})$ and that $(s \times s)$ -matrix B_{ss} has the eigenvalues for which (13) is valid.*

1) *If system (2) has an almost periodic irregular with respect to $\text{mod}(A)$ solution x , then this solution is irregular forced.*

2) *System (2) has an irregular forced almost periodic solution if and only if (5), (10), and*

$$(16) \quad \sup_{-\infty < t < +\infty} \left| \int_{t_0}^t \sum_{k=1}^s z_k^{(j)}(\tau) \psi_k^{(j)}(\tau) d\tau \right| < +\infty \quad (j = \overline{1, p})$$

hold.

Proof. Let x be a partially irregular almost periodic solution of system (2). Then by Theorem 1 inequality (5) is true and system (9) has an almost periodic solution \tilde{y} such that $\text{mod}(\tilde{y}) = \text{mod}(x)$. It follows from [17, Theorem 2] that estimate (16) holds. Note that \tilde{y} satisfies (8) as well. Therefore identity (10) is valid. Since $\alpha_k = 0$, $\beta_k \in \text{mod}(\varphi)$ ($k = \overline{1, p}$), and $\text{mod}(\psi^{(1)}) \subseteq \text{mod}(\varphi)$, we have $\text{mod}(\tilde{y}) \subseteq \text{mod}(\varphi)$. Hence, $\text{mod}(x) \subseteq \text{mod}(\varphi)$, i.e. the solution x is irregular forced.

Conversely, assume that the conditions of Theorem 3 hold. It follows from (5) and Lemma 1 that there exists the matrix Q such that the transformation (6) reduces system (4) to the form (7). Since the last $n - s$ columns of \tilde{B} are linearly independent, we obtain $y_{s+1} = \dots = y_n = 0$. Thus, system (7) is reduced to (8). Note that B_{ss} has the eigenvalues (13) by assumption. Consequently, (15) are the solutions to (14). By [17, Theorem 2], (13), and (16), system (9) has the almost periodic solution \tilde{y} and $\text{mod}(\tilde{y}) \subseteq \text{mod}(\psi^{(1)}) \subseteq \text{mod}(\varphi)$. It follows from (10) and (8) that $y = (\tilde{y}^\top, 0, \dots, 0)^\top$ satisfies (7). By (6), we obtain the almost periodic solution $x = Qy$ of system (4). By [7], x is a solution of system (2) as well. Since $\text{mod}(x) = \text{mod}(\tilde{y})$, we see that the solution x is irregular forced. \square

COROLLARY 1. *The system (2) has an almost periodic irregular with respect to $\text{mod}(A)$ solution x if and only if x satisfies the following conditions*

$$\dot{x} = A(t_0)x + \varphi(t), \quad [A(t) - A(t_0)]x = 0, \quad t \in \mathbb{R},$$

for any $t_0 \in \mathbb{R}$.

4. AN EXAMPLE

Let a_1 , a_2 , and φ_1 be scalar real almost periodic nonzero functions such that

$$\lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T a_j(t) dt = \alpha_j \quad (j = 1, 2), \quad \sup_{-\infty < t < +\infty} \left| \int_{t_0}^t \varphi_1(\tau) d\tau \right| < +\infty.$$

Suppose that $\text{mod}(a) \cap \text{mod}(\varphi_1) = \{0\}$, where $a = (a_1, a_2)^\top$. Consider the system

$$\dot{x} = -a_1(t)x + a_1(t)y + \varphi_1(t),$$

$$(17) \quad \dot{y} = (1 - a_1(t) - a_2(t))x + (a_1(t) + a_2(t))y + \varphi_1(t) - \varphi_2(t), \quad t, x, y \in \mathbb{R},$$

where $\varphi_2(t) = \int_{t_0}^t \varphi_1(\tau) d\tau$. It follows from [16, p. 83] that $\varphi_2(t)$ is almost periodic. Note that $\text{mod}(\varphi_1) = \text{mod}(\varphi_2)$. We have

$$A(t) = \begin{pmatrix} -a_1(t) & a_1(t) \\ 1 - a_1(t) - a_2(t) & a_1(t) + a_2(t) \end{pmatrix}, \quad \hat{A} = \begin{pmatrix} -\alpha_1 & \alpha_1 \\ 1 - \alpha_1 - \alpha_2 & \alpha_1 + \alpha_2 \end{pmatrix}$$

and $\text{rank}_{\text{col}} \tilde{A} = 1 < 2$ ($\tilde{A} = A - \hat{A}$). By Lemma 1 there exists a nonsingular matrix Q such that

$$\tilde{A}(t)Q = \begin{pmatrix} 0 & a_1(t) - \alpha_1 \\ 0 & a_1(t) - \alpha_1 + a_2(t) - \alpha_2 \end{pmatrix}, \quad Q = \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix}.$$

It follows from Theorem 1 and Theorem 3 that system (17) has an irregular forced almost periodic solution. It is easy to see that the solution $x = \varphi_2$, $y = \varphi_2$ is a solution with the required properties.

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